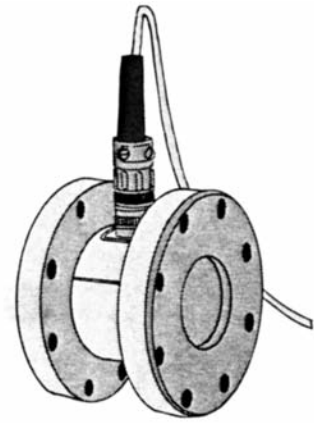


# TQ101

## Reaction Torque Sensor

INSTRUCTION  
SHEET**M1461/0010**

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### GENERAL DESCRIPTION

The OMEGA TQ101 Series Reaction Torque Sensors are ideal in measuring reaction or restraining torques such as found in motor mounts, pump mounts, machine mounts, etc. They can also be used in limited rotation applications such as the torque required to turn a nut or an actuator shaft. The sensor is designed with flanges enabling easy installation or adaption. The TQ101 torque sensor is rugged enough for the factory, yet accurate enough for the laboratory.

### HOW TORQUE SENSORS WORK

Torque sensors have an output or sensitivity in mV/V. What this sensitivity/output represents is as follows:

$$\begin{array}{l} \text{Change in Millivolt output} \\ \text{from zero load to the full} \\ \text{scale capacity of the sensor} \\ \text{(21.3 mV in this example)} \end{array} = \begin{array}{l} \text{Output/Sensitivity} \\ \text{(example 2.13 mV/V)} \end{array} \times \begin{array}{l} \text{Excitation} \\ \text{(10.0 VDC)} \end{array}$$

Torque sensors rarely have exactly zero millivolts at no load. Most sensors have a small DC offset of a few millivolts, which is normal. To scale a system, the end-user simply scales the recorder/meter for a full scale range, then connects the torque sensor.

### SPECIFICATIONS

<b>RATED OUTPUT:</b>	2.0 mV/V nominal
<b>EXCITATION:</b>	10 Vdc, 20 Vdc maximum
<b>ACCURACY:</b>	0.18% F.S.
<b>LINEARITY:</b>	0.10% F.S.
<b>HYSTERESIS:</b>	0.10% F.S.
<b>REPEATABILITY:</b>	0.10% F.S.
<b>ZERO BALANCE:</b>	1.0% F.S.
<b>OPERATING TEMP. RANGE:</b>	-65°F to 250°F
<b>COMPENSATED TEMP. RANGE:</b>	70°F to 170°F
<b>THERMAL EFFECTS</b>	
Zero:	0.002% F.S./°F
Span:	0.002% Rdg/°F
<b>MAX. LOAD</b>	
Safe:	150% F.S.
Ultimate:	300% F.S.
<b>BRIDGE RESISTANCE:</b>	350 ohms nominal
<b>FULL SCALE ANGULAR DEFLECTION:</b>	1.2 degrees
<b>CONSTRUCTION:</b>	
Sensing element:	Aluminum (up to 500 in-lb), nickel plated steel (above 500 in-lb)
Cover:	Aluminum (100, 200 and 500 in-lb) and nickel plated steel (all other ranges)
<b>ELECTRICAL:</b>	Mating connector supplied

## INSTALLATION INSTRUCTIONS

While the TQ101 Rotary Torque Sensor is a very rugged device, it should not be subjected to torsional loads in excess of 150% of its rated capacity. It is recommended to use grade 8 bolts or better to ensure a quality connection to the flanges. The sensor can be used to measure torque in both clockwise and counterclockwise directions. When alternating clockwise and counterclockwise torsional loads are applied to the sensor, there should be no play in either loading direction.

## WIRING

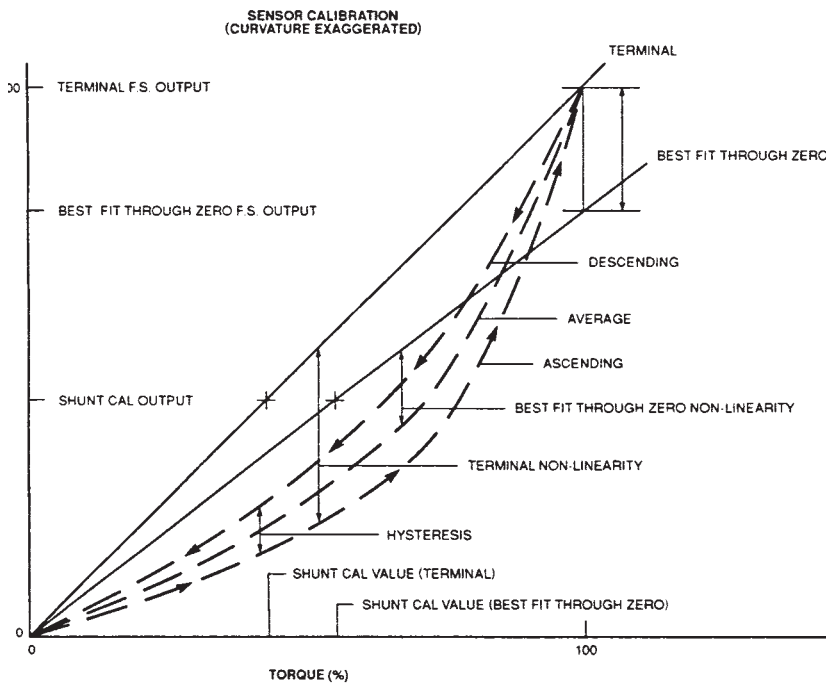
PIN A: + EXCITATION  
PIN B: + SIGNAL  
PIN C: - SIGNAL  
PIN D: - EXCITATION

## NIST TRACEABILITY

The TQ101 sensor is calibrated using a known load (applied to an NIST traceable load cell) through a known distance (measured by an NIST traceable lever arm). This set-up is considered a tertiary standard, traceable to NIST.

## GENERAL CALIBRATION PROCEDURE

The sensor is cycled through the operating range to develop a stable hysteresis loop. Known loads are then applied to the sensor by means of dead weights or a reference load cell in ascending and descending increments. The data recorded is then best fit to second degree equations which describe ascending, descending, and average calibration curves. These equations are incrementally solved to generate theoretical sensor outputs at various loads. The calibration sheet supplies you with these data points and their meanings are defined in the following diagram:



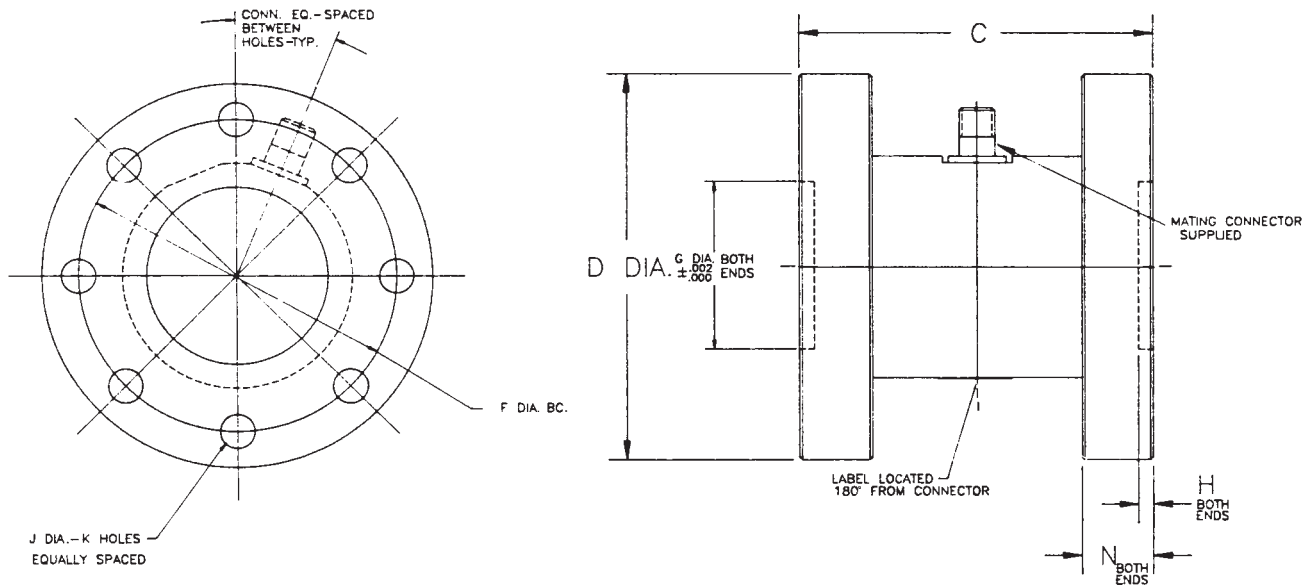
Terminal Non-linearity (N/L): computed from deviations of ascending theoretical data from a straight line connecting the zero and full scale points.

Terminal hysteresis (HYS): computed from the differences between descending and ascending theoretical data.

Best fit through zero Non-linearity (BF/0): computed from deviations of average theoretical data from a straight line through zero with a slope which produces minimum deviations with average theoretical data.

Best fit through zero outputs and best fit through zero shunt cal values should be used when the sensor is assumed to be linear. If the instrumentation is capable of correcting second order non-linearity, the average outputs and shunt cal output values should be used.

# DIMENSIONS



MODEL NO.	CAPACITY	DIMENSIONS (INCHES)							
		IN-IBF	C	D	F	G	H	N	J
TQ101-10	10		1.75	1.75	1.38	.75	.125	.31	.21
TQ101-20	20		1.75	1.75	1.38	.75	.125	.31	.21
TQ101-50	50		1.75	1.75	1.38	.75	.125	.31	.21
TQ101-100	100		2.25	3.00	2.50	1.25	.125	.38	.27
TQ101-200	200		2.25	3.00	2.50	1.25	.125	.38	.27
TQ101-500	500		2.25	3.00	2.50	1.25	.125	.38	.27
TQ101-1K	1,000		3.00	4.00	3.25	1.50	.125	.50	.33
TQ101-2K	2,000		3.00	4.00	3.25	1.50	.125	.50	.33
TQ101-5K	5,000		3.50	5.00	4.25	2.00	.25	.75	.39
TQ101-10K	10,000		3.50	5.00	4.25	2.00	.25	.75	.39
TQ101-15K	15,000		7.38	8.00	6.50	3.50	.31	1.50	.64
TQ101-20K	20,000		7.38	8.00	6.50	3.50	.31	1.50	.64
TQ101-50K	50,000		7.38	8.00	6.50	3.50	.31	1.50	.64
TQ101-100K	100,000		8.50	9.75	8.00	4.00	.31	1.50	.77



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The purchaser is responsible for shipping charges, freight, insurance and proper packaging to prevent breakage in transit.

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1. Purchase Order number under which the product was PURCHASED,
2. Model and serial number of the product under warranty, and
3. Repair instructions and/or specific problems relative to the product.

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1. Purchase Order number to cover the COST of the repair,
2. Model and serial number of the product, and
3. Repair instructions and/or specific problems relative to the product.

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