

CN7500/CN7800 Temperature Controller Instruction Sheet

Thank you very much for choosing Omega Engineering Series CN7500/CN7800 Temperature/Process Controller. Please read this instruction sheet before using your controller to ensure proper operation and please keep this instruction sheet handy for quick reference.

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Precaution

DANGER! Caution! Electric Shock!

- 1. Do not touch the AC terminals while the power is supplied to the controller to prevent an electric shock.
- 2. Make sure the power is disconnected while checking the unit inside.
- 3. The symbol indicates that this Controller is protected throughout by DOUBLE INSULATION or REINFORCED INSULATION (equivalent to Class II of IEC 536).

Mount the controller in a location that will not be subject to excessive temperature, shock, or vibration. All models are designed for mounting in an enclosed panel.

- Always use recommended solder-less terminals: Fork terminal with isolation (M3 screw, width is 7.0mm (6.0mm for 32B Series), hole diameter 3.2mm). Screw size: M3 x 6.5 (With 6.8 x 6.8 square washer). Screw size for 32B Series: M3 x 4.5 (With 6.0 x 6.0 square washer). Recommended tightening torque: 0.4 N.m (4kgf.cm). Applicable wire: Solid/twisted wire of 2 mm², 12AWG to 24AWG. Please be sure to tighten them properly.
- 2. Do not allow dust or foreign objects to fall inside the controller to prevent it from malfunctioning.
- 3. Never modify or disassemble the controller.
- 4. Do not connect anything to the "No used" terminals.
- 5. Make sure all wires are connected to the correct polarity of terminals.
- 6. Do not install and/or use the controller in places subject to: Dust or corrosive gases and liquid, high humidity and high radiation, vibration and shock, high voltage and high frequency
- 7. Power must be off when wiring and changing a temperature sensor.
- 8. Be sure to use compensating wires that match the thermocouple types when extending or connecting the thermocouple wires.
- 9. Please use wires with resistance when extending or connecting a platinum resistance sensor (RTD).
- 10. Please keep the wire as short as possible when wiring a platinum resistance sensor (RTD) to the controller and please route power wires as far as possible from load wires to prevent interference and induced noise.
- 11. This controller is an open-type unit and must be placed in an enclosure away from high temperature, humidity, dripping water, corrosive materials, airborne dust and electric shock or vibration.
- 12. Please make sure power cables and signals from instruments are all installed properly before energizing the controller, otherwise serious damage may occur.
- 13. Please do not touch the terminals in the controller or try to repair the controller when power is applied to prevent an electric shock.

- 14. Wait at least one minute after power is disconnected to allow capacitors to discharge, and please do not touch any internal circuit within this period.
- 15. Do not use acid or alkaline liquids for cleaning. Please use a soft, dry cloth to clean the controller.
- 16. This instrument is not furnished with a power switch or fuse. Therefore, if a fuse or power switch is required, install the protection close to the instrument. Recommended fuse rating: Rated voltage 250 V, Rated current 1 A. Fuse type: Time-lag fuse
- 17. Note: This controller does not provide overcurrent protection. Use of this product requires that suitable overcurrent protection device(s) must be added to ensure compliance with all relevant electrical standards and codes. (Rated 250 V, 15 Amps max). A suitable disconnecting device should be provided near the controller in the end-use installation.



CN7800 PV SV AT OUT1 OUT2 ALM

Display, LED and Pushbuttons

PV displays process value

SV displays setpoint value.

INDEX: advances the display to the next menu item

UP ARROW: Increments a value or changes a menu item.

DOWN ARROW: Increments a value or changes a menu item.

ENTER: stores the value or item change.

Note: CN7500 Series does not support an additional alarm output, however, the user can set 2nd output as alarm mode.

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Temperature Sensor Type and Temperature Range

| Input Temperature Sensor Type | Register Value | LED Display | Temperature Range |
|-------------------------------|----------------|---------------|-------------------------|
| 0 ~ 50mV Analog Input | 17 | กับ | -999 ~ 9999 |
| 4 ~ 20mA Analog Input | 16 | - 7 84 | -999 ~ 9999 |
| 0 ~ 20mA Analog Input | 15 | - 280 | -999 ~ 9999 |
| 0V ~ 10V Analog Input | 14 | U 10 | -999 ~ 9999 |
| 0V ~ 5V Analog Input | 13 | υS | -999 ~ 9999 |
| Platinum Resistance (Pt100) | 12 | <i>P</i> E | -200 ~ 600°C |
| Platinum Resistance (JPt100) | 11 | <i>പ</i> РЕ | -20 ~ 400°C |
| Thermocouple TXK type | 10 | 555 | -200 ~ 800°C |
| Thermocouple U type | 9 | U U | -200 ~ 500°C |
| Thermocouple L type | 8 | L | -200 ~ 850°C |
| Thermocouple B type | 7 | 6 | 100 ~ 1800°C |
| Thermocouple S type | 6 | 5 | 0 ~ 1700 [°] C |
| Thermocouple R type | 5 | r. | 0 ~ 1700°C |
| Thermocouple N type | 4 | n | -200 ~ 1300°C |
| Thermocouple E type | 3 | 3 | 0 ~ 600°C |
| Thermocouple T type | 2 | ٤ | -200 ~ 400°C |
| Thermocouple J type | 1 | ل ل | -100 ~ 1200°C |
| Thermocouple K type | 0 | 2 | -200 ~ 1300°C |

Note 1: An internal precision resistor for the current input is built-in, please refer to item 15, How To Set Up Current Input.

Note 2: (in the operation mode) specifies the decimal point position. All input types except thermocouple B, S, and R type, allow the decimal point position to be specified.

The default range of analog input is -999 ~ 9999. For example, when a 0~20mA analog input is selected as the input temperature sensor type, -999 indicates 0mA and 9999 indicates 20mA. If change the input range to 0 ~ 2000, then 0 indicates 0mA and 2000 indicates 20mA. One display scale is equal to 0.01mA.

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Operation

There are three modes of operation: operation, regulation and initial setting. When power is applied, the controller will default to the operation mode. Press the regulation mode. If the regulation mode. If the regulation mode, the controller will switch to the initial setting mode. Pressing the regulation mode or initial setting mode, forces the controller to return to the operation mode. PV/SV: Sets the temperature set point and displays the temperature process value. Use regulation were set the temperature set point.

Setting method: While in any function mode, press the key to select the desired function and use the keys to change settings. Press key to save the changes. Menu items are listed below.

| Regulation Mode | Operation Mode | Initial Setting Mode |
|---|--|---|
| RE Auto-tuning (Set in PID control and RUN mode) Press P | Image: 1234 Use Image: 1234 Key to set temperature set point Press Image: 1234 | Press 🖙 🦆 |
| 4 groups PID modes (n=0~3). When n=4, PID control is auto regulated. Press Image: Control Section | r = 5 Control setting RUN or STOP Press ☑ ↓ See "Execution" under Section 6 | 논우ᇅ · Set temperature unit do not display when analog input Press 로 다 |
| PD control offset setting (When PID control is ON and Ti=0, set the value of PdoF. Press P | PLCA Start pattern setting. Appears only when C-5 to PSEP Press Image: Constraint of the setting of the set of the | EP-H Set upper-limit of temperature range Press 🖙 🗘 |
| Heating hystereisis setting (Set in ON/OFF control mode) Press 🖙 🗘 | 5.9 Decimal point position selection (except for B, S, R type, all the other types can be set) Press P | EP-L Set lower-limit of temperature range Press |
| Cooling hystereisis setting (Set in ON/OFF control mode) Press 🖙 🗘 | BL IX Upper-limit alarm 1 (This parameter is available only when ALA1 function enables) Press P | Etet Sets Control Mode: on/off, pid, Prog, or manual. (Set to ProG for ramp/soak patterns) See Pattern and set editing. Press 🖙 🗘 |
| HEAD or CLAD Heating/Cooling control cycle setting (Set in PID control mode) Press 🖙 🗘 | 8:1: (This parameter is available only when ALA1 function enables)Press Q | Ramp/soak pattern. Only displayed when CtrL is set to ProG. |
| KCPC Control cycle setting of 2nd output group (Set in PID control and Dual Loop output control mode) Press 🔄 🗘 | ALA2 function enables) Press | 5-HE Select heating/cooling control or dual loop output control Press |

| CoEFP value of 1st & 2nd output group during dual loop output controlP value of 2nd output group = (P value of 1st output group) xCoEFPressI | REPENDENT (This parameter is available only when ALA2 function enables) Press Press | R! R I Alarm 1 mode setting Press 🖙 🗘 |
|--|---|---|
| Dead Band (Set in Dual Loop output control mode) Press | BL 3X Upper-limit alarm 3 (This parameter is available only when ALA3 function enables) Press P | RL R 2 Alarm 2 mode setting Press P |
| EPOF Regulate temperature deviation value Press | 8L3L Lower-limit alarm 3 (This parameter is available only when ALA3 function enables) Press 💽 🗘 | ALA3 Alarm 3 mode setting Press 🖙 🗘 |
| CrxC Regulate upper-limit of analog output value (The setting display when analog output) Press 🖙 🗘 | LoE Setting lock mode Press 🖙 | 5 <i>RL</i> 8 Set system alarm Press P |
| Crea output value (The setting display when analog output) Press To return to auto-tuning mode | Display and adjust output value of 1st output group (Display in PID control mode and manual RUN mode) Press 🖙 🗘 | Communication write function enable/disable Press 🖙 🗘 |
| | Display and adjust output value of 2nd output group (Display in dual loop PID control mode and manual RUN mode) Press 🖙 🕂 | C-St ASCII, RTU communication format selection Press P |
| | | Communication address setting Press 🖸 🗘 |
| | | BPS Communication baud rate setting Press |
| | | LEn Data length setting Press ☞ ↓ |
| | | 우규는 Y Parity bit setting Press 📼 🗘 |
| | | Stop bit setting Press 🖙 to return input type setting |

1 Scale = 2.8uA = 1.3mV for tuning output value

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PID Control

PEDP \sim **PEDP**: PIDn, n = 0 ~ 4, found in the regulation mode, four groups of user-defined PID settings and an auto tuning function are available. Each group contains a set value, proportional band, integral time, derivative time, and integral deviation settings (P, I, D, IOF) for PID control.

PCdH : n = 4, is the auto PID parameter. The controller will automatically select a most useful PID parameter

based on current temperature setting. Displayed SV values correspond to

508 503

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503 : is the temperature setting which corresponds to the selected PID parameter via user-defined or AT (auto-tuning).

After AT(auto-tuning) the values will be stored.

PID mode selection (regulation mode): any one of four PID modes (n=0~3) can be selected. When n=4, the unit will perform auto-tuning.

| Press ☞ ▷~3 groups PID | 5ມວີ PID setting: n=0.Press 🖙 🤱 | 5.3 PID setting: n=3.Press 📼 🦆 |
|------------------------|--|---|
| | Proportion band setting: n=0. Press ☞ ↓ | P3 Proportion band setting: n=3. Press |
| | 🚺 Ti setting: n=0. Press 📼 🦞 | 🚺 Ti setting: n=3. Press 📼 🦞 |
| | d🖁 Td setting: n=0.Press 🖙 🤱 | d 🗄 Td setting: n=3.Press 📼 🤱 |
| | CoFCIntegral deviation setting: n=0.AT setting.Press ♀↓back to PID deviation setting | CoF3Integral deviation setting: n=3.AT setting.Press☑ ↓ back to PID deviation setting |

Pattern and Set Editing (Ramp and Soak Programming)

Description of Function and Parameters Setting:

To set-up or edit the ramp/soak function. $\frac{c_{c}}{c_{c}}$ in the initial setting mode must be set to $\frac{\rho_{cob}}{\rho_{cob}}$. Will immediately follow in the menu list.

The Ramp and Soak function is supported by 8 different patterns (Pattern No. 0 ~ 7). Each pattern contains 8 steps (step No. 0 ~ 7) for set point and execution time, one Link Pattern parameter, one Cycle parameter and one Actual Step parameter.

The set point (SV) should reach temperature X after the execution time T. The default of step No. 0 is soak control. The unit will control the temperature (PV) to reach the set point X and then keep the temperature at set point X. The execution time T is determined by step No, 0.

The following display is an example of operation of pattern No. 0. Pheno PAtn where n = 0-7.

| PREn Select desired editing pattern number select OFF Press Image: Comparison of the select number | Edit temperature of step No. 0 of pattern No. 0 Press P | PSUS Select actual step No. when program control is executing Press Press |
|--|--|--|
| Exit pattern and step editing selection Switch to 5 - HC and continue setting | Edit time of step No. 0 of pattern No. 0, unit is hh.mm Press 🖙 🗘 | Set additional execution cycle number(0 to 99)PressImage: Constraint of the set of th |
| | Set step No.1-7 in order | Set link pattern, OFF indicates |
| | Edit temperature of step No. 7 of pattern No. 0 Press | Press a to return pattern No. editing mode |
| | Edit time of step No. 7 of pattern No. 0, unit is hh.mm Press < to set actual step No. | |

Actual Step Parameter P597: Offered for each pattern (0-7), the user can select to execute only certain steps in the pattern. For example, when **PSP** is set to 2, pattern No 7 will only execute steps 0 through 2.

Cycle Parameter Cycle Parameter will execute the selected pattern X amount of times. For example, when **EBEN** is set to 2, pattern No. 4 will cycle through the steps and then cycle through the steps 2 more times.

Link Pattern Parameter Configuration : Offered for each pattern (0-7), the link parameter designates the next pattern to execute. For example, when is set to 2, pattern No. 2 will execute next after the execution of pattern No. 0. If configuration is set to offered, the program will stop after executing the current pattern and the temperature will be maintained at the set point of the last step.

Execution :

| The execution of the ramp and soak function is initiated through $\frac{1}{5}$ in the operation mode. |
|--|
| When c=5 is set to cur, the program will start to execute in order from the step 0 of the start pattern. |
| When is set to 520P, the program will stop and the control output is disabled. |
| When is set to PSEP, the program will stop and the temperature will be maintained at the set point |
| before program was stopped. Select again, then the program will restart and execute from step 0 of start |
| pattern. The start pattern setting Pten is accessed when is set to P5tP and the INDEX key |
| is pressed. (The start pattern setting only appears in PSEP mode). |
| When is set to <i>Phod</i> , the program will hold and the temperature at that time will be controlled at the |
| set point before program hold. Select clin again, then the program will follow the step before hold and start to execute through the rest of the time. |
| Display : During ramp and soak program control, the SV default display is P-XX, P indicates the current |
| execution pattern and XX indicates the current execution step. Press 🛛 🗠 to change the SV display item to |
| set point value 5P or residual time ことこ. |
| After selecting, press 💭 key, and then the temperature set point of the current execution step will display on SV display. |
| After selecting , press key, and then the residual time of the current execution step will display on SV display. |
| |

Heating, Cooling or Dual Loop Output Control

Temperature control can be achieved either by heating or cooling. In the CN7500/CN7800 series, heating and cooling can be operated simultaneously (Dual Loop output control) to perform temperature control. When Dual Loop output control is used, two control outputs must be connected to the heating and cooling devices. Please refer to the following for the operation: Settings for heat, cool, or heat and cool are found in the initial

settings mode under

Select **HERE**, for heating (reverse) control on Output 1.

Select Cool, for cooling (forward) control on Output 1. By

selecting HERE or Cool the 2nd output group is regarded as an alarm output. For dual loop control, select

HIE2 or **CIN2**. When selecting **HIE2**, the 1st output group is heating (reverse) control and the 2nd output group is cooling





(forward) control. When selecting **C H2**, the 1st output group is cooling (forward) control and the 2nd output group is heating (reverse) control.

When dual loop control is selected

Only visible when dual loop output and PID control method is configured. The parameter sets the P value of the 2nd output based on the P value of the 1st output which is set in parameter PCdn. The P value of 2nd output group is

equal to (P value of 1st output group) x CoEF and the value of I and D of 2nd output group are the same as the value of I and D of 1st output group.

dERd Dead Band, shown in figures 1, 2 and 3. This parameter sets an area in which the heating and cooling control output is 0 centering around the set point in a Dual Loop output control mode.





LoC: Settings lock. To avoid incorrect operation, two key lock functions are provided.

lock all settings. All parameters and temperature settings can be locked to disable changes. can lock settings except the SV (Set point) value. All parameters and temperature settings can be locked with the

exception of the SV value. Press 🔁 and 🔄

key simultaneously, the "Lock" status can be released.

Auto-tuning parameter, automatically sets P (Proportional Band), I(Integral Time) and D(Derivative Time) parameters. Correct input must be connected to the unit for this parameter to be changed.

Alarm Outputs

Depending on the controller model, there can be up to three alarm outputs. Each alarm output can be configured for an alarm type listed below. Alarm types are set in the initial setting mode. The alarm output is activated whenever the process temperature value (PV) is getting higher or lower than the set point of alarm limit.

| Set Value | Alarm Type | Alarm Output Operation |
|-----------|---|-------------------------------------|
| 0 | Alarm function disabled | Output is OFF |
| 1 | Deviation upper- and lower-limit: This alarm output operates when PV value is higher than the setting value SV+(AL-H) or lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV SV+(AL-H) |
| 2 | Deviation upper-limit: This alarm output operates when PV value is higher than the setting value SV+(AL-H). | ON OFF SV SV+(AL-H) |
| 3 | Deviation lower-limit: This alarm output operates when PV value is lower than the setting value SV-(AL-L). | OFF SV-(AL-L) SV |
| 4 | Reverse deviation upper- and lower-limit: This alarm output operates when PV value is in the range of the setting value SV+(AL-H) and the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV SV+(AL-H) |
| 5 | Absolute value upper- and lower-limit: This alarm output operates when PV value is higher than the setting value AL-H or lower than the setting value AL-L. | OFF AL-L AL-H |

| 6 | Absolute value upper-limit: This alarm output operates when PV value is higher than the setting value AL-H. | ON OFF |
|----|--|-------------------------------------|
| 7 | Absolute value lower-limit: This alarm output operates when PV value is lower than the setting value AL-L. | OFF AL-L |
| 8 | Deviation upper- and lower-limit with standby sequence: This alarm output operates when PV value reaches set point (SV value) and the value is higher than the setting value SV+(AL-H) or lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV SV+(AL-H) |
| 9 | Deviation upper-limit with standby sequence: This alarm output operates when PV value reaches set point (SV value) and the reached value is higher than the setting value SV+(AL-H). | ON OFF SV SV+(AL-H) |
| 10 | Deviation lower-limit with standby sequence: This alarm output operates when PV value reaches the set point (SV value) and the reached value is lower than the setting value SV-(AL-L). | ON OFF SV-(AL-L) SV |
| 11 | Hysteresis upper-limit alarm output: This alarm output operates if PV value is higher than the setting value SV+(AL-H). This alarm output is OFF when PV value is lower than the setting value SV+(AL-L). | ON OFF AL-L AL-H |
| 12 | Hysteresis lower-limit alarm output: This alarm output operates if PV value is lower than the setting value SV-(AL-H). This alarm output is OFF when PV value is higher than the setting value SV-(AL-L). | OFF AL-H AL-L |
| 13 | CT alarm output: This alarm operates when the current measured by transformer (CT) is lower than AL-L or higher than AL-H (This alarm output is available only for the controller with current transformer). | OFF AL-L SV AL-H |
| 14 | When program control is end status, alarm output is ON. | |
| 15 | When RAMP UP status happens to PID program control, alarm output is ON. | |
| 16 | When RAMP DOWN status happens to PID program control, alarm output is ON. | |
| 17 | When SOAK status happens to PID program control, alarm output is ON. | |
| 18 | When RUN status happens to PID program control, alarm output is ON. | |

Note: AL-H and AL-L include AL1H, AL2H, AL3H and AL1L, AL2L, AL3L)

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Specifications

| Input Voltage | 100 to 240VAC 50/60Hz | |
|-------------------------|---|--|
| Operation Voltage Range | 85% to 110% of rated voltage | |
| Power Consumption | 5VA max. | |
| Memory Protection | EEPROM 4K bit (non-volatile memory (number of writes: 100,000) | |
| Display Method | 2 line x 4 character 7-segment LED display Process value (PV): Red color, Set point (SV): Green color | |

| | Thermocouple: K, J, T, E, N, R, S, B, L, U, TXK | | |
|----------------------|--|--|--|
| Sensor Type | 3-wire Platinum RTD: Pt100, JPt100 | | |
| | Analog input: 0~5V, 0~10V, 0~ 20 m A, 4 ~ 20 m A, 0 ~ 50mV | | |
| Control Mode | PID, ON/OFF, Manual or PID program control (Ramp/Soak control) | | |
| | Relay output: SPDT (SPST: 1/16 DIN and 1/32 DIN size), Max. load 250VAC, 5A resistive load | | |
| Control Output | Voltage pulse output: DC 14V, Max. output current 40mA | | |
| | Current output: DC 4 ~ 20m A output (Load resistance: Max. 600Ω) | | |
| | Linear voltage output: 0~10V *(B Series only) | | |
| Display Accuracy | 0 or 1 digit to the right of the decimal point (selectable) | | |
| Sampling Rate | Analog input: 150 msec/ per scan Thermocouple or Platinum RTD: 400 msec/per scan | | |
| RS-485 Communication | MODBUS ASCII / RTU communication protocol | | |
| Vibration Resistance | 10 to 55Hz, 10m/s ² for 10min, each in X, Y and Z directions | | |
| Shock Resistance | Max. 300m/ s ² , 3 times in each 3 axes, 6 directions | | |
| Ambient Temperature | 32°F to 122°F (0°C to + 50°C) | | |
| Storage Temperature | -4°F to 150°F (-20°C to + 65°C) | | |
| Altitude | 2000m or less | | |
| Relative Humidity | 35% to 80% (non-condensing) | | |

RS-485 Communication

- 1. Supporting transmission speed: 2,400, 4,800, 9,600, 19,200, 38,400bps
- 2. Non-supported formats: 7, N, 1 or 8, O, 2 or 8, E, 2
- 3. Communication protocol: Modbus (ASCII or RTU)
- 4. Function code: 03H to read the contents of register (Max. 8 words). 06H to write 1 (one) word into register. 02H to read the bits data (Max. 16 bits). 05H to write 1 (one) bit into register.
- 5. Address and Content of Data Register:

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| Address | Content | Explanation |
|---------|----------------------------------|--|
| | Process value (PV) | Measuring unit is 0.1, updated one time in 0.4 second |
| | | The following reading value display indicates error occurs: |
| | | 8002H: Initial process (Temperature value is not got yet) |
| 1000H | | 8003H: Temperature sensor is not connected |
| | | 8004H: Temperature sensor input error |
| | | 8006H: Cannot get temperature value, ADC input error |
| | | 8007H: Memory read/write error |
| 1001H | Set point (SV) | Unit is 0.1, °C or °F |
| 1002H | Upper-limit of temperature range | The data content should not be higher than the temperature range |
| 1003H | Lower-limit of temperature range | The data content should not be lower than the temperature range |
| 1004H | Input temperature sensor type | Please refer to the contents of the "Temperature Sensor Type and Temperature Range" for detail |
| 1005H | Control method | 0: PID, 1: ON/OFF, 2: manual tuning, 3: PID grogram control |

| Address | Content | Explanation |
|---------|---|---|
| 1006H | Heating/Cooling control selection | 0: Heating, 1: Cooling, 2: Heating/Cooling, 3: Cooling/Heating |
| 1007H | 1st group of Heating/Cooling control cycle | 0~99, 0:0.5 sec |
| 1008H | 2nd group of Heating/Cooling control cycle | 0~99, 0:0.5 sec |
| 1009H | PB Proportional band | 0.1 ~ 999.9 |
| 100AH | Ti Integral time | 0 ~ 9,999 |
| 100BH | Td Derivative time | 0 ~ 9,999 |
| 100CH | Integration default | 0 ~ 100%, unit is 0.1% |
| 100DH | Proportional control offset error value, when Ti = 0 | 0 ~ 100%, unit is 0.1% |
| 100EH | The setting of COEF when Dual Loop output control are used | 0.01 ~ 99.99 |
| 100FH | The setting of Dead band when Dual Loop output control are used | -999 ~ 9,999 |
| 1010H | Hysteresis setting value of the 1st output group | 0 ~ 9,999 |
| 1011H | Hysteresis setting value of the 2nd output group | 0 ~ 9,999 |
| 1012H | Output value read and write of Output 1 | Unit is 0.1%, write operation is valid under manual tuning mode only. |
| 1013H | Output value read and write of Output 2 | Unit is 0.1%, write operation is valid under manual tuning mode only. |
| 1014H | Upper-limit regulation of analog linear output | 1 Unit = 2.8uA (Current Output) = 1.3mV (Linear Voltage Output) |
| 1015H | Lower-limit regulation of analog linear output | 1 Unit = 2.8uA (Current Output) = 1.3mV (Linear Voltage Output) |
| 1016H | Temperature regulation value | -999 ~ +999, unit: 0.1 |
| 1017H | Analog decimal setting | 0~3 |
| 101CH | PID parameter selection | |
| 101DH | SV value corresponded to PID value | Only valid within available range, unit: 0.1 scale |
| 1020H | Alarm 1 type | Please refer to the contents of the "Alarm Outputs" for detail |
| 1021H | Alarm 2 type | Please refer to the contents of the "Alarm Outputs" for detail |
| 1022H | Alarm 3 type | Please refer to the contents of the "Alarm Outputs" for detail |
| 1023H | System alarm setting | 0: None (default), 1 ~ 3: Set Alarm 1 to Alarm 3 |
| 1024H | Upper-limit alarm 1 | Please refer to the contents of the "Alarm Outputs" for detail |
| 1025H | Lower-limit alarm 1 | Please refer to the contents of the "Alarm Outputs" for detail |
| 1026H | Upper-limit alarm 2 | Please refer to the contents of the "Alarm Outputs" for detail |
| 1027H | Lower-limit alarm 2 | Please refer to the contents of the "Alarm Outputs" for detail |
| 1028H | Upper-limit alarm 3 | Please refer to the contents of the "Alarm Outputs" for detail |

| Address | Content | Explanation | | | |
|--|---|--|--|--|--|
| 1029H | Lower-limit alarm 3 | Please refer to the contents of the "Alarm Outputs" for detail | | | |
| 102AH | Read LED status | b0: Alm3, b1: Alm2, b2: F, b3:°C, b4: Alm1, b5: OUT2, b6: OUT1, b7: AT | | | |
| 102BH | Read pushbutton status | b0: Set, b1: Select, b2: Up, b3: Down. 0 is to push | | | |
| 102CH | Setting lock status | 0: Normal, 1: All setting lock, 11: Lock others than SV value | | | |
| 102FH | Software version | V1.00 indicates 0x100 | | | |
| 1030H | Start pattern number | 0 ~ 7 | | | |
| 1040H~ 1047H | Actual step number setting inside the correspond pattern | 0 ~ 7 = N, indicate that this pattern is executed from step 0 to step N | | | |
| 1050H~ 1057H | Cycle number for repeating the execution of the correspond pattern | 0 ~ 99 indicate that this pattern has been executed for 1 ~ 100 times | | | |
| 1060H~ 1067H | Link pattern number setting of the correspond pattern | $0 \sim 8$, 8 indicates the program end. $0 \sim 7$ indicates the next execution pattern number after executing the current pattern | | | |
| 2000H~ 203FH | Pattern 0~7 temperature set point setting Pattern 0 temperature is set to 2000H~2007H | -999 ~ 9,999 | | | |
| 2080H~ 20BFH | Pattern 0~7 execution time setting Pattern 0 time is set to 2080H~2087H | Time 0 ~ 900 (1 minute per scale) | | | |
| Address and Content of Bit Register: (First bit of reading will put into LSB, Write data = FF00H for bit set, 0000H for bit clear) | | | | | |
| 0810H | Communication write-in selection | Communication write in disabled: 0 (default), Communication write in enabled: 1 | | | |
| 0811H | Temperature unit display selection | °C/linear input (default): 1 , °F : 0 | | | |
| 0812H | Decimal point position selection | Except for the thermocouple B, S, R type, all the other thermocouple type are valid. (0 or 1) | | | |
| 0813H | AT setting | OFF: 0 (default), ON: 1 | | | |
| 0814H | Control RUN/STOP setting | 0: STOP, 1: RUN (default) | | | |
| 0815H | STOP setting for PID program control | 0: RUN (default), 1: STOP | | | |

0816H Temporarily STOP for PID program control 0: RUN (default), 1: Temporarily STOP

7. Communication Transmission Format : Command Code: 02: read N bits, 05: write 1 bits, 03: read N words, 06: write 1 words



External Dimensions

Dimensions are in millimeter (inch)



CN7800



Mounting

Mounting Method

Step 1: Insert the controller through the panel cutout.

- Step 2: Insert the mounting bracket into the mounting groove at the top and bottom of the controller
- Step 3: Push the mounting bracket forward until the bracket stops at panel wall.
- Step 4: Insert and tighten screws on bracket to secure the controller in place. (The screw torque should be 0.8kgf-cm to 1.5kgf-cm)

CN7500 Mounting Method:



CN7800 Mounting Method:



Mounting Bracket Installation





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Error Acknowledgement and Display

Communication error code response description:

| Error Status 102EH / 4750H | PV read back 1000H / 4700H | Error status |
|----------------------------|----------------------------|---|
| 0001H | M/A | PV unstable |
| 0002H | 8002H | Re-initial, no temperature at this time |
| 0003H | 8003H | Input sensor did not connect |
| 0004H | 8004H | Input signal error |
| 0005H | N/A | Over input range |
| 0006H | 8006H | ADC fail |
| 0007H | N/A | EEPROM read/write error |

Display message:

| | Power ON | | Normal display | | |
|-----------------------|----------|--------------------------------------|------------------|--------------------|--|
| PV | 8 ISO | CN7500/CN7800 series, Firmware V1.50 | 5000 | Present value | |
| SV | ur E | Output VR type with Event option | 88 | Set value | |
| Sensor didn't connect | | | Input error | | |
| PV | no | No | Err | Error | |
| SV | Cont | Connect | CnPt | Input | |
| EEPROM error | | | Input over range | | |
| PV | Err | Error | 1 005 | PV flash when over | |
| SV | Proñ | EEPROM | 88 | | |

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How to Set Up Current Input

For normal input

For current input (4 ~ 20mA, 0 ~ 20mA)



M-4437/02