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Ω OMEGA® **User's Guide**



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OM-USB-32DIO **32-Channel High Speed Digital** **I/O USB Data Acquisition Module**



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About this User's Guide

What you will learn from this user's guide

This user's guide describes the Omega Engineering OM-USB-32DIO data acquisition device and lists device specifications.

Conventions in this user's guide

For more information

Text presented in a box signifies additional information and helpful hints related to the subject matter you are reading.

Caution! Shaded caution statements present information to help you avoid injuring yourself and others, damaging your hardware, or losing your data.

bold text **Bold** text is used for the names of objects on a screen, such as buttons, text boxes, and check boxes.

italic text *Italic* text is used for the names of manuals and help topic titles, and to emphasize a word or phrase.

Where to find more information

Additional information about OM-USB-32DIO Series hardware is available on our website at www.omega.com. You can also contact Omega Engineering by phone, fax, or email with specific questions.

- Phone: (203) 359-1660
- Fax: (203) 359-7700
- Email: das@omega.com

Introducing the OM-USB-32DIO

The OM-USB-32DIO is a USB 2.0 high-speed synchronous digital I/O device that provides the following features:

- 32 bits of bidirectional TTL digital I/O
- Pattern detection and generation
- Input scan rate up to 8 MS/s
- Output update rate of up to 8 MS/s
- Independent input and output scan clocks
- 24 mA source, 10 mA sink output current
- External trigger input
- Screw terminals for field wiring connections

The OM-USB-32DIO is powered by the +5 volt USB supply from your computer; no external power is required. A USB cable is shipped with the device. A board-only OEM form factor is available.

Functional block diagram

OM-USB-32DIO functions are illustrated in the block diagram shown here.

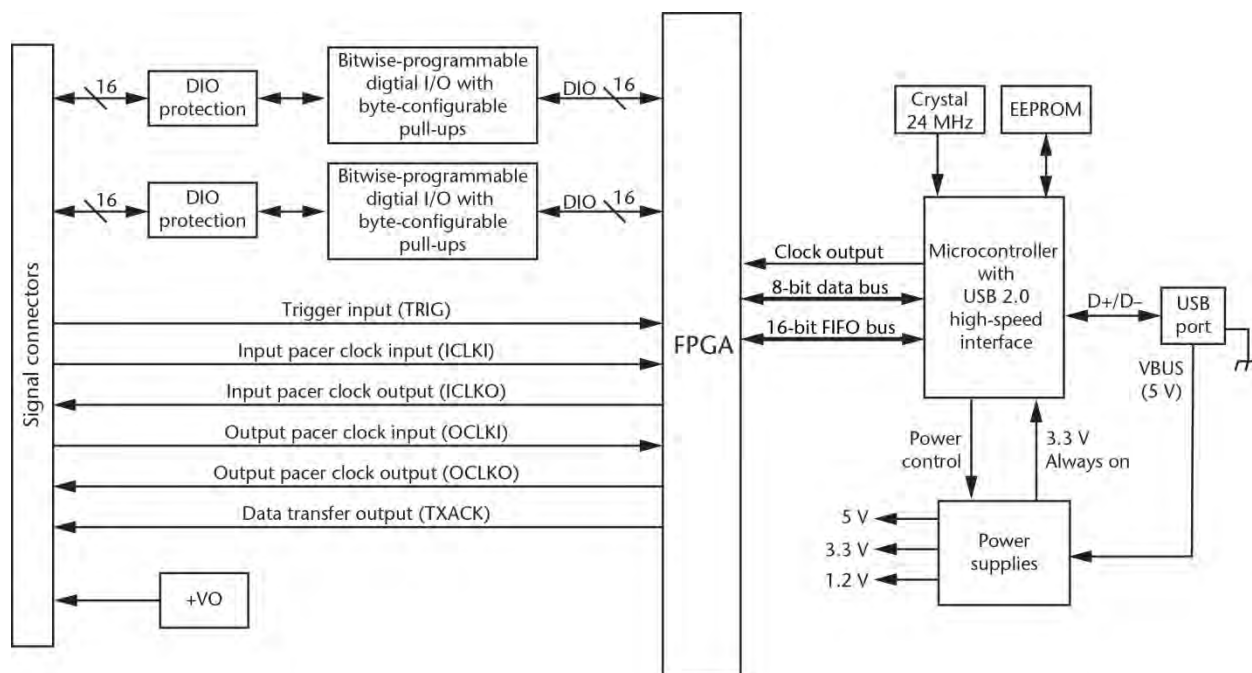


Figure 1. Functional block diagram

Installing the OM-USB-32DIO

Unpacking

As with any electronic device, take care while handling to avoid damage from static electricity. Before removing the OM-USB-32DIO from its packaging, ground yourself using a wrist strap or by simply touching the computer chassis or other grounded object to eliminate any stored static charge.

If any components are missing or damaged, notify Omega Engineering immediately by phone, fax, or e-mail.

- Phone: (203) 359-1660
- Fax: (203) 359-7700
- Email: das@omega.com

Installing the software

Refer to the *Software User's Guide* for instructions on installing the software on the CD. This booklet is available in PDF at <http://www.omega.com/manuals/manualpdf/M4803.pdf>.

Installing the hardware

To connect the OM-USB-32DIO to your system, turn on your computer and connect the USB cable to an available USB port on the computer or to an external USB hub connected to the computer. Connect the other end of the USB cable to the USB connector on the device. No external power is required. A green **Status** LED turns on when power is applied.

When you connect the device for the first time, a **Found New Hardware** dialog opens when the operating system detects the device. The dialog closes after the device is installed.

Firmware updates

OM-USB-32DIO firmware can be updated in the field using InstaCal if required.

Functional Details

External components

The OM-USB-32DIO has the following external components:

- Screw terminals
- USB connector
- LED indicators

Screw terminals

The screw terminals provide the following connections:

- 32 digital I/O bits configured as two 16-bit ports (**P0 D0** to **P1 D15**)
- External input scan clock input (**ICLKI**) and output (**ICLKO**) for digital inputs
- External output scan clock input (**OCLKI**) and output (**OCLKO**) for digital outputs
- External trigger input (**TRIG**)
- Data transfer output (**TXACK**)
- Power output (**+VO**)
- Digital ground (**GND**)

The pinout is shown in Figure 2.

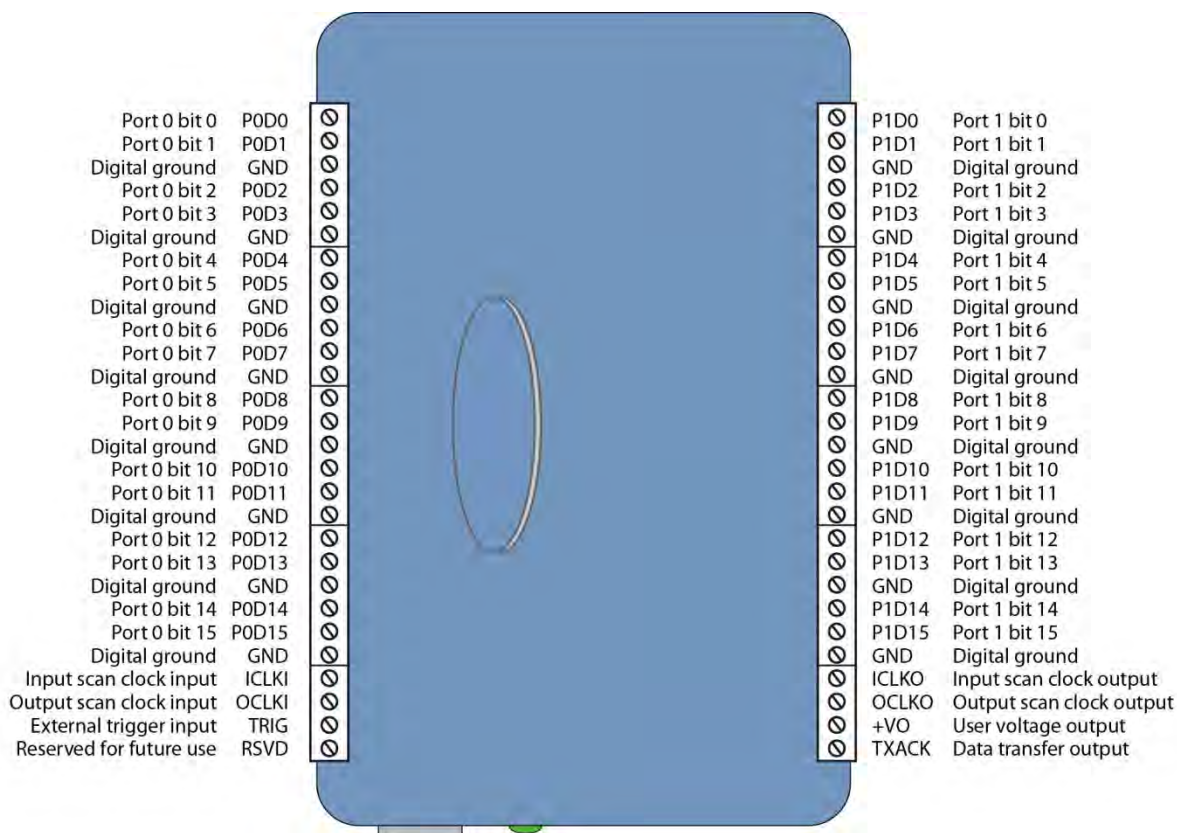


Figure 2. OM-USB-32DIO pinout

USB connector

The USB connector provides +5 V power and communication. No external power supply is required.

LED indicators

The OM-USB-32DIO has two LED indicators that indicate the status of power and data. The LEDs are stacked one above the other; refer to Figure 3.

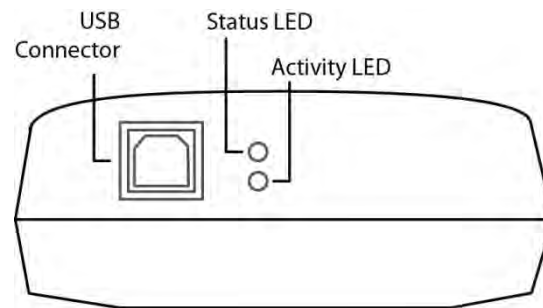


Figure 3. LED indicators

- The **Status** LED turns on when power is applied.
- The **Activity** LED blinks when data is being transmitted over the USB bus.

Signal connections

Digital I/O

The OM-USB-32DIO provides 32 digital I/O bits that are configured as two ports of 16-bits each. You can connect up to 16 DIO lines to port 0 (**P0 D0** through **D0 D15**), and up to 16 DIO lines to port 1 (**P1 D0** through **P1 D15**). Each digital bit is individually configurable for input or output. Refer to [Digital operations](#) on page 9 for more information.

Clock I/O

You can pace input scanning operations using the onboard input scan clock or with an external signal connected to **ICKLI**. The input clock frequency is 8 MHz, maximum.

When the internal input clock paces operations, a duty cycle of 50% is maintained on **ICKLO**. When an external clock is used, the signal is output immediately after the external clock input is received.

Input pacer clock connections:

- **ICKLI**: accepts an external scan clock signal to pace the internal input scan.
- **ICKLO**: outputs the internal input scan clock. When externally clocked, this pin outputs a delayed version of the **ICKLI** signal. The delay is no more than 83.33 ns, and is due to the time required for the signal to propagate from the external clock to the device's FPGA before it is output.

You can pace the output pattern generation using the onboard output scan clock or with an external signal connected to **OCKLI**. The output clock frequency is 8 MHz, maximum.

Output pacer clock connections:

- **OCKLI**: accepts an external scan clock signal to pace the output scan.
- **OCKLO**: outputs the internal output scan clock. When externally clocked, this pin outputs a delayed version of the **OCKLI** signal. The delay is no more than 83.33 ns, and is due to the time required for the signal to propagate from the external clock to the device's FPGA before it is output.

Trigger input

The **TRIG** terminal is an external digital trigger input that can be used to trigger digital input or output scans.

Data transfer output

The **TXACK** pin is a timing output that may be used when transferring data to an external peripheral device or to a second OM-USB-32DIO. Refer to the [Digital output scanning](#) section on page 9 for more information.

User voltage power output

The **+VO** terminal can output up to 10 mA maximum. You can use this terminal to supply power to external devices or circuitry.

Caution! The **+VO** terminal is an output. Do not connect to an external power supply or you may damage the device and possibly the computer.

Ground

The digital ground (**GND**) pins provide a common ground for all I/O signals and the power terminal.

Digital operations

When performing software polling operations, the port can contain any combination of input or output bits. When performing hardware-paced output scans, all bits in the port must be set for output. For input scans, however, any bits in the port that are configured for output are ignored. Since each port is configured independently, both software polling and hardware scanning operations can be performed at the same time.

The digital I/O terminals can detect the state of any TTL-level input. Refer to the schematic shown in Figure 4.

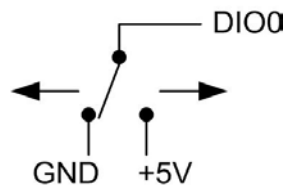


Figure 4. Schematic showing switch detection by digital channel DIO0

If you set the switch to the +5 V input, DIO0 reads *TRUE* (1). If you move the switch to GND, DIO0 reads *FALSE* (0).

Digital output scanning

Digital outputs can source 24 mA and sink 10 mA.

Either port can output a 16-bit digital pattern. The pattern is updated at a rate up to 8 MS/s, and clocked using the output scan clock.

Use both ports to output a 32-bit digital pattern. Data from one port is read and stored in the FIFO buffer until the second port is read. Both ports are output simultaneously to the pins on the rising edge of the next pacer clock signal.

The OM-USB-32DIO utilizes a delay between the output scan clock and the **TXACK** pin output. When each data value of an output scan is output, the **TXACK** pin is updated after a lag of 83.33 nS. This delay allows an external device that is accepting the data to know that the data is stable at that point, and ensures a coherent data transfer between devices.

When transferring data to a second (slave) OM-USB-32DIO, the input scan clock on the slave device is paced by the **TXACK** pin on the master device to ensure that the output data of the master is valid when acquired by the slave.

Pull-up/ down configuration

Each group of eight DIO bits can be pulled up to 5V or down to 0V (default) through 47 k Ω resistors via onboard jumpers **W3** to **W6**.

- W3 configures port 0 bit 0 to bit 7
- W4 configures port 0 bit 8 to bit 15
- W5 configures port 1 bit 0 to bit 7
- W6 configures port 1 bit 8 to bit 15

The pull-up/down voltage is common to all 47 k Ω resistors.

Figure 5 shows the jumper and pin locations on the board.

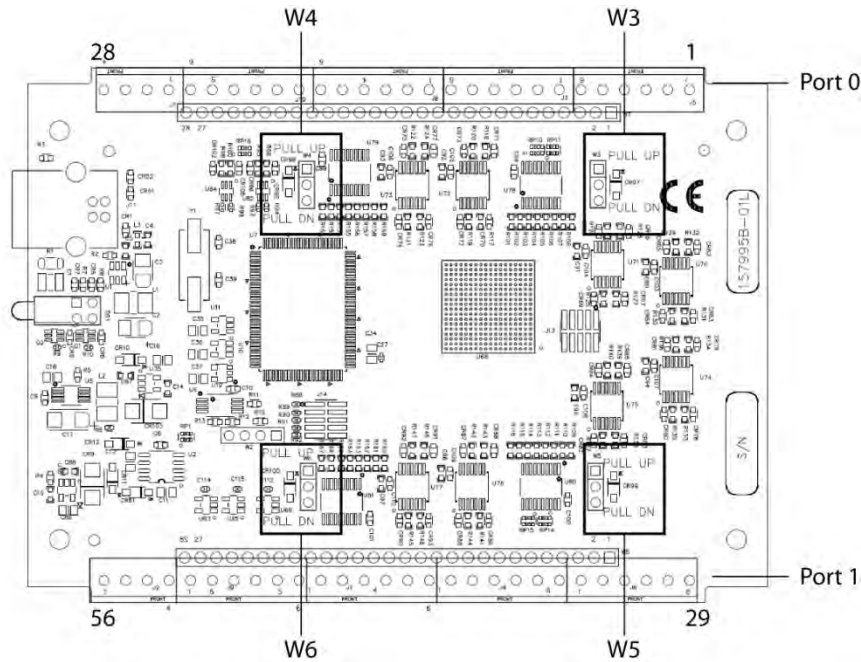


Figure 5. Pull-up/ down jumper locations

Each jumper is configured for pull-down by default (see Figure 6). Jumper pins 1 and 2 to configure the inputs for pull-up (+5V).

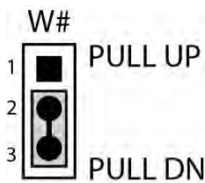


Figure 6. Pull-up/ down jumper, default

You must remove the board from its enclosure in order to change the pull-up down configuration. Complete the following steps to access the pull-up/down jumpers on the board:

Caution! The discharge of static electricity can damage some electronic components. Before removing the device from its housing, ground yourself using a wrist strap or touch the computer chassis or other grounded object to eliminate any stored static charge.

1. Turn the device over and rest the top of the housing on a flat, stable surface.
2. Peel off the four rubber feet on the bottom of the device to access the screws.
3. Remove the four screws from the bottom of the device.
4. Hold both the top and bottom sections together, turn the device over and rest it on the surface, then carefully remove the top section of the case to expose the circuit board.
5. Configure the appropriate jumper for either pull-up or pull-down. Each jumper is configured by default for pull-down.
6. Replace the top section of the case, and fasten it to the bottom section with the four screws. Replace the rubber feet onto each screw.

For more information about digital signal connections
 For general information about digital signal connections and digital I/O techniques, refer to the *OMB-DAQ-2400*, *OMB-DAQ-TC-RACK*, *OM-NET*, *OM-USB*, *OM-WEB*, and *OM-WLS Series General Guide to Signal Connections* (available on our web site at www.omega.com/manuals/manualpdf/M4830.pdf).

Triggering

The OM-USB-32DIO supports digital and pattern triggering.

Digital triggering

The **TRIG** pin is used for external TTL-level triggering, and can be used to trigger input or output scans. Trigger latency is less than $1\ \mu\text{s}$. The trigger mode is software-selectable for edge or level sensitive, and high or low logic. The default setting at power up is edge sensitive, rising edge. You can set up a repetitive trigger mode with software; the trigger is automatically rearmed after it is activated.

Pattern triggering

Either digital port can be used for pattern triggering. Supported trigger types are Above Pattern, Below Pattern, Equal Pattern, and Not Equal Pattern. Specific bits can be masked or ignored. The trigger latency is 1 scan clock period. You can input or output a digital pattern under the timing control of a clock signal.

A timing diagram showing digital pattern detection is shown in Figure 7. The pulse width of each clock cycle is 10.416 ns. The scan is triggered when a pattern is detected.

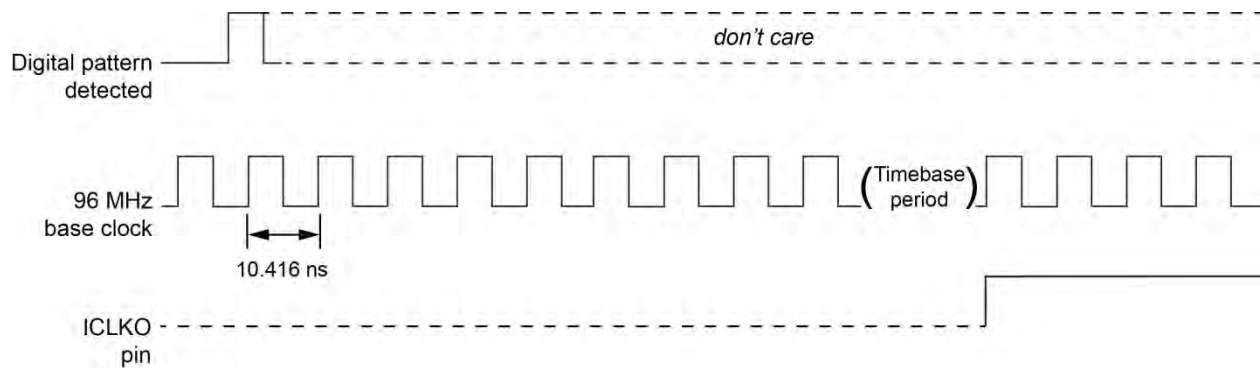


Figure 7. Digital pattern detection timing diagram

Signals after the trigger are ignored by the trigger circuit. You can increase the clock frequency up to 8 MHz to change how fast a pattern is detected.

Mechanical drawings

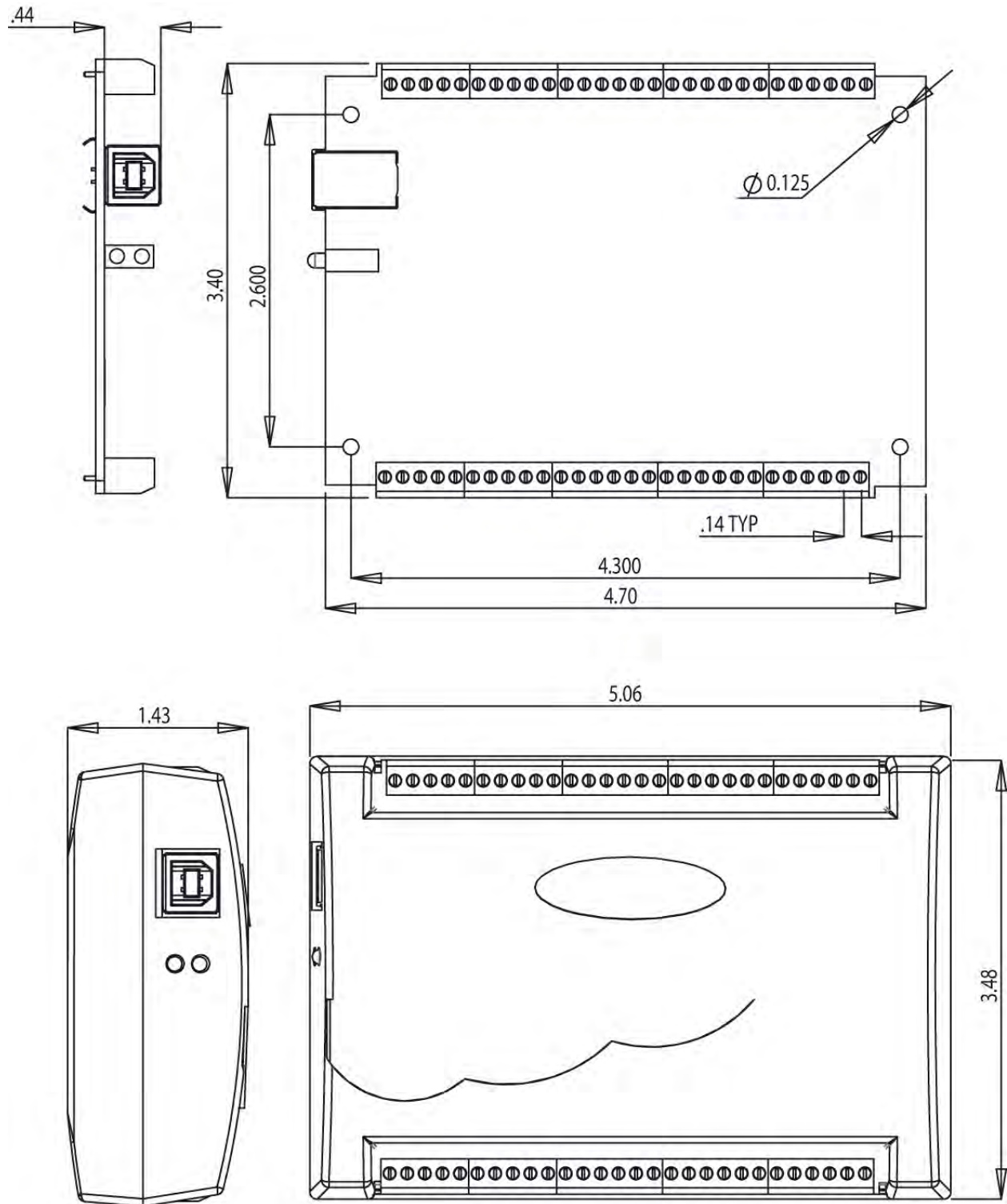


Figure 8. OM-USB-32DIO circuit board (top) and enclosure dimensions

Specifications

All specifications are subject to change without notice.

Typical for 25 °C unless otherwise specified.

Specifications in *italic text* are guaranteed by design.

Digital input/ output

Table 1. Digital I/O specifications

Parameter	Specification
Digital type	TTL
Number of I/O	32 (2 ports of 16 bits)
Configuration	Bit-configurable as input (power on default) or output
Pull-up configuration	Each port has two 47 k Ω resistors configurable as a pull-up or pull-down (default) with an internal jumper. Each jumper configures 8 digital bits. <ul style="list-style-type: none"> ■ Jumper W3 configures port 0 bit 0 to bit 7 ■ Jumper W4 configures port 0 bit 8 to bit 15 ■ Jumper W5 configures port 1 bit 0 to bit 7 ■ Jumper W6 configures port 1 bit 8 to bit 15
Digital I/O transfer rate (system-paced, asynchronous)	33 to 8000 port reads/writes or single bit reads/writes per second typical, system dependent.
Digital I/O transfer rate (synchronous)	0.022 Hz to 8 MHz, based on the internal clock speed of 96 MHz
Digital input pacing	Onboard clock, external input scan clock (ICLKI)
Digital input trigger source	External single channel digital trigger (TRIG) or Pattern Detection
Digital output pacing	Onboard clock, external output scan clock (OCLKI)
Digital output trigger source	External single channel digital trigger (TRIG) or Pattern Detection
Input high voltage	2.0 V min 5.0 V absolute max
Input low voltage	0.8 V max 0 V recommended min
Output high voltage	4.4 V min (IOH = -50 μ A) 2.96 V min (IOH = -24 mA)
Output low voltage	0.1 V max (IOL = 50 μ A) 0.77 V max (IOL = 10 mA)
Output current	24 mA source, 10 mA sink max per pin, constrained to 384 mA across all output pins (digital outputs, pacer clock outputs, and +VO)

External trigger

Table 2. Digital trigger specifications

Parameter	Specification
Trigger source	External digital; TRIG terminal
Trigger mode	Software-selectable for edge or level sensitive, rising or falling edge, high or low level.
Retrigger mode	Trigger is rearmed after each trigger event
Trigger latency	100 ns max
Trigger pulse width	100 ns min
Input type	Schmitt trigger, 47 k Ω pull-down to ground with 33 Ω in series
Schmitt trigger hysteresis	0.76 V typ 0.4 V min 1.2 V max

Parameter	Specification
Input high voltage threshold	1.74 V typ 1.3 V min 2.2 V max
Input high voltage limit	5.5 V absolute max
Input low voltage threshold	0.98 V typ 0.6 V min 1.5 V max
Input low voltage limit	-0.5 V absolute min 0 V recommended min

Pattern trigger

Table 3. Pattern trigger specifications

Parameter	Specification
Trigger source	Port 0 or Port 1
Trigger types	Above pattern, Below pattern, Equal pattern, or Not equal pattern
Trigger stability	Digital port must be stable for 31.25 ns to be recognized as a pattern
Trigger bit width	Up to 16, adjustable through bitmask
Trigger latency	Up to 1 scan period

Clock input/ output

Table 4. Clock I/O specifications

Parameter	Specification
Terminal names	ICLKI, ICLKO, OCLKI, OCLKO
Terminal type	ICLKI: Input scan clock input, active on rising edge ICLKO: Input scan clock output, power on default is 0V, active on rising edge OCLKI: Output scan clock input, active on rising edge OCLKO: Output scan clock output, power on default is 0V, active on rising edge
Input clock frequency	8 MHz, max
Input clock pulse width	10.417 ns min
Input type	Schmitt trigger, 47 k Ω pull-down to ground with 33 Ω in series
Input Schmitt trigger hysteresis	0.76 V typ 0.4 V min 1.2 V max
Input high voltage threshold	1.74 V typ 1.3 V min 2.2 V max
Input high voltage limit	5.5 V absolute max
Input low voltage threshold	0.98 V typ 0.6 V min 1.5 V max
Input low voltage limit	-0.5 V absolute min 0 V recommended min
Output clock frequency	8 MHz, max
Output clock pulse width	Minimum 62.5 ns at 8 MHz, but varies according to the sample rate; always maintains a 50% duty cycle when using the internal clock. When using the external clock, it follows the external clock input.
Output high voltage	4.4 V min (IOH = -50 μ A) 2.96 V min (IOH = -24 mA)
Output low voltage	0.1 V max (IOL = 50 μ A) 0.77 V max (IOL = 10 mA)
Output current	24 mA source, 10mA sink max per pin, constrained to 384 mA across all output pins (digital outputs, pacer clock outputs, and +VO)
Handshaking	The TXACK output will have an 83.33ns delay from the OCLKO signal to ensure coherent data transfers between devices.

Memory

Table 5. Memory specifications

Parameter	Specification
FIFO	8 KS
Non-volatile EEPROM	32 KB (10 KB firmware storage, 22 KB user data)

Power

Table 6. Power specifications

Parameter	Condition	Specification
Supply current, USB source	During enumeration	< 100 mA
	After USB enumeration	< 500 mA
+VO voltage output range	After USB enumeration	5 V, $\pm 5\%$
+VO output current	After USB enumeration	24 mA max per pin, constrained to 384 mA across all output pins (digital outputs, pacer clock outputs, and +VO)

USB

Table 7. USB specifications

Parameter	Specification
USB device type	USB 2.0 (high-speed)
Device compatibility	USB 1.1, USB 2.0, USB 3.0
USB cable type	A-B cable, UL type AWM 2725 or equivalent. Min 24 AWG VBUS/GND, min 28 AWG D+/D-.
USB cable length	3 m (9.84 ft) max

Environmental

Table 8. Environmental specifications

Parameter	Specification
Operating temperature range	0 °C to 50 °C
Storage temperature range	-40 °C to 70 °C
Humidity	0% to 90% non-condensing

Mechanical

Table 9. Mechanical specifications

Parameter	Specification
Dimensions (L × W × H)	128.52 × 88.39 × 35.56 mm (5.06 × 3.48 × 1.43 in.)

Signal connector

Table 10. Screw terminal specifications

Parameter	Specification
Connector type	Screw terminal
Wire gauge range	16 AWG to 30 AWG

Screw terminal pinout

Table 11. Screw terminal pinout

Pin	Signal name	Pin description	Pin	Signal name	Pin description
1	P0D0	Port 0 bit 0	29	P1D0	Port 1 bit 0
2	P0D1	Port 0 bit 1	30	P1D1	Port 1 bit 1
3	GND	Digital ground	31	GND	Digital ground
4	P0D2	Port 0 bit 2	32	P1D2	Port 1 bit 2
5	P0D3	Port 0 bit 3	33	P1D3	Port 1 bit 3
6	GND	Digital ground	34	GND	Digital ground
7	P0D4	Port 0 bit 4	35	P1D4	Port 1 bit 4
8	P0D5	Port 0 bit 5	36	P1D5	Port 1 bit 5
9	GND	Digital ground	37	GND	Digital ground
10	P0D6	Port 0 bit 6	38	P1D6	Port 1 bit 6
11	P0D7	Port 0 bit 7	39	P1D7	Port 1 bit 7
12	GND	Digital ground	40	GND	Digital ground
13	P0D8	Port 0 bit 8	41	P1D8	Port 1 bit 8
14	P0D9	Port 0 bit 9	42	P1D9	Port 1 bit 9
15	GND	Digital ground	43	GND	Digital ground
16	P0D10	Port 0 bit 10	44	P1D10	Port 1 bit 10
17	P0D11	Port 0 bit 11	45	P1D11	Port 1 bit 11
18	GND	Digital ground	46	GND	Digital ground
19	P0D12	Port 0 bit 12	47	P1D12	Port 1 bit 12
20	P0D13	Port 0 bit 13	48	P1D13	Port 1 bit 13
21	GND	Digital ground	49	GND	Digital ground
22	P0D14	Port 0 bit 14	50	P1D14	Port 1 bit 14
23	P0D15	Port 0 bit 15	51	P1D15	Port 1 bit 15
24	GND	Digital ground	52	GND	Digital ground
25	ICLK1	Input scan clock input	53	ICLKO	Input scan clock output
26	OCLK1	Output scan clock input	54	OCLKO	Output scan clock output
27	TRIG	External trigger input	55	+VO	User voltage output
28	RSVD	Reserved for future use	56	TXACK	Data transfer output

WARRANTY/DISCLAIMER

OMEGA ENGINEERING, INC. warrants this unit to be free of defects in materials and workmanship for a period of **13 months** from date of purchase. OMEGA's WARRANTY adds an additional one (1) month grace period to the normal **one (1) year product warranty** to cover handling and shipping time. This ensures that OMEGA's customers receive maximum coverage on each product.

If the unit malfunctions, it must be returned to the factory for evaluation. OMEGA's Customer Service Department will issue an Authorized Return (AR) number immediately upon phone or written request. Upon examination by OMEGA, if the unit is found to be defective, it will be repaired or replaced at no charge. OMEGA's WARRANTY does not apply to defects resulting from any action of the purchaser, including but not limited to mishandling, improper interfacing, operation outside of design limits, improper repair, or unauthorized modification. This WARRANTY is VOID if the unit shows evidence of having been tampered with or shows evidence of having been damaged as a result of excessive corrosion; or current, heat, moisture or vibration; improper specification; misapplication; misuse or other operating conditions outside of OMEGA's control. Components in which wear is not warranted, include but are not limited to contact points, fuses, and triacs.

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The purchaser is responsible for shipping charges, freight, insurance and proper packaging to prevent breakage in transit.

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- ☑ Refractometers
- ☑ Pumps & Tubing
- ☑ Air, Soil & Water Monitors
- ☑ Industrial Water & Wastewater Treatment
- ☑ pH, Conductivity & Dissolved Oxygen Instruments