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CN710/CN730/CN740 Temperature Controller Instruction Sheet

Thank you very much for purchasing Omega Engineering CN700 Series Temperature Controller. Please read this instruction sheet before using your controller to ensure proper operation and please keep this instruction sheet handy for auick reference

Precaution

- DANGER! Caution! Electric Shock!
- DO NOT touch the AC terminals while the power is supplied to the controller to prevent an electric shock. 1 Make sure power is disconnected while checking the unit inside. 2.
- The symbol \square indicates this Controller is protected throughout by DOUBLE INSULATION or REINFORCED 3. INSULATION (equivalent to Class II of IEC 536).

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Mount the controller in a location that will not be subject to excessive temperature, shock, or vibration. All models are designed for mounting in an enclosed panel.

- 1. Always use recommended solder-less terminals: Fork terminal with isolation (M3 screw, width is 7.0mm, hole diameter 3.2mm). Screw size: M3 x 6.5 (With 6.8 x 6.8 square washer). Recommended tightening torque: 0.4 N.m. (4kgf cm). Applicable wire: Solid/twisted wire of 2 mm², 12AWG to 24AWG. Please be sure to tighten them properly
- 2. DO NOT allow dust or foreign objects to fall inside the controller to prevent it from malfunctioning.
- Never modify or disassemble the controller 3.
- DO NOT connect anything to the "Not used" terminals. 4.
- Make sure all wires are connected to the correct polarity of terminals. 5
- 6. DO NOT install and/or use the controller in places subject to: Dust or corrosive gases and liquid, high humidity and high radiation, vibration and shock, high voltage and high frequency
- Power must be off when wiring and changing a temperature sensor.
- Be sure to use compensating wires that match the thermocouple types when extending or connecting the 8. thermocouple wires.
- 9. Please use wires with resistance when extending or connecting a platinum resistance sensor (RTD). 10. Please keep the wire as short as possible when wiring a platinum resistance sensor (RTD) to the controller and
- please route power wires as far as possible from load wires to prevent interference and induced noise. 11. This controller is an open-type unit and must be placed in an enclosure away from high temperature, humidity, dripping water, corrosive materials, airborne dust and electric shock or vibration.
- 12. Please make sure power cables and signals from instruments are all installed properly before energizing the controller, otherwise serious damage may occur.
- 13. Please do not touch the terminals in the controller or try to repair the controller when power is applied to prevent an electric shock.
- 14. Wait at least one minute after power is disconnected to allow capacitors to discharge, and please do not touch any internal circuit within this period.
- 15. DO NOT use acid or alkaline liquids for cleaning. Please use a soft, dry cloth to clean the controller.
- 16. This instrument is not furnished with a power switch or fuse. Therefore, if a fuse or power switch is required, install the protection close to the instrument. Recommended fuse rating: Rated voltage 250 V, Rated current 1 A. Fuse type: Time-lag fuse
- 17. Note: This controller does not provide overcurrent protection. Use of this product requires that suitable overcurrent protection device(s) must be added to ensure compliance with all relevant electrical standards and codes. (Rated 250 V, 15 Amps max). A suitable disconnecting device should be provided near the controller in the end-use installation

Display, LED, & Pushbuttons



| Input Temperature Sensor Type | Register Value | LED Display | Temperature Range |
|------------------------------------|----------------|-------------|-------------------|
| Platinum resistance (Pt100) type2 | 14 | P53 | -20.0 ~ 500.0°C |
| Platinum resistance (Pt100) type1 | 13 | PE (| -200 ~ 600°C |
| Platinum resistance (JPt100) type2 | 12 | J865 | 0.0 ~ 100.0°C |
| Platinum resistance (JPt100) type1 | 11 | JPE 1 | -20.0 ~ 400.0°C |
| Thermocouple (TC) B type | 10 | ხ | 100 ~ 1,800°C |
| Thermocouple (TC) S type | 9 | 5 | 0 ~ 1,700 °C |
| Thermocouple (TC) R type | 8 | C | 0 ~ 1,700 °C |
| Thermocouple (TC) N type | 7 | 0 | -200 ~ 1,300 °C |
| Thermocouple (TC) E type | 6 | 8 | 0 ~ 600 °C |
| Thermocouple (TC) T type2 | 5 | 53 | -20.0 ~ 400.0°C |
| Thermocouple (TC) T type1 | 4 | 5 | -200 ~ 400°C |
| Thermocouple (TC) J type2 | 3 | 56 | -20.0 ~ 400.0°C |
| Thermocouple (TC) J type1 | 2 | J 1 | -100 ~ 850°C |
| Thermocouple (TC) K type2 | 1 | 53 | -20.0 ~ 500.0°C |
| Thermocouple (TC) K type1 | 0 | 81 | -200 ~ 1,300°C |
| Thermocouple (TC) L type | 16 | Ł | -200 ~ 850°C |
| Thermocouple (TC) U type | 17 | U | -200 to 500°C |
| Thermocouple (TC) Txk type | 18 | 828 | -200 to 800°C |

Operation

There are three modes of operation: operation, regulation and initial setting. When power is applied, the controller will default to the operation mode. Press D to switch to regulation mode. If D is pressed for more than 3 seconds, the controller will switch to the initial setting mode. Pressing D while in the regulation mode or initial setting mode, forces the controller to return to the operation mode. PV/SV: Sets the temperature set point and displays the temperature process value. Use **I** to set the temperature set point.

Setting method: While in any function mode, press 💬 to select the desired function and use 🛆 💟 to change settings. Press Press to save the changes. Menu items are listed below.

| Regulation Mode | Operation Mode | Initial Setting Mode |
|--|--|---|
| 82 Auto-tuning | 1234 Use 🔨 🔨 to set | Set input type |
| (Set in PID control & RUN mode) Press | temperature set point 7 Press ▽ | Press \mathbf{r} |
| (in PID control) | Control setting RUN or STOP | Kertemperature unit (Not displayed when in analog input) |
| Press 🖙 🗸 | 7 Press 📼 🗸 | Press 📼 ∇ |
| (in PID control) | BL IH Upper-limit alarm 1 (This parameter is available only when ALA1 function is enabled.) | EP-H Set upper-limit of temperature range |
| Press 🕶 🗸 | 7 Press 📼 🗸 | Press 📼 ∇ |
| G Set derivative time (Kt) (in PID control) | BLFL Lower-limit alarm 1 (This parameter is available only when ALA1 function is enabled.) | EP-L Set lower-limit of temperature range |
| Press 🕶 🗸 | 7 Press 📼 ▽ | Press 📼 ∇ |
| PdoF or CoF P/PD control offset (when PID control is ON and Ki=0 set the value of PdoF. If Ki≠0, A (Auto-tuning will automatically set the value of ioF. | HEPH Upper-limit alarm 2 (This parameter is available only when T ALA2 function is enabled.) | Set Control method: ON/OFF, PID, or manual. |
| Press 🗖 🗸 | 7 Press 📼 🗸 | Press \mathbf{Press} |
| HES or EES Heating/cooling hysteresis (in ON/OFF control) | BLEE Lower-limit alarm 2 (This parameter is available only when ALA2 function is enabled.) | S-HC Select heating or cooling control. |
| Press 🗖 🗸 | 7 Press 📼 ▽ | Press $\mathbf{\overline{P}}$ |
| HEPd or ELPd Heating/cooling control cycle setting (Set in PID control mode) | Set lock mode | RLR Alarm 1 mode setting |
| Press 📼 🗸 | 7 Press 🖙 🗸 | Press $\mathbf{\nabla}$ |
| EPoF Regulate temperature deviation value | out Display and adjust output value. | RLR2 Alarm 2 mode setting |
| Press 🕶 🗸 | 7 Press 📼 🗸 | Press $lacksquare$ |
| CRE Regulate upper-limit of analog output value (The setting is displayed when in analog output) | | CoSH Communication write function enabled/disabled |
| Press Pr | 7 | Press $\mathbf{\nabla}$ |

| CCLO Regulate lower-limit of analog output value |
|--|
| (The setting is displayed when i |
| analog output) |
| Press 📼 to return to "auto- |
| |
| |
| |

Parameters List

LED Display

1. Operation Mode: The default mode after start-up

| LED Display | Explanation | Default |
|--------------|--|---------|
| r - 5 | RUN/STOP: Control setting. Run ($rigin)$ or Stop ($520P$) mode on the SV display. | RUN |
| 81 18 | ALARM 1 HIGH: Upper limit for alarm 1. (Only available when alarm is set in the initial setting mode). | 4.0°C |
| 81 11 | ALARM 1 LOW: Lower limit for alarm 1. (Only available when alarm is set in the initial setting mode). | 4.0°C |
| 8658 | ALARM 2 HIGH: Upper limit for alarm 2. (Only available when alarm is set in the initial setting mode). | 4.0°C |
| 8151 | ALARM 2 LOW: Lower limit for alarm 2. (Only available when alarm is set in the initial setting mode). | 4.0°C |
| LoC | Lock Function Setting: LoC1, LoC2, or OFF. LoC1 mode will lock all settings, LoC2 locks everything except the set point value, and OFF will not lock any settings. Press and a keys simultaneously, to release the lock status. | OFF |
| oUt | OUT: The Output value adjustment and display in manual tuning control. (Not available in ON/OFF or Auto-tuning control). | 0 |
| . Regulation | Mode: Control parameters Settings | |

| 85 | function in PID control is select |
|------------------|--|
| Р | P (Proportiona |
| Ē | I (Integral Time |
| ರ | D (Derivative T |
| PdoF | PdoF: Offset o selected and the |
| CoF | ioF: Default va Time in regulat parameter whe |
| HE S | HtS (Heating H heating hystere |
| 685 | CtS (Cooling H cooling hystere |
| HEP9 | HtPd: PID heat selected in the |
| 6693 | CIPd: PID cool selected in the |
| 6PoF | TPoF: Regulat |
| ErHE | CrHi: Regulate |
| Erto | CrLo: Regulate |
| Erto | HtS (Heating H heating hystere |
| . Initial Settin | g Mode: Initial |
| LED Display | |
| in92 | INPUT: Select (Please refer to Range" for deta |
| 290n | Engineering U |
| 6 8- 8 | T-High: Upper |
| 58-L | T-Low: Lower |

CONTROL ME

method for the

Control Action

Fei

S-80

| 1 | E - no setting | Communication address |
|--------|-------------------|-------------------------------|
| uning" | | Press $\mathbf{\nabla}$ |
| | 5PS setting | Communication baud rate |
| | | Press 🗖 $ abla$ |
| | 180 | Data length setting |
| | | Press 🖙 ∇ |
| | ዖгとソ | Parity bit setting |
| | | Press 🖙 🗸 |
| | Stop | Stop bit setting |
| | Press | to return to "set input type" |
| | | |

Default Explanation AT (Auto-Tuning): ON or OFF, when set ON, the execution of the auto-tuning OFF control mode is automatically started. (Only available when PID cted in initial settings) al Band in PID control): Sets P value 47.6 e in PID control): Sets I value. 260 Time in PID control): Sets D value. 41 output when P or PD control function is on. PID in initial settings is 0 the value of Ki (Integral Time in regulation mode) is equal to zero. alue of integral volume when PID control is ON and the Ki (Integral tion mode) is not equal to zero. AT function can automatically set this 0 en PID control is active and Ki≠0. Hysteresis): Available only in ON/OFF control. Sets the value the 0 resis Hysteresis): Available only in ON/OFF control. Sets the value the 0 esis ating control cycle setting. Only available when a PID control is Output initial settings. Selection: Voltage: 4 sec ling control cycle setting. Only available when a PID control is Relay: 20 sec. initial settings. ates the temperature deviation value. 0 es the 20mA output deviation value. 0 tes the 4mA output deviation value 0 Hysteresis): Available only in ON/OFF control. Sets the value the 0 settings of the controller and communication parameters

| Explanation | Default |
|---|---------|
| input temperature sensor type o the contents of the "Temperature Sensor Type and Temperature ail) | PT2 |
| nit(°F or °C): Select engineering unit F or C. | °C |
| limit for temperature range. | 500.0 |
| imit for temperature range. | -20.0 |
| THOD (ON/OFF, PID, or manual tuning [^ら おっじ]): Sets the control set point value. | PID |
| (Direct or Reverse Acting): Cooling [Cool] or heating [HEAT]. | HEAT |

| LED Display | Explanation | Default |
|---------------|--|---------|
| 868 1 | ALARM 1: Alarm 1 setting. (See Alarm Output Section for set values and descriptions). | 0 |
| 8185 | ALARM 2: Alarm 2 setting. (See Alarm Output Section for set values and descriptions). | 0 |
| CoSK | C WE: Write-in function disabled/enabled. Can be set only when unit is equipped with serial communication. | OFF |
| 8-00 | C NO: Address setting. Can be set only when unit is equipped with serial communication. | 1 |
| 685 | BPS: Baud rate setting. Can be set only when unit is equipped with serial communication. | 9,600 |
| 180 | Length: Data length setting. Can be set only when unit is equipped with serial communication. | 7 |
| ዖィとソ | Parity: Parity bit setting. Can be set only when unit is equipped with serial communication. | E |
| <u> </u> Stop | Stop Bit: Stop bit setting. Can be set only when unit is equipped with serial communication. | 1 |

Execution

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The programming execution is initiated through -5 in the operation mode.

When is set to when the program will start to execute in order from the step 0 of the start pattern.

When set to set to set to set of the program will stop and the control output is disabled

Heating & Cooling

Temperature control can be achieved either by heating or cooling. Please refer to the following for the operation: Settings for heat or cool operation are found in the initial settings mode under

Select **HERE**, for heating (reverse) control on Output 1.

Select for cooling (forward) control on Output 1

Input Error Indication

| Setting value | Temperature sensor is not connected | Measured temperature value exceeds the temperature range | Unknown input |
|---------------|--|--|---------------|
| PV | 00 | outr | Err |
| SV | Cont | | CnPE. |
| - | | | |

Alarm Outputs

Depending on the controller model, there can be up to two alarm outputs. Each alarm output can be configured for an alarm type listed below. Alarm types are set in the initial setting mode. The alarm output is activated whenever the process temperature value (PV) is getting higher or lower than the set point of alarm limit.

| Set Value | Alarm Type Alarm Output | | peration |
|--------------|--|-----------------------------------|----------------|
| 0 | Alarm function disabled | Narm function disabled Output OFF | |
| 1 | Deviation upper- and lower-limit: This alarm output operates when PV value is higher than the setting value SV+(AL-H) or lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV | SV+(AL-H) |
| 2 | Deviation upper-limit: This alarm output operates when PV value is higher than the setting value SV+(AL-H). | ON OFF | ▲ SV+(AL-H) |
| 3 | Deviation lower-limit: This alarm output operates when PV value is lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV | |
| 4 | Reverse deviation upper- and lower-limit: This alarm output operates when PV value is in the range of the setting value SV+(AL-H) and SV-(AL-L). | ON OFF SV-(AL-L) SV | SV+(AL-H) |
| 5 | Absolute value upper- and lower-limit: This alarm output operates when PV value is higher than the setting value AL-H or lower than setting value AL-L. | ON OFF AL-L | AL-H |
| 6 | Absolute value upper-limit: This alarm output operates when PV value is higher than the setting value AL-H. | ON OFF | AL-H |
| 7 | Absolute value lower-limit: This alarm output operates when PV value is lower than the setting value AL-L. | OFF AL-L | |
| 8 | Deviation upper- and lower-limit with standby sequence: This alarm output operates when PV value reaches set point (SV value) and the value is higher than the setting value SV+(AL-H) or lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV | SV+(AL-H) |
| 9 | Deviation upper-limit with standby sequence: This alarm output operates when PV value reaches set point (SV value) and the reached value is higher than the setting value SV+(AL-H). | ON OFF | SV+(AL-H |
| 10 | Deviation lower-limit with standby sequence: This alarm output operates when PV value reaches the set point (SV value) and the reached value is lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV | |
| 11 | Hysteresis alarm output: Heating control: This alarm output operates if PV value is higher than the setting value SV+ (AL-H). This alarm output is OFF when PV value is lower than the setting value SV+ (AL-L). | ON OFF SV AL | -L AL-H |

| Set Value | Alarm Type | Alarm Output Operation |
|--------------|--|------------------------|
| 12 | Hysteresis alarm output: Cooling control: This alarm output operates if PV value is lower than the setting value SV-(AL-H). This alarm output is OFF when PV value is higher than the setting value SV- (AL-L). | OFF AL-H AL-L SV |

(Note: AL-H and AL-L include AL1H, AL2H and AL1L, AL2L)

With the standby sequence, the alarm output will be temporarily disabled until the PV value reaches the set value. Then, the alarm output will operate. Once the alarming output operation is activated, there is a 1.5 sec. delay time to avoid any malfunction.

| 8 | Specification |
|-------------------------|---|
| | 100 to 240VAC 50/60Hz |
| | |
| Operation voltage range | 05% to 110% of rated voltage |
| Power consumption | 5VA max. |
| Memory protection | EEPROM 4K bit (non-volatile memory (number of writes: 100,000) |
| Display method | 2 line x 4 character 7-segment LED display Process value (PV): Red color, Set point (SV): Green color |
| Sensor type | Thermocouple: K, J, T, E, N, R, S, B, L, U, TXK |
| | 3-wire Platinum RTD: Pt100, JPt100 |
| Control mode | PID, ON/OFF, manual or auto-tuning. |
| | Relay output: SPDT (SPST on the 1/16 DIN size series16C), Max. load 250VAC, 5A resistive load |
| | Voltage pulse output: DC 14V, Max. output current 40mA |
| | Current output: DC 4 ~ 20m A output (Load resistance: Max. 600Ω) |
| Display accuracy | 0.1% of measuring range. |
| Sampling rate | 0.5 sec. |
| RS-485 communication | MODBUS ASCII communication protocol (only on models designated with serial communication). |
| Vibration resistance | 10 to 55Hz, 10m/s ² for 10min, each in X, Y and Z directions |
| Shock resistance | Max. 300m/ s ² , 3 times in each 3 axes, 6 directions |
| Ambient temperature | 32°F to 122°F (0°C ~ +50°C) |
| Storage temperature | -4°F ~ 150°F (-20°C ~ +65°C) |
| Altitude | 2,000m or less |
| Relative humidity | 0% ~ 80% (non-condensing) |
| | |

95.

CN740

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60.0 mir (2.36)

65.0 min.



Plan Cutout & External Dimensions

Panel Cutout [dimensions are in mm (in.)] Terminals Identification



110.0 min. (4.33)

92.0 (3.62)

mm (in)

92.0 +0.6 (3.62) +0.02

9

CN730

120.0 mit (4.72)







Mounting Bracket Installation



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1.





Mounting

Step 2: Insert the mounting bracket into the mounting groove at the top and bottom of the controller

Step 3: Push the mounting bracket forward until the bracket stops at panel wall.

Step 4: Insert and tighten screws on bracket to secure the controller in place. (The screw torque should be 0.8kgf-cm









2.

