

# User's Guide



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## **OME-A822PG ISA-BUS Multi-Functional Board Windows 2000 Software Manual**



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**WARNING:** These products are not designed for use in, and should not be used for, patient-connected applications.

# OME-A-822PGL/H

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## Software Manual [For Windows 2000]

Table of Contents

<b>1. DECLARATION FILES.....</b>	<b>4</b>
1.1 A822.H .....	5
1.2 A822.BAS .....	10
1.3 A822.PAS.....	16
<b>2. REFERENCE .....</b>	<b>24</b>
2.1 RANGE CONFIGURATION CODE .....	24
2.2 ERROR CODE .....	25
2.3 OTHER MANUALS .....	27
<b>3. FUNCTION DESCRIPTION .....</b>	<b>28</b>
3.1 TEST FUNCTION.....	30
3.1.1 A822_SHORT_SUB_2 .....	30
3.1.2 A822_FLOAT_SUB_2 .....	30
3.1.3 A822_Get_DLL_Version .....	31
3.1.4 A822_GetDriverVersion.....	31
3.2 DI/DO FUNCTION .....	32
3.2.1 A822_DI .....	32
3.2.2 A822_DO.....	32
3.2.3 A822_OutputByte.....	33
3.2.4 A822_OutputWord.....	33
3.2.5 A822_InputByte.....	34
3.2.6 A822_InputWord .....	34
3.3 A/D, D/A FUNCTION.....	35
3.3.1 A822_SetChGain .....	35
3.3.2 A822_Fast_AD_Hex.....	36
3.3.3 A822_Fast_AD_Float.....	36
3.3.4 A822_AD_Hex.....	37
3.3.5 A822_AD_Float.....	37
3.3.6 A822_ADs_Hex .....	38
3.3.7 A822_ADs_Float .....	39
3.3.8 A822_DA_Hex.....	40
3.3.9 A822_DA_Uni5 .....	40
3.3.10 A822_DA_Uni10 .....	41
3.4 DRIVER FUNCTION .....	42
3.4.1 A822_DriverInit.....	42
3.4.2 A822_DriverClose.....	42
3.4.3 A822_SetTriggerMode.....	43
3.4.4 A822_DELAY.....	44
3.4.5 A822_Check_Address.....	44
3.4.6 A822_GetConfigAddress .....	45
3.4.7 A822_ActiveBoard.....	45
3.4.8 A822_SetCounter.....	46
3.4.9 A822_ReadCounter .....	46
3.5 AD, INTERRUPT FUNCTION.....	47
3.5.1 A822_Int_Install.....	47
3.5.2 A822_Int_Start.....	47
3.5.3 A822_Int_Stop .....	48
3.5.4 A822_Int_Remove.....	48
3.5.5 A822_Int_GetCount.....	48
3.5.6 A822_Int_GetHexBuf.....	49

- 3.5.7 *A822\_Int\_GetFloatBuf*..... 49
- 3.5.8 *Architecture of Interrupt mode* ..... 50
- 3.6 AD, CHANNEL SCAN FUNCTION ..... 51
  - 3.6.1 *Introduction* ..... 51
  - 3.6.2 *A822\_ChScan\_Clear* ..... 52
  - 3.6.3 *A822\_ChScan\_Add*..... 52
  - 3.6.4 *A822\_ChScan\_PollingHex*..... 53
  - 3.6.5 *A822\_ChScan\_PollingFloat*..... 54
- 3.7 AD INTERRUPT, CHANNEL SCAN FUNCTION..... 55
  - 3.7.1 *Introduction*..... 55
  - 3.7.2 *A822\_ChScan\_IntInstall*..... 57
  - 3.7.3 *A822\_ChScan\_IntStart*..... 57
  - 3.7.4 *A822\_ChScan\_IntStop*..... 58
  - 3.7.5 *A822\_ChScan\_IntRemove* ..... 58
  - 3.7.6 *A822\_ChScan\_IntGetCount* ..... 58
  - 3.7.7 *A822\_ChScan\_IntGetHexBuf*..... 59
  - 3.7.8 *A822\_ChScan\_IntGetFloatBuf*..... 59
- 4. PROGRAM ARCHITECTURE..... 60**
- 5. REPORT PROBLEMS ..... 61**

# 1. DECLARATION FILES

Please refer to user manual "[CalIDLL.pdf](#)".

For Windows 2000:

```
|--\Driver
|   |--\A822.DLL    ← Dynamic Linking Library
|   |--\A822.sys   ← device driver
|   |--\Napwnt.sys ← device driver
|   |
|   |--\BCB        ← For Borland C++ Builder
|   |   |--\A822.H ← Header file
|   |   |--\A822.Lib ← Import Library for BCB only
|   |
|   |--\Delphi     ← For Delphi
|   |   |--\A822.pas ← Declaration file
|   |
|   |--\VB         ← For Visual Basic
|   |   |--\A822.bas ← Declaration file
|   |
|   |--\VC        ← For Visual C++
|   |   |--\A822.H  ← Header file
|   |   |--\A822.Lib ← Import Library for VC only
```

## 1.1 A822.H

```

#ifdef __cplusplus
    #define EXPORTS extern "C" __declspec (dllimport)
#else
    #define EXPORTS
#endif

/***** DEFINE A822 RELATIVE ADDRESS *****/
#define A822_TIMER0      0x00
#define A822_TIMER1      0x01
#define A822_TIMER2      0x02
#define A822_TIMER_MODE  0x03
#define A822_AD_LO        0x04 /* Analog to Digital, Low Byte */
#define A822_AD_HI        0x05 /* Analog to Digital, High Byte */
#define A822_DA_CH0_LO    0x04 /* Digit to Analog, CH 0 */
#define A822_DA_CH0_HI    0x05
#define A822_DA_CH1_LO    0x06 /* Digit to Analog, CH 1 */
#define A822_DA_CH1_HI    0x07
#define A822_DI_LO        0x06 /* Digit Input */
#define A822_DO_LO        0x0D /* Digit Output */

#define A822_CLEAR_IRQ    0x08
#define A822_SET_GAIN     0x09
#define A822_SET_CH       0x0A
#define A822_SET_MODE     0x0B
#define A822_SOFT_TRIG    0x0C

#define A822_POLLING_MODE 1
#define A822_DMA_MODE     2
#define A822_INTERRUPT_MODE 6
    
```

```
/** define the gain mode **/  
#define A822_BI_1 0  
#define A822_BI_10 1  
#define A822_BI_100 2  
#define A822_BI_1000 3  
#define A822_UNI_1 4  
#define A822_UNI_10 5  
#define A822_UNI_100 6  
#define A822_UNI_1000 7  
#define A822_BI_05 8  
#define A822_BI_5 9  
#define A822_BI_50 10  
#define A822_BI_500 11  
  
#define A822_BI_2 1  
#define A822_BI_4 2  
#define A822_BI_8 3  
#define A822_UNI_2 5  
#define A822_UNI_4 6  
#define A822_UNI_8 7  
  
#define A822PGL 0  
#define A822PGH 1
```



```

#define A822_NoError 0
#define A822_DriverOpenError 1
#define A822_DriverNoOpen 2
#define A822_GetDriverVersionError 3
#define A822_InstallIrqError 4
#define A822_ClearIntCountError 5
#define A822_GetIntCountError 6
#define A822_GetBufferError 7
#define A822_InstallBufError 10
#define A822_AllocateMemoryError 11
#define A822_CardTypeError 12
#define A822_TimeoutError 13
#define A822_OtherError 14
#define A822_ExceedBoardNumber 15
#define A822_CardNotFound 16
#define A822_GetTotalBoardError 17
#define A822_ChannelNoError 18
#define A822_IntStopError 19
#define A822_IntInstallEventError 20
#define A822_GetConfigError 21
#define A822_ActiveBoardError 22
#define A822_ConfigCodeError 23
#define A822_BufferFull 24
#define A822_NoChannelToScan 25
#define A822_IntInstallChannelError 26
#define A822_IntInstallConfigError 27

```

// Functions of Test

```

EXPORTS short CALLBACK A822_SHORT_SUB_2(short nA, short nB);
EXPORTS float CALLBACK A822_FLOAT_SUB_2(float fA, float fB);
EXPORTS WORD CALLBACK A822_Get_DLL_Version(void);
EXPORTS WORD CALLBACK A822_GetDriverVersion(WORD
*wDriverVersion);

```

// Functions of DI/DO

```

EXPORTS WORD CALLBACK A822_DI(WORD *wInVal);
EXPORTS WORD CALLBACK A822_DO(WORD wHexValue);

```

```

// Functions of AD/DA
EXPORTS WORD CALLBACK A822_SetChGain
    (WORD wChannel, WORD wConfig, WORD wCardType);
EXPORTS WORD CALLBACK A822_Fast_AD_Hex(WORD *wVal);
EXPORTS WORD CALLBACK A822_Fast_AD_Float(float *fVal);
EXPORTS WORD CALLBACK A822_AD_Hex
    (WORD wChannel, WORD wConfig, WORD wCardType, WORD *wVal);
EXPORTS WORD CALLBACK A822_AD_Float
    (WORD wChannel, WORD wConfig, WORD wCardType, float *fVal);
EXPORTS WORD CALLBACK A822_ADs_Hex( WORD wBuf[], WORD
wCount );
EXPORTS WORD CALLBACK A822_ADs_Float( float fBuf[], WORD wCount );
EXPORTS WORD CALLBACK A822_Hex2Float
    (WORD wConfig, WORD wCardType, WORD wHex, float *fVal);

EXPORTS WORD CALLBACK A822_DA_Hex(WORD wChannel, WORD
wHexValue);
EXPORTS WORD CALLBACK A822_DA_Uni5(WORD wChannel, float fValue);
EXPORTS WORD CALLBACK A822_DA_Uni10(WORD wChannel, float fValue);

// Functions of Driver
EXPORTS WORD CALLBACK A822_DriverInit(WORD *wTotalBoards);
EXPORTS void CALLBACK A822_DriverClose(void);
EXPORTS WORD CALLBACK A822_DELAY(WORD wDownCount);
EXPORTS WORD CALLBACK A822_Check_Address(void);
EXPORTS WORD CALLBACK A822_GetConfigAddress
    (WORD *wAddrBase, WORD *wCurrentBoard);
EXPORTS WORD CALLBACK A822_ActiveBoard( WORD wBoardNo );
EXPORTS void CALLBACK A822_SetTriggerMode(WORD wTriggerMode );

EXPORTS void CALLBACK A822_OutputByte
    (WORD wPortAddr, UCHAR bOutputVal);
EXPORTS void CALLBACK A822_OutputWord
    (WORD wPortAddr, WORD wOutputVal);
EXPORTS WORD CALLBACK A822_InputByte(WORD wPortAddr);
EXPORTS WORD CALLBACK A822_InputWord(WORD wPortAddr);

```

```
// Functions of Interrupt
EXPORTS WORD CALLBACK A822_Int_Install
    (HANDLE *hEvent, DWORD dwCount);
EXPORTS WORD CALLBACK A822_Int_Start(WORD c1, WORD c2);
EXPORTS WORD CALLBACK A822_Int_Stop(void);
EXPORTS WORD CALLBACK A822_Int_Remove(void);
EXPORTS WORD CALLBACK A822_Int_GetCount(DWORD *dwVal);
EXPORTS WORD CALLBACK A822_Int_GetHexBuf
    (WORD wBuf[], DWORD dwNum );
EXPORTS WORD CALLBACK A822_Int_GetFloatBuf
    (float fBuf[], DWORD dwNum );

// Functions of Channel Scan
EXPORTS void CALLBACK A822_ChScan_Clear(void);
EXPORTS WORD CALLBACK A822_ChScan_Add
    (WORD wChannel, WORD wConfig);
EXPORTS WORD CALLBACK A822_ChScan_PollingHex
    (WORD wCardType, WORD wBuf[], WORD wNumPerCh);
EXPORTS WORD CALLBACK A822_ChScan_PollingFloat
    (WORD wCardType, float fBuf[], WORD wNumPerCh);

// Functions of Channel Scan for Interrupt Only
EXPORTS WORD CALLBACK A822_ChScan_IntInstall
    (HANDLE *hEvent, DWORD dwNumPerCh);
EXPORTS WORD CALLBACK A822_ChScan_IntStart
    (WORD c1, WORD c2, WORD wCardType);
EXPORTS WORD CALLBACK A822_ChScan_IntGetCount(DWORD *dwVal);
EXPORTS WORD CALLBACK A822_ChScan_IntGetHexBuf(WORD wBuf[]);
EXPORTS WORD CALLBACK A822_ChScan_IntGetFloatBuf(float fBuf[]);
EXPORTS WORD CALLBACK A822_ChScan_IntStop(void);
EXPORTS WORD CALLBACK A822_ChScan_IntRemove(void);
```

## 1.2 A822.BAS

Attribute VB\_Name = "A822"

\*\*\*\*\*

' The Declare of A822.DLL for A822 DAQ Card

\*\*\*\*\*

Declare Sub Sleep Lib "kernel32" (ByVal dwMilliseconds As Long)

\*\*\*\*\* DEFINE A822 RELATIVE ADDRESS \*\*\*\*\*/

```
Global Const A822_TIMER0      = &H0
Global Const A822_Timer1     = &H1
Global Const A822_TIMER2     = &H2
Global Const A822_TIMER_MODE = &H3
Global Const A822_AD_LO      = &H4      '* Analog to Digital, Low Byte */
Global Const A822_AD_HI      = &H5      '* Analog to Digital, High Byte */
Global Const A822_DA_CH0_LO = &H4      '* Digit to Analog, CH 0 */
Global Const A822_DA_CH0_HI = &H5
Global Const A822_DA_CH1_LO = &H6      '* Digit to Analog, CH 1 */
Global Const A822_DA_CH1_HI = &H7
Global Const A822_DI_LO      = &H6      '* Digit Input */
Global Const A822_DO_LO      = &HD      '* Digit Output */

Global Const A822_CLEAR_IRQ = &H8
Global Const A822_SET_GAIN  = &H9
Global Const A822_SET_CH    = &HA
Global Const A822_SET_MODE  = &HB
Global Const A822_SOFT_TRIG = &HC

Global Const A822_POLLING_MODE = 1
Global Const A822_DMA_MODE     = 2
Global Const A822_INTERRUPT_MODE = 6
```

```
*** define the gain mode ***/  
Global Const A822_BI_1      = 0  
Global Const A822_BI_10     = 1  
Global Const A822_BI_100    = 2  
Global Const A822_BI_1000   = 3  
Global Const A822_UNI_1     = 4  
Global Const A822_UNI_10    = 5  
Global Const A822_UNI_100   = 6  
Global Const A822_UNI_1000  = 7  
Global Const A822_BI_05     = 8  
Global Const A822_BI_5      = 9  
Global Const A822_BI_50     = 10  
Global Const A822_BI_500    = 11  
  
Global Const A822_BI_2      = 1  
Global Const A822_BI_4      = 2  
Global Const A822_BI_8      = 3  
Global Const A822_UNI_2     = 5  
Global Const A822_UNI_4     = 6  
Global Const A822_UNI_8     = 7  
  
Global Const A822PGL        = 0  
Global Const A822PGH        = 1
```

Global Const A822\_NoError = 0  
 Global Const A822\_DriverOpenError = 1  
 Global Const A822\_DriverNoOpen = 2  
 Global Const A822\_GetDriverVersionError = 3  
 Global Const A822\_InstallIrqError = 4  
 Global Const A822\_ClearIntCountError = 5  
 Global Const A822\_GetIntCountError = 6  
 Global Const A822\_GetBufferError = 7  
 Global Const A822\_InstallBufError = 10  
 Global Const A822\_AllocateMemoryError = 11  
 Global Const A822\_CardTypeError = 12  
 Global Const A822\_TimeoutError = 13  
 Global Const A822\_OtherError = 14  
 Global Const A822\_ExceedBoardNumber = 15  
 Global Const A822\_CardNotFound = 16  
 Global Const A822\_GetTotalBoardError = 17  
 Global Const A822\_ChannelNoError = 18  
 Global Const A822\_IntStopError = 19  
 Global Const A822\_IntInstallEventError = 20  
 Global Const A822\_GetConfigError = 21  
 Global Const A822\_ActiveBoardError = 22  
 Global Const A822\_ConfigCodeError = 23  
 Global Const A822\_BufferFull = 24  
 Global Const A822\_NoChannelToScan = 25  
 Global Const A822\_IntInstallChannelError = 26  
 Global Const A822\_IntInstallConfigError = 27

\*\*\*\*\* Test Functions \*\*\*\*\*

Declare Function A822\_SHORT\_SUB\_2 Lib "A822.DLL" \_  
 (ByVal nA As Integer, ByVal nB As Integer) As Integer  
 Declare Function A822\_FLOAT\_SUB\_2 Lib "A822.DLL" \_  
 (ByVal fA As Single, ByVal fB As Single) As Single  
 Declare Function A822\_Get\_DLL\_Version Lib "A822.DLL" () As Integer  
 Declare Function A822\_GetDriverVersion Lib "A822.DLL" \_  
 (wDriverVersion As Integer) As Integer

\*\*\*\*\* DI/DO Functions \*\*\*\*\*

Declare Function A822\_DI Lib "A822.DLL" \_  
 (wInVal As Integer) As Integer  
 Declare Function A822\_DO Lib "A822.DLL" \_  
 (ByVal wHexValue As Integer) As Integer

\*\*\*\*\* AD/DA Functions \*\*\*\*\*

```
Declare Function A822_SetChGain Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal wConfig As Integer, _
    ByVal wCardType As Integer) As Integer
Declare Function A822_Fast_AD_Hex Lib "A822.DLL" _
    (wVal As Integer) As Integer
Declare Function A822_Fast_AD_Float Lib "A822.DLL" _
    (fVal As Single) As Integer
Declare Function A822_AD_Hex Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal wConfig As Integer, _
    ByVal wCardType As Integer, wVal As Integer) As Integer
Declare Function A822_AD_Float Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal wConfig As Integer, _
    ByVal wCardType As Integer, fVal As Single) As Integer
Declare Function A822_ADs_Hex Lib "A822.DLL" _
    (wBuf As Integer, ByVal wCount As Integer) As Integer
Declare Function A822_ADs_Float Lib "A822.DLL" _
    (fbuf As Single, ByVal wCount As Integer) As Integer
Declare Function A822_Hex2Float Lib "A822.DLL" _
    (ByVal wConfig As Integer, ByVal wCardType As Integer, _
    ByVal wVal As Integer, fVal As Single) As Integer

Declare Function A822_DA_Hex Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal wHexValue As Integer) As Integer
Declare Function A822_DA_Uni5 Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal fValue As Single) As Integer
Declare Function A822_DA_Uni10 Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal fValue As Single) As Integer
```

\*\*\*\*\* Driver Functions \*\*\*\*\*

```
Declare Function A822_DriverInit Lib "A822.DLL" _
    (wTotalBoards As Integer) As Integer
Declare Sub A822_DriverClose Lib "A822.DLL" ()
Declare Function A822_DELAY Lib "A822.DLL" _
    (ByVal wDownCount As Integer) As Integer
Declare Function A822_Check_Address Lib "A822.DLL" () As Integer
Declare Function A822_GetConfigAddress Lib "A822.DLL" _
    (wAddrBase As Integer, wCurrentBoard As Integer) As Integer
Declare Function A822_ActiveBoard Lib "A822.DLL" _
    (ByVal wBoardNo As Integer) As Integer
```

```

Declare Sub A822_OutputByte Lib "A822.DLL" _
    (ByVal wPortAddr As Integer, ByVal bOutputVal As Byte)
Declare Sub A822_OutputWord Lib "A822.DLL" _
    (ByVal wPortAddr As Integer, ByVal wOutputVal As Integer)
Declare Function A822_InputByte Lib "A822.DLL" _
    (ByVal wPortAddr As Integer) As Integer
Declare Function A822_InputWord Lib "A822.DLL" _
    (ByVal wPortAddr As Integer) As Integer

```

\*\*\*\*\* IRQ Functions \*\*\*\*\*

```

Declare Sub A822_SetTriggerMode Lib "A822.DLL" _
    (ByVal wTriggerMode As Integer)
Declare Function A822_Int_Install Lib "A822.DLL" _
    (hEvent As Long, ByVal dwCount As Integer) As Integer
Declare Function A822_Int_Start Lib "A822.DLL" _
    (ByVal c1 As Integer, ByVal c2 As Integer) As Integer
Declare Function A822_Int_Stop Lib "A822.DLL" () As Integer
Declare Function A822_Int_Remove Lib "A822.DLL" () As Integer
Declare Function A822_Int_GetCount Lib "A822.DLL" _
    (dwVal As Long) As Integer
Declare Function A822_Int_GetHexBuf Lib "A822.DLL" _
    (wBuffer As Integer, ByVal dwNum As Long) As Integer
Declare Function A822_Int_GetFloatBuf Lib "A822.DLL" _
    (fbuffer As Single, ByVal dwNum As Integer) As Integer

```

' Functions of Channel Scan

```

Declare Sub A822_ChScan_Clear Lib "A822.DLL" ()
Declare Function A822_ChScan_Add Lib "A822.DLL" _
    (ByVal wChannel As Integer, ByVal wConfig As Integer) _
    As Integer
Declare Function A822_ChScan_PollingHex Lib "A822.DLL" _
    (ByVal wCardType As Integer, wBuf as Integer, _
    ByVal wNumPerCh As Integer) As Integer
Declare Function A822_ChScan_PollingFloat Lib "A822.DLL" _
    (ByVal wCardType As Integer, fBuf as Single, _
    ByVal wNumPerCh As Integer) As Integer

```



```
' Functions of Channel Scan for Interrupt Only
Declare Function A822_ChScan_IntInstall Lib "A822.DLL" _
    (hEvent As Long, ByVal dwNumPerCh as Long) As Integer
Declare Function A822_ChScan_IntStart Lib "A822.DLL" _
    (ByVal c1 As Integer, ByVal c2 As Integer, _
    ByVal wCardType As Integer) As Integer
Declare Function A822_ChScan_IntGetCount Lib "A822.DLL" _
    (dwVal As Long) As Integer
Declare Function A822_ChScan_IntGetHexBuf Lib "A822.DLL" _
    (wBuf As Integer) As Integer
Declare Function A822_ChScan_IntGetFloatBuf Lib "A822.DLL" _
    (fBuf As Single) As Integer
Declare Function A822_ChScan_IntStop Lib "A822.DLL" () As Integer
Declare Function A822_ChScan_IntRemove Lib "A822.DLL" () As Integer
```

## 1.3 A822.PAS

unit A822;

interface

type PSingle=^Single;  
 PWord=^Word;  
 PInteger=^Integer;

Const

```
//***** DEFINE A822 RELATIVE ADDRESS *****/
A822_TIMER0           = $00;
A822_TIMER1           = $01;
A822_TIMER2           = $02;
A822_TIMER_MODE       = $03;
A822_AD_LO             = $04;  /* Analog to Digital, Low Byte */
A822_AD_HI             = $05;  /* Analog to Digital, High Byte */
A822_DA_CH0_LO        = $04;  /* Digit to Analog, CH 0 */
A822_DA_CH0_HI        = $05;
A822_DA_CH1_LO        = $06;  /* Digit to Analog, CH 1 */
A822_DA_CH1_HI        = $07;
A822_DI_LO             = $06;  /* Digit Input */
A822_DO_LO             = $0D;  /* Digit Output */

A822_CLEAR_IRQ        = $08;
A822_SET_GAIN         = $09;
A822_SET_CH           = $0A;
A822_SET_MODE         = $0B;
A822_SOFT_TRIG        = $0C;

A822_POLLING_MODE     = 1;
A822_DMA_MODE         = 2;
A822_INTERRUPT_MODE   = 6;
```

```
/** define the gain mode */
A822_BI_1      = 0;
A822_BI_10     = 1;
A822_BI_100    = 2;
A822_BI_1000   = 3;
A822_UNI_1     = 4;
A822_UNI_10    = 5;
A822_UNI_100   = 6;
A822_UNI_1000  = 7;
A822_BI_05     = 8;
A822_BI_5      = 9;
A822_BI_50     = 10;
A822_BI_500    = 11;

A822_BI_2      = 1;
A822_BI_4      = 2;
A822_BI_8      = 3;
A822_UNI_2     = 5;
A822_UNI_4     = 6;
A822_UNI_8     = 7;

A822PGL        = 0;
A822PGH        = 1;
```

A822\_NoError = 0;  
A822\_DriverOpenError = 1;  
A822\_DriverNoOpen = 2;  
A822\_GetDriverVersionError = 3;  
A822\_InstallIrqError = 4;  
A822\_ClearIntCountError = 5;  
A822\_GetIntCountError = 6;  
A822\_GetBufferError = 7;  
A822\_InstallBufError = 10;  
A822\_AllocateMemoryError = 11;  
A822\_CardTypeError = 12;  
A822\_TimeoutError = 13;  
A822\_OtherError = 14;  
A822\_ExceedBoardNumber = 15;  
A822\_CardNotFound = 16;  
A822\_GetTotalBoardError = 17;  
A822\_ChannelNoError = 18;  
A822\_IntStopError = 19;  
A822\_IntInstallEventError = 20;  
A822\_GetConfigError = 21;  
A822\_ActiveBoardError = 22;  
A822\_ConfigCodeError = 23;  
A822\_BufferFull = 24;  
A822\_NoChannelToScan = 25;  
A822\_IntInstallChannelError = 26;  
A822\_IntInstallConfigError = 27;

// Function of Test

Function A822\_SHORT\_SUB\_2(nA, nB : SmallInt):SmallInt; StdCall;  
Function A822\_FLOAT\_SUB\_2(fA, fB : Single):Single; StdCall;  
Function A822\_Get\_DLL\_Version:WORD; StdCall;  
Function A822\_GetDriverVersion(var wDriverVersion:WORD):Word; StdCall;

// Function of DI/DO

Function A822\_DO(wHexValue:Word):Word; StdCall;  
Function A822\_DI(var wInVal:Word):Word; StdCall;

// Function of AD/DA

```
Function A822_SetChGain(wChannel,wConfig,wCardType:WORD):Word;
StdCall;
Function A822_Fast_AD_Hex(var wVal:WORD):Word; StdCall;
Function A822_Fast_AD_Float(var fVal:Single):Word; StdCall;
Function A822_AD_Hex
    (wChannel,wConfig,wCardType:WORD; var wVal:Word):Word; StdCall;
Function A822_AD_Float
    (wChannel,wConfig,wCardType:WORD; var fVal:Single):Word; StdCall;
Function A822_ADs_Hex( wBuf:PWord; wCount:WORD):WORD; StdCall;
Function A822_ADs_Float(fBuf:PSingle; wCount:WORD):WORD; StdCall;
Function A822_Hex2Float
    ( wConfig, wCardType:Word; wVal:Word; var fVal:Single ):WORD; StdCall;
```

```
Function A822_DA_Hex(wChannel, wHexValue:WORD):WORD; StdCall;
Function A822_DA_Uni5(wChannel:Word;fValue:Single):WORD; StdCall;
Function A822_DA_Uni10(wChannel:Word;fValue:Single):WORD; StdCall;
```

// Function of Driver

```
Function A822_DriverInit(var wTotalBoards:WORD):WORD; StdCall;
Procedure A822_DriverClose; StdCall;
Function A822_DELAY(wDownCount:WORD):WORD; StdCall;
Function A822_Check_Address:WORD; StdCall;
Function A822_GetConfigAddress
    (var wAddrBase:WORD; var wCurrentBoard:WORD):WORD; StdCall;
Function A822_ActiveBoard(wBoardNo:WORD):WORD; StdCall;
```

```
Procedure A822_OutputByte(wPortAddr:WORD; bOutputVal:Byte); StdCall;
Procedure A822_OutputWord(wPortAddr:WORD; wOutputVal:WORD); StdCall;
Function A822_InputByte(wPortAddr:WORD):WORD; StdCall;
Function A822_InputWord(wPortAddr:WORD):WORD; StdCall;
```

// Function of Interrupt

```
Procedure A822_SetTriggerMode( wTriggerMode:WORD ); StdCall;
Function A822_Int_Install(var hEvent:LongInt; dwCount:LongInt):WORD; StdCall;
Function A822_Int_Start(c1,c2:WORD):WORD; StdCall;
Function A822_Int_Stop:WORD; StdCall;
Function A822_Int_Remove:WORD; StdCall;
Function A822_Int_GetCount(var dwVal:LongInt):WORD; StdCall;
Function A822_Int_GetHexBuf(wBuf:PWORD; dwNum:LongInt):WORD; StdCall;
Function A822_Int_GetFloatBuf(fBuf:PSingle; dwNum:LongInt):WORD; StdCall;
```

```
// Functions of Channel Scan
Procedure A822_ChScan_Clear; StdCall;
Function A822_ChScan_Add
    (wChannel:WORD; wConfig:WORD):WORD; StdCall;
Function A822_ChScan_PollingHex
    (wCardType:WORD; wBuf:PWORD; wNumPerCh:WORD):WORD; StdCall;
Function A822_ChScan_PollingFloat
    (wCardType:WORD; fBuf:PSingle; wNumPerCh:WORD):WORD; StdCall;
```

```
// Functions of Channel Scan for Interrupt Only
Function A822_ChScan_IntInstall
    (var hEvent:LongInt; dwNumPerCh:LongInt):WORD; StdCall;
Function A822_ChScan_IntStart
    (c1:WORD; c2:WORD; wCardType:WORD):WORD; StdCall;
Function A822_ChScan_IntGetCount(var dwVal:LongInt):WORD; StdCall;
Function A822_ChScan_IntGetHexBuf(wBuf:PWORD):WORD; StdCall;
Function A822_ChScan_IntGetFloatBuf(fBuf:PSingle):WORD; StdCall;
Function A822_ChScan_IntStop:WORD; StdCall;
Function A822_ChScan_IntRemove:WORD; StdCall;
```

implementation

```
Function A822_SHORT_SUB_2;                external 'A822.DLL' name
'A822_SHORT_SUB_2';
Function A822_FLOAT_SUB_2;                external 'A822.DLL' name
'A822_FLOAT_SUB_2';
Function A822_Get_DLL_Version;            external 'A822.DLL' name
'A822_Get_DLL_Version';
Function A822_GetDriverVersion;           external 'A822.DLL' name
'A822_GetDriverVersion';

Function A822_DO;                          external 'A822.DLL' name
'A822_DO';
Function A822_DI;                          external 'A822.DLL' name
'A822_DI';
```

Function A822_SetChGain; 'A822_SetChGain';	external 'A822.DLL' name
Function A822_Fast_AD_Hex; 'A822_Fast_AD_Hex';	external 'A822.DLL' name
Function A822_Fast_AD_Float; 'A822_Fast_AD_Float';	external 'A822.DLL' name
Function A822_AD_Hex; 'A822_AD_Hex';	external 'A822.DLL' name
Function A822_AD_Float; 'A822_AD_Float';	external 'A822.DLL' name
Function A822_ADs_Hex; 'A822_ADs_Hex';	external 'A822.DLL' name
Function A822_ADs_Float; 'A822_ADs_Float';	external 'A822.DLL' name
Function A822_Hex2Float; 'A822_Hex2Float';	external 'A822.DLL' name
Function A822_DA_Hex; 'A822_DA_Hex';	external 'A822.DLL' name
Function A822_DA_Uni5; 'A822_DA_Uni5';	external 'A822.DLL' name
Function A822_DA_Uni10; 'A822_DA_Uni10';	external 'A822.DLL' name
Function A822_DriverInit; 'A822_DriverInit';	external 'A822.DLL' name
Procedure A822_DriverClose; 'A822_DriverClose';	external 'A822.DLL' name
Function A822_DELAY; 'A822_DELAY';	external 'A822.DLL' name
Function A822_Check_Address; 'A822_Check_Address';	external 'A822.DLL' name
Function A822_GetConfigAddress; 'A822_GetConfigAddress';	external 'A822.DLL' name
Function A822_ActiveBoard; 'A822_ActiveBoard';	external 'A822.DLL' name

Procedure A822_OutputByte; 'A822_OutputByte';	external 'A822.DLL' name
Procedure A822_OutputWord; 'A822_OutputWord';	external 'A822.DLL' name
Function A822_InputByte; 'A822_InputByte';	external 'A822.DLL' name
Function A822_InputWord; 'A822_InputWord';	external 'A822.DLL' name
Procedure A822_SetTriggerMode; 'A822_SetTriggerMode';	external 'A822.DLL' name
Function A822_Int_Install; 'A822_Int_Install';	external 'A822.DLL' name
Function A822_Int_Start; 'A822_Int_Start';	external 'A822.DLL' name
Function A822_Int_Stop; 'A822_Int_Stop';	external 'A822.DLL' name
Function A822_Int_Remove; 'A822_Int_Remove';	external 'A822.DLL' name
Function A822_Int_GetCount; 'A822_Int_GetCount';	external 'A822.DLL' name
Function A822_Int_GetHexBuf; 'A822_Int_GetHexBuf';	external 'A822.DLL' name
Function A822_Int_GetFloatBuf; 'A822_Int_GetFloatBuf';	external 'A822.DLL' name
// Functions of Channel Scan	
Procedure A822_ChScan_Clear; 'A822_ChScan_Clear';	external 'A822.DLL' name
Function A822_ChScan_Add; 'A822_ChScan_Add';	external 'A822.DLL' name
Function A822_ChScan_PollingHex; 'A822_ChScan_PollingHex';	external 'A822.DLL' name
Function A822_ChScan_PollingFloat; 'A822_ChScan_PollingFloat';	external 'A822.DLL' name



```
// Functions of Channel Scan for Interrupt Only
Function A822_ChScan_IntlInstall;          external 'A822.DLL' name
'A822_ChScan_IntlInstall';
Function A822_ChScan_IntStart;           external 'A822.DLL' name
'A822_ChScan_IntStart';
Function A822_ChScan_IntGetCount;        external 'A822.DLL' name
'A822_ChScan_IntGetCount';
Function A822_ChScan_IntGetHexBuf;       external 'A822.DLL' name
'A822_ChScan_IntGetHexBuf';
Function A822_ChScan_IntGetFloatBuf;     external 'A822.DLL' name
'A822_ChScan_IntGetFloatBuf';
Function A822_ChScan_IntStop;            external 'A822.DLL' name
'A822_ChScan_IntStop';
Function A822_ChScan_IntRemove;          external 'A822.DLL' name
'A822_ChScan_IntRemove';

end.
```

## 2. REFERENCE

---

### 2.1 RANGE CONFIGURATION CODE

**The AD converter of OME-A822PGH/L is 12-bit under all configuration codes.** If the analog input range is configured to +/- 5V range, the resolution of one bit is equal to 2.44 mV. If the analog input range is configured to +/- 2.5V range, the resolution will be 1.22 mV. If the analog input signal is about 1 V, use configuration 0/1/2 (for OME-A822PGL) will get nearly the same result **except resolution. So choosing the correct configuration code can achieve the highest precision measurement.**

**OME-A-822PGL Input Signal Range Configuration Code Table**

Bipolar/Unipolar	Input Signal Range	Configuration Code
Bipolar	<b>+/- 5V</b>	<b>0</b>
Bipolar	<b>+/- 2.5V</b>	<b>1</b>
Bipolar	<b>+/- 1.25V</b>	<b>2</b>
Bipolar	<b>+/- 0.0625V</b>	<b>3</b>
Unipolar	<b>0V ~ 10V</b>	<b>4</b>
Unipolar	<b>0V ~ 5V</b>	<b>5</b>
Unipolar	<b>0V ~ 2.5V</b>	<b>6</b>
Unipolar	<b>0V ~ 1.25V</b>	<b>7</b>
Bipolar	<b>+/- 10V</b>	<b>8</b>

**OME-A-822PGH Input Signal Range Configuration Code Table**

Bipolar/Unipolar	Input Signal Range	Configuration Code
Bipolar	<b>+/- 5V</b>	<b>0</b>
Bipolar	<b>+/- 0.5V</b>	<b>1</b>
Bipolar	<b>+/- 0.05V</b>	<b>2</b>
Bipolar	<b>+/- 0.005V</b>	<b>3</b>
Unipolar	<b>0 ~ 10V</b>	<b>4</b>
Unipolar	<b>0 ~ 1V</b>	<b>5</b>
Unipolar	<b>0 ~ 0.1V</b>	<b>6</b>
Unipolar	<b>0 ~ 0.01V</b>	<b>7</b>
Bipolar	<b>+/- 10V</b>	<b>8</b>
Bipolar	<b>+/- 1V</b>	<b>9</b>
Bipolar	<b>+/- 0.1V</b>	<b>10</b>
Bipolar	<b>+/- 0.01V</b>	<b>11</b>

## 2.2 ERROR CODE

Error Code	Number	Description
A822_NoError	0	OK
A822_DriverOpenError	1	Please check if the driver installed correctly.
A822_DriverNoOpen	2	Please call the driver initial function to open the driver first.
A822_GetDriverVersionError	3	Can't call the device driver function. Please call the driver initial function to open the driver first.
A822_InstallIrqError	4	<ol style="list-style-type: none"> <li>1. Please call the driver initial function to open the driver firstly.</li> <li>2. Please check the resource that does not conflicted with other device.</li> </ol>
A822_ClearIntCountError	5	Can't call the device driver function. Please call the driver initial function to open the driver first.
A822_GetIntCountError	6	Can't call the device driver function. Please call the driver initial function to open the driver first.
A822_GetBufferError	7	Can't call the device driver function. Please call the driver initial function to open the driver first.
A822_AllocateMemoryError	11	Can't allocate the memory for buffer. Please check your system's resource.
A822_CardTypeError	12	Valid range is : 0 to 1 (OME-A-822L or OME-A-822H)
A822_TimeoutError	13	ADC timeout error
A822_OtherError	14	Unknown error
A822_ExceedBoardNumber	15	The driver initial function will return number of total boards. The board number to be active must less then this number. For example: if the driver initial function returns 3, and the valid range is 0 to 2.

A822_CardNotFound	16	The card not found by the device driver. Please check your hardware and driver settings.
A822_ChannelNoError	17	The valid AD channel no range is 0 to 15. The valid DA channel no range is 0 to 1.
A822_IntStopError	18	Can't call the device driver function. Please call the driver initial function to open the driver first.
A822_IntInstallEventError	19	Can't call the device driver function. Please call the driver initial function to open the driver first.
A822_GetConfigError	20	1. Can't call the device driver function. Please call the driver initial function to open the driver firstly. 2. Call the "ActiveBoard" function first.
A822_ActiveBoardError	21	1. Please call the driver initial function to open the driver first. 2. The driver initial function will return number of total boards. The board number to be active must less then this number.
A822_ConfigCodeError	22	Please refer to "Section 2.1 Range Configuration Code" for the valid configuration code.
A822_BufferFull	23	The buffer for the Channel Scan had full. The max number of buffer is 100 channels to scan. Please use the A822_ChScan_Clear() function to clear the buffer.
A822_NoChannelToScan	24	The user has to setting the channels to scan. Please use the A822_ChScan_Add() function to add channel and configuration-code to buffer for the Channel Scan.
A822_IntInstallChannelError	25	Failed to install the list for the Channel Scan into the interrupt service routine. Please check your system's resource.
A822_IntInstallConfigError	26	Failed to install the list for the Channel Scan into the interrupt service routine. Please check your system's resource.

## 2.3 OTHER MANUALS

Please refer to the following user manuals:

- **SoftInst.pdf:**  
Install the software package under Windows 95/98/NT/2000.
- **CallDll.pdf:**  
Include the declaration files and call the DLL functions with VC++5, VB5, Delphi3 and Borland C++ Builder 3.
- **ResCheck.pdf:**  
Check the resources I/O Port address, IRQ number and DMA number for add-on cards under Windows 95/98/NT/2000.
- **PnPInstall.pdf:**  
Install the Plug and Play information file (\*.inf) under Windows 95/98/2000.

## 3. FUNCTION DESCRIPTION

These functions in DLL are divided into several groups as following:

1. The test functions
2. The DI/O functions
3. The AD/DA fixed-mode functions
4. The Driver functions
5. The AD Interrupt Mode functions
6. The AD, Channel Scan functions
7. The AD Interrupt, Channel Scan functions

The functions of test listing as follows:

1. A822\_SHORT\_SUB\_2
2. A822\_FLOAT\_SUB\_2
3. A822\_Get\_DLL\_Version
4. A822\_GetDriverVersion

The functions of DI/O listing as follows:

1. A822\_DI
2. A822\_DO
3. A822\_InputByte
4. A822\_InputWord
5. A822\_OutputByte
6. A822\_OutputWord

The functions of AD/DA listing as follows:

1. A822\_SetChGain
2. A822\_Fast\_AD\_Hex
3. A822\_Fast\_AD\_Float
4. A822\_AD\_Hex
5. A822\_AD\_Float
6. A822\_ADs\_Hex
7. A822\_ADs\_Float
8. A822\_Hex2Float
9. A822\_DA\_Hex
10. A822\_DA\_Uni5
11. A822\_DA\_Uni10

The functions of Driver listing as follows:

1. A822\_DriverInit
2. A822\_DriverClose
3. A822\_DELAY
4. A822\_Check\_Address
5. A822\_SetTriggerMode
6. A822\_GetConfigAddress
7. A822\_ActiveBoard
8. A822\_SetCounter
9. A822\_ReadCounter

The functions of AD Interrupt listing as follows:

1. A822\_Int\_Install
2. A822\_Int\_Start
3. A822\_Int\_Stop
4. A822\_Int\_Remove
5. A822\_Int\_GetCount
6. A822\_Int\_GetHexBuf
7. A822\_Int\_GetFloatBuf

The functions of AD, Channel Scan listing as follows:

1. A822\_ChScan\_Clear
2. A822\_ChScan\_Add
3. A822\_ChScan\_PollingHex
4. A822\_ChScan\_PollingFlaot

The functions of AD Interrupt, Channel Scan listing as follows:

1. A822\_ChScan\_IntInstall
2. A822\_ChScan\_IntStart
3. A822\_ChScan\_IntStop
4. A822\_ChScan\_IntRemove
5. A822\_ChScan\_IntGetCount
6. A822\_ChScan\_IntGetHexBuf
7. A822\_ChScan\_IntGetFloatBuf

In this chapter, we use some keywords to indicate the attribute of Parameters.

Keyword	Parameter Set by user before calling this function ?	User Gets the data/value from this parameter after calling this function ?
[In]	Yes	No
[Out]	No	Yes
[In, Out]	Yes	Yes

Note: All of the parameters require space allocation by the user.

## 3.1 TEST FUNCTION

---

### 3.1.1 A822\_SHORT\_SUB\_2

- **Description:**  
Compute  $C=A-B$  in **short** formats, **short = 16-bit signed integer.**  
This function is provided for testing purpose.
  - **Syntax:**  
short A822\_SHORT\_SUB\_2(short nA, short nB);
  - **Parameter:**  
nA : [In] short integer  
nB : [In] short integer
  - **Return:**  
return=nA-nB → short integer
- 

### 3.1.2 A822\_FLOAT\_SUB\_2

- **Description:**  
Compute  $A-B$  in **float** format, **float = 32-bit floating pointer number.**  
This function is provided for testing purpose.
  - **Syntax:**  
float A822\_FLOAT\_SUB\_2(float fA, float fB);
  - **Parameter:**  
fA : [In] floating point value  
fB : [In] floating point value
  - **Return:**  
return=fA-fB → floating point value
-



### 3.1.3 A822\_Get\_DLL\_Version

- **Description:**  
Read the software version of the A822.DLL.
- **Syntax:**  
WORD A822\_Get\_DLL\_Version(void) ;
- **Parameter:**  
void
- **Return:**  
return=0x200 → Version 2.00 (**WORD = 16-bit unsigned integer**)

---

---

### 3.1.4 A822\_GetDriverVersion

- **Description:**  
This subroutine will get the version number from the device driver.
- **Syntax:**  
WORD A822\_GetDriverVersion(WORD \*wDriverVersion) ;
- **Parameter:**  
wDriverVersion            : [Out] the address of wDriverVersion.  
                                      when wDriverVerion=0x210 → version 2.10
- **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detailed information.

## 3.2 DI/DO FUNCTION

---

---

### 3.2.1 A822\_DI

- **Description:**  
This subroutine will read the 16-bit data from the digital input port.
  - **Syntax:**  
WORD A822\_DI(WORD \*wInVal);
  - **Parameter:**  
wInVal : [In] 16 bits Digital-Input value.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detailed information.
- 
- 

### 3.2.2 A822\_DO

- **Description:**  
This subroutine will send the 16-bit data to digital output port.
  - **Syntax:**  
WORD A822\_DO(WORD wHexValue);
  - **Parameter:**  
wHexValue : [In] 16 bit data sent to digital output port
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detailed information.
- 
-

### 3.2.3 A822\_OutputByte

- **Description:**  
This subroutine will send the 8-bit data to the desired I/O port.
- **Syntax:**  
void A822\_OutputByte(WORD wPortAddr, UCHAR bOutputVal);
- **Parameter:**  
wPortAddr : [In] I/O port address, for example, 0x220  
bOutputVal : [In] 8-bit data sent to I/O port
- **Return:**  
void

---

### 3.2.4 A822\_OutputWord

- **Description:**  
This subroutine will send the 16-bit data to the desired I/O port.
- **Syntax:**  
void A822\_OutputByte(WORD wPortAddr, WORD wOutputVal);
- **Parameter:**  
wPortAddr : [In] I/O port address, for example, 0x220  
wOutputVal : [In] 16-bit data sent to I/O port
- **Return:**  
void

## 3.2.5 A822\_InputByte

- **Description:**  
This subroutine will input the 8-bit data from the desired I/O port.
  - **Syntax:**  
WORD A822\_InputByte(WORD wPortAddr);
  - **Parameter:**  
wPortAddr : [In] I/O port address, for example, 0x220
  - **Return:**  
16-bit data with the leading 8 bits are all 0
- 

## 3.2.6 A822\_InputWord

- **Description:**  
This subroutine will input the 16-bit data from the desired I/O port.
- **Syntax:**  
WORD DIO\_InputWord(WORD wPortAddr);
- **Parameter:**  
wPortAddr : [In] I/O port address, for example, 0x220
- **Return:**  
16-bit data.

## 3.3 A/D, D/A FUNCTION

---

---

### 3.3.1 A822\_SetChGain

- **Description:**

The subroutine sets the channel number and configuration code for the ADC. And then user delays for the settling time.

The user have to call this function once before calling the “A822\_Fast\_AD\_Hex()”, “A822\_Fast\_AD\_Float()”, “A822\_Int\_Start()”, “A822\_ADs\_Hex()” and “A822\_ADs\_Float()” functions.

- **Syntax:**

```
WORD A822_SetChGain  
(WORD wChannel, WORD wConfig, WORD wCardType);
```

- **Parameter:**

wChannel : [In] A/D channel number, 0 to 15.  
wConfig : [In] Configuration code, refer to “[Section 2.1 Range Configuration Code](#)” for detailed information.  
wCardType : [In] 0 → OME-A-822PGL, 1 → OME-A-822PGH

- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detailed information.

### 3.3.2 A822\_Fast\_AD\_Hex

- **Description:**

This subroutine will perform an A/D conversion by polling. The A/D converter is 12 bits for OME-A822PGH/L. **The user has to call the "A822\_SetChGain()" function before calling this function.**

- **Syntax:**

WORD A822\_Fast\_AD\_Hex(WORD \*wVal);

- **Parameter:**

wVal : [Out] 12 bits hex value of Analog-Input.

- **Return:**

Please refer to "**Section 2.2 Error Code**" for the detailed information.

---

---

### 3.3.3 A822\_Fast\_AD\_Float

- **Description:**

This subroutine will perform an A/D conversion by polling. The A/D converter is 12 bits for OME-A822PGH/L. This subroutine will compute the result according to the **configuration code**. **The user has to call the "A822\_SetChGain()" function before calling this function.**

- **Syntax:**

WORD A822\_Fast\_AD\_Float(float \*fVal);

- **Parameter:**

fVal : [Out] Floating point value of Analog-Input.

- **Return:**

Please refer to "**Section 2.2 Error Code**" for the detailed information.

---

### 3.3.4 A822\_AD\_Hex

- **Description:**

This subroutine will perform an A/D conversion by polling. The A/D converter is 12 bits for OME-A822PGH/L.
  - **Syntax:**

WORD A822\_AD\_Hex  
(WORD wChannel, WORD wConfig, WORD wCardType, WORD \*wVal);
  - **Parameter:**

wChannel	: [In] A/D channel number, 0 to 15.
wConfig	: [In] Configuration code, refer to “ <a href="#">Section 2.1 Range Configuration Code</a> ” for detail information
wCardType	: [In] 0 → OME-A-822PGL, 1 → OME-A-822PGH
wVal	: [Out] 12 bits hex value of Analog-Input.
  - **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detailed information.
- 

### 3.3.5 A822\_AD\_Float

- **Description:**

This subroutine will perform an A/D conversion by polling. The A/D converter is 12 bits for OME-A822PGH/L. This subroutine will compute the result according to the **configuration code**.
- **Syntax:**

WORD A822\_AD\_Float  
(WORD wChannel, WORD wConfig, WORD wCardType, float \*fVal);
- **Parameter:**

wChannel	: [In] A/D channel number, 0 to 15.
wConfig	: [In] Configuration code, refer to “ <a href="#">Section 2.1 Range Configuration Code</a> ” for detail information
wCardType	: [In] 0 → OME-A-822PGL, 1 → OME-A-822PGH
fVal	: [Out] Floating point value of Analog-Input.
- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detailed information.

### 3.3.6 A822\_ADs\_Hex

- **Description:**

This subroutine will perform a number of A/D conversions by polling. This subroutine is very similar to A822\_AD\_Hex except that this subroutine will perform wCount of conversions instead of just one conversion. The A/D conversion happens at the ISA bus's max speed. After A/D conversion, the A/D data are stored in a buffer in Hex format. The **wBuf** is the starting address of this data buffer. **The user has to call the "A822\_SetChGain()" function before calling this function.**

- **Syntax:**

WORD A822\_ADs\_Hex(WORD wBuf[], WORD wCount);

- **Parameter:**

wBuf : [Out] Starting address of the data buffer  
(In WORD format)

The user must allocate space for this buffer and send the address in the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.

wCount : [In] Number of A/D conversions will be performed

- **Return:**

Please refer to "**Section 2.2 Error Code**" for the detail information.



### 3.3.7 A822\_ADs\_Float

- **Description:**

This subroutine will perform a number of A/D conversions by polling. This subroutine is very similar to A822\_AD except that this subroutine will perform wCount of conversions instead of just one conversion. The A/D conversion happens at the ISA bus's max speed. Then the A/D data are stored in a data buffer in Float format. The **fBuf** is the starting address of this data buffer. **The user has to call the "A822\_SetChGain()" function before calling this function.**

- **Syntax:**

WORD A822\_ADs\_Float(float fBuf[], WORD wCount);

- **Parameter:**

fBuf : [Out] Starting address of the data buffer  
(In float format)

The user must allocate space for this buffer and send the address in the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.

wCount : [In] Number of A/D conversions will be performed

- **Return:**

Please refer to "**Section 2.2 Error Code**" for the detail information.

### 3.3.8 A822\_DA\_Hex

- **Description:**

This subroutine will send 12 bits of data to D/A analog output. The output range of D/A maybe 0-5V or 0-10V **set by the hardware jumper, JP1**. The software **cannot detect** the output range of D/A converter. **For examples, if hardware select -5V, the 0xff will send out 5V. If hardware select -10V, the 0xff will send out 10V. The factory setting select 0-5V D/A output range.**

- **Syntax:**

WORD A822\_DA\_Hex(WORD wChannel, WORD wHexValue);

- **Parameter:**

wChannel : [In] D/A channels number, validate for 0 or 1.  
wHexValue : [In] 12 bit data send to D/A converter

- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.

---

---

### 3.3.9 A822\_DA\_Uni5

- **Description:**

This subroutine will send the 12 bits of data to D/A analog output. The output range of D/A dependent on **hardware jumper settings, JP1 (- 5v or – 10v), JP10/JP11 (Bipolar or Unipolar)**. The software **cannot detect** the output range of D/A converter. This subroutine can be used only when the jumper's settings are: **Unipolar, -5v**. The **output range is between 0.0v and 5.0v**. Please refer to hardware manual to setting jumpers.

- **Syntax:**

void A822\_DA\_Uni5 (WORD wChannel, float fValue);

- **Parameter:**

wChannel : [In] D/A channel number, validated for 0 or 1  
fValue : [In] 12 bit data send to D/A converter

- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.

---

### 3.3.10 A822 \_DA\_Uni10

- **Description:**

This subroutine will send the 12 bits of data to D/A analog output. The output range of D/A dependent on **hardware jumper settings, JP1 ( - 5v or - 10v) , JP10/JP11 (Bipolar or Unipolar)**. The software **cannot detect** the output range of D/A converter. This subroutine can be used only when the jumper's settings are: **Unipolar , -10v** . The **output range is between 0.0v and 10.0v**. Please refer to hardware manual to setting jumpers.

- **Syntax:**

void A822 \_DA\_Uni10 (WORD wChannel, float fValue);

- **Parameter:**

wChannel : [In] D/A channels number, validate for 0 or 1  
fValue : [In] 12 bit data send to D/A converter

- **Return:**

Please refer to “**Section 2.2 Error Code**” for the detail information.

## 3.4 DRIVER FUNCTION

---

---

### 3.4.1 A822\_DriverInit

- **Description:**

This subroutine will open the device driver. After calling the A822\_DriverInit() function, the user still have to call the A822\_ActiveBoard() function before accessing the device.

- **Syntax:**

WORD A822\_DriverInit(WORD \*wTotalBoards);

- **Parameter:**

WTotalBoards : [Out] Returns the number of boards that were found by the driver.

- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.

---

---

### 3.4.2 A822\_DriverClose

- **Description:**

This subroutine will close the device driver.

- **Syntax:**

void A822\_DriverClose(void);

- **Parameter:**

None

- **Return:**

None

### 3.4.3 A822\_SetTriggerMode

- **Description:**

This subroutine will set the trigger mode - internal or external. The default value/mode is the internal trigger mode if the user does not use this function. The user must call this function before calling any AD function (include the "A822\_ActiveBoard" and "A822\_Check\_Address" functions) if the user uses external trigger mode.

Please refer to the hardware manual to set the jumper JP4(A/D Trigger Source Selection). The JP4 default setting is "INTTRG"(Internal-Trigger).

- **Syntax:**

void A822\_SetTriggerMode(WORD wTriggerMode )

- **Parameter:**

wTriggerMode : [In] 0: Internal Trigger Mode  
1: External Trigger Mode

- **Return:**

None

### 3.4.4 A822\_DELAY

- **Description:**  
This subroutine will delay **wDownCount** mS (machine independent timer).  
This function uses the Counter0 to implement delay function.  
The unit of A822\_DELAY() is 0.5uSeconds. (2MHz → 2000K times/sec)
- **Syntax:**  
WORD A822\_DELAY(WORD wDownCount);
- **Parameter:**  
wDownCount : [In] Number of 0.5uS it will delay
- **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.

---

### 3.4.5 A822\_Check\_Address

- **Description:**  
This subroutine will detect the OME-A-822PGH/L in I/O base address.  
This subroutine will perform one A/D conversion. If successful, it found an OME-A-822PGH/L. This function will always return 0 if the user set the trigger mode to external.  
  
Refer to the function "A822\_SetTriggerMode".
- **Syntax:**  
WORD A822\_Check\_Address(void);
- **Parameter:**  
None
- **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.

### 3.4.6 A822\_GetConfigAddress

- **Description:**

This subroutine returns the Base-Address and board-number of the current board.

If the current board is invalid, the Base-Address will be 0.

- **Syntax:**

```
WORD A822_GetConfigAddress  
    (WORD *wAddrBase, WORD *wCurrentBoard);
```

- **Parameter:**

wAddrBase : [Out] Returns the Base-Address of the current board.  
wCurrentBoard : [Out] Returns the board-number of the current board.

- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.

---

### 3.4.7 A822\_ActiveBoard

- **Description:**

This subroutine activates the specified board. User can then call the A822\_Check\_Address() function to check this hardware automatically. If the function can not access this device, it also returns A822\_CardNotFound error code. Please refer to the “A822\_DriverInit()” function for the valid range of board numbers.

- **Syntax:**

```
WORD A822_ActiveBoard( WORD wBoardNo );
```

- **Parameter:**

wBoardNo : [In] The board number to be active.

- **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.

---

### 3.4.8 A822\_SetCounter

- **Description:**  
This subroutine will set the 8254 counter mode and value.
- **Syntax:**  

```
void A822_SetCounter(WORD wCounterNo,  
                    WORD bCounterMode, DWORD wCounterValue);
```
- **Parameter:**  
wCounterNo : [Input] Counter Number 0 to 2 for the 8254  
wCounterMode : [Input] Counter Mode 0 to 5 for the 8254  
wCounterValue : [Input] Counter Value 0 to 65535 for the 8254
- **Return:**  
None

---

### 3.4.9 A822\_ReadCounter

- **Description:**  
This subroutine will read the 8254 counter value.
- **Syntax:**  

```
DWORD A822_ReadCounter(WORD wCounterNo, WORD bCounterMode);
```
- **Parameter:**  
wCounterNo : [Input] Counter Number 0 to 2 for the 8254  
wCounterMode : [Input] Counter Mode 0 to 5 for the 8254
- **Return:**  
Return the counter's value and only the lower WORD is valid.



## 3.5 AD, INTERRUPT FUNCTION

---

### 3.5.1 A822\_Int\_Install

- **Description:**

This subroutine will install interrupt handler and allocate buffer. For more detail information of using interrupt please refer to “[Section 3.5.8 Architecture of Interrupt Mode](#)”.
  - **Syntax:**

```
WORD A822_Int_Install(HANDLE *hEvent, DWORD dwCount );
```
  - **Parameter:**

hEvent	: [In]	The Event handle that created by the user.
dwCount	: [In]	The desired A/D entries count for interrupt transfer.
  - **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.
- 

### 3.5.2 A822\_Int\_Start

- **Description:**

This subroutine will clear the interrupt-counter and start the interrupt transfer for a specific A/D channel and programming the gain code and sampling rate. **The user has to call the “[A822\\_SetChGain\(\)](#)” function once before this function.**
  - **Syntax:**

```
WORD A822_Int_Start(WORD c1, Word c2);
```
  - **Parameter:**

c1,c2	: [In]	the sampling rate is $2M/(c1*c2)$ c1 → Counter1, c2 → Counter2
-------	--------	---

These values be used only when the Trigger-Mode is set to Internal-Trigger. Please refer to the function “[A822\\_SetTriggerMode](#)”.
  - **Return:**

Please refer to “[Section 2.2 Error Code](#)” for the detail information.
-

### 3.5.3 A822\_Int\_Stop

- **Description:**  
This subroutine will stop the interrupt transfer.
  - **Syntax:**  
WORD A822\_Int\_Stop(void );
  - **Parameter:**  
void.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.
- 

### 3.5.4 A822\_Int\_Remove

- **Description:**  
This subroutine will remove the interrupt handler and free the buffer.
  - **Syntax:**  
WORD A822\_Int\_Remove(void );
  - **Parameter:**  
void.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.
- 

### 3.5.5 A822\_Int\_GetCount

- **Description:**  
This subroutine will read the transferred count of interrupts.
  - **Syntax:**  
WORD A822\_Int\_GetCount(DWORD \*dwVal )
  - **Parameter:**  
dwVal : [Out] Returns the count of interrupts transferred.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.
-

### 3.5.6 A822\_Int\_GetHexBuf

- **Description:**

This subroutine will copy the transferred interrupted data into the user's buffer.

- **Syntax:**

WORD A822\_Int\_GetHexBuf(WORD wBuf[], DWORD dwNum)

- **Parameter:**

wBuf : [Out] The address of wBuffer(In WORD format).

The user must allocate spaces for this buffer and send the address in the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.

dwNum : [In] The number to transfer.

- **Return:**

Please refer to "[Section 2.2 Error Code](#)" for the detail information.

---

### 3.5.7 A822\_Int\_GetFloatBuf

- **Description:**

This subroutine will copy the transferred interrupted data into the user's buffer.

- **Syntax:**

WORD A822\_Int\_GetFloatBuf(float fBuf[],DWORD dwNum)

- **Parameter:**

fBuf : [Out] The address of fBuffer(In float format).

The user must allocate spaces for this buffer and send the address in the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.

dwNum : [In] The number to transfer.

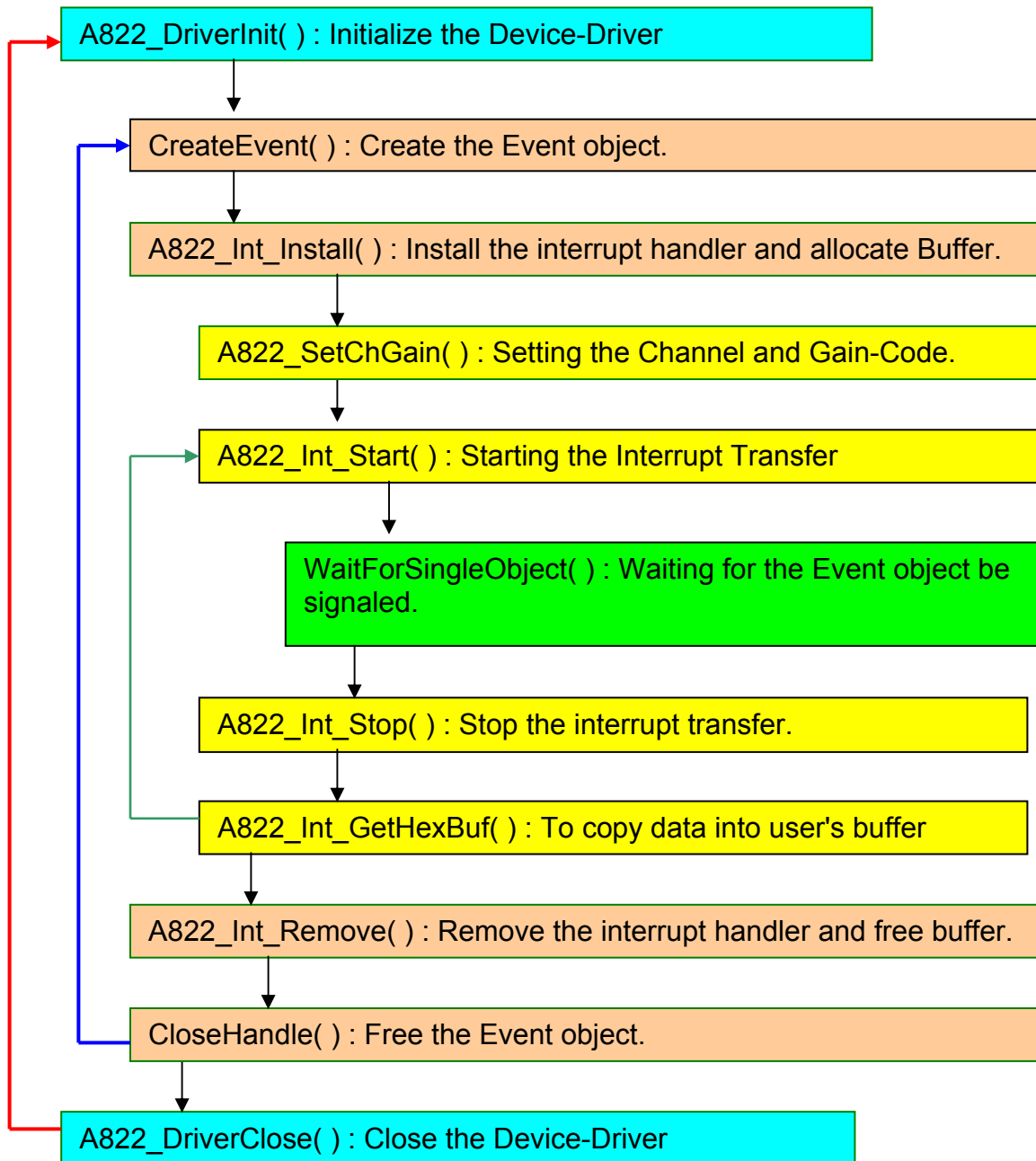
- **Return:**

Please refer to "[Section 2.2 Error Code](#)" for the detail information.

---

### 3.5.8 Architecture of Interrupt mode

The functions listed in sections 3.5.1 to 3.5.7 are the functions to perform the A/D conversion with interrupt transfer. The flow chart to program these functions is given as follows:

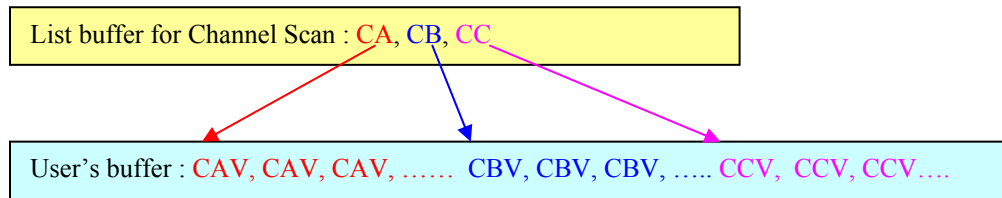


## 3.6 AD, CHANNEL SCAN FUNCTION

### 3.6.1 Introduction

The user can specify channels into a list buffer. User then uses other functions to perform the ADC to get the data. Then user can read the list buffer to change to next channel and set to specify configuration code.

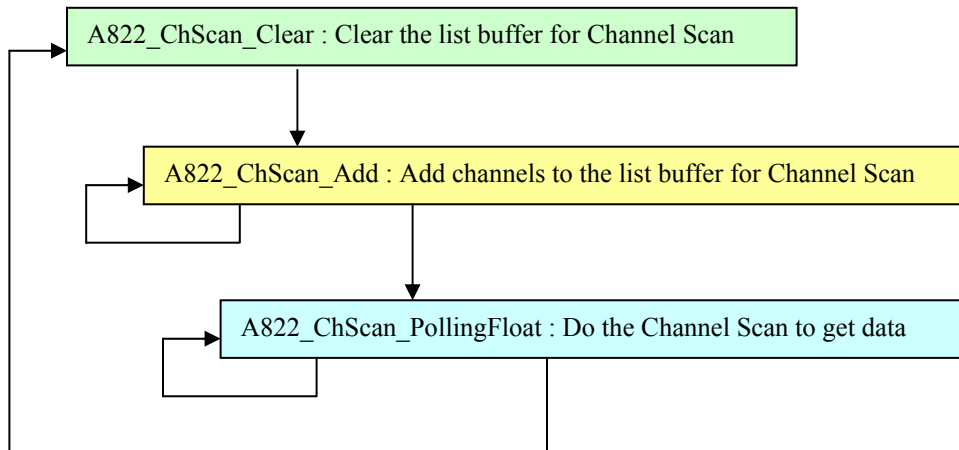
The data will be saved into the following style:



Note:

CA= Channel A; CB= Channel B; CC= Channel C  
CAV= Channel A's value; CBV= Channel B's value;  
CCV= Channel C's value

The user program's architecture should be as described below:



### 3.6.2 A822\_ChScan\_Clear

- **Description:**  
This subroutine will clear the list buffer for the Channel Scan.
- **Syntax:**  
void A822\_ChScan\_Clear(void);
- **Parameter:**  
None
- **Return:**  
None

---

---

### 3.6.3 A822\_ChScan\_Add

- **Description:**  
This function will add the specified channel number and configuration-code into the list buffer for the Channel Scan. The max number of the list buffer (for the Channel Scan) is 100 channels.
- **Syntax:**  
WORD A822\_ChScan\_Add(WORD wChannel, WORD wConfig);
- **Parameter:**  
wChannel : [In] Which channel to be scanned.  
WConfig : [In] Specify the configuration-code for this channel.
- **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.

### 3.6.4 A822\_ChScan\_PollingHex

- **Description:**

This subroutine will perform a number of A/D conversions by polling. After getting the channel's data, it then reads the list buffer for the Channel Scan to change to next channel and set to specified configuration code. The A/D conversion happens at the ISA bus's max speed. After A/D conversion, the A/D data are stored in a buffer in Hex format.

Before calling this function, the user have to call the A822\_ChScan\_Clear() and A822\_ChScan\_Add() functions to setup the list buffer for Channel Scan. Please refer to the "[Section 3.6.1 Introduction](#)" for more information.

- **Syntax:**

WORD A822\_ChScan\_PollingHex  
 (WORD wCardType, WORD wBuf[], WORD wNumPerCh);

- **Parameter:**

WCardType : [In] 0: OME-A-822L      1: OME-A-822H  
 wBuf : [Out] Starting address of the data buffer (WORD format)  
 The user must allocate spaces for this buffer and send the address into the function. This function will fill the data into this buffer. The user can analyzes these data from the buffer after calling this function.

The buffer size  
 = Total-Channels \* wNumPerCh \* sizeof(WORD)

wNumPerCh : [In] Number of A/D conversions will be performed for every channel.

- **Return:**

Please refer to "[Section 2.2 Error Code](#)" for the detail information.

## 3.6.5 A822\_ChScan\_PollingFloat

- **Description:**

This subroutine will perform a number of A/D conversions by polling. And after getting the channel's data, it will then read the list buffer for the Channel Scan to change to next channel and set to specified configuration code. The A/D conversion happens at the ISA bus's max speed. After A/D conversion, the A/D data gets stored in a buffer in floating format.

Before calling this function, the user have to call the A822\_ChScan\_Clear() and A822\_ChScan\_Add() functions to setup the list buffer for Channel Scan. Please refer to the "[Section 3.6.1 Introduction](#)" for more information.

- **Syntax:**

```
WORD A822_ChScan_PollingFloat
    (WORD wCardType, float fBuf[], WORD wNumPerCh);
```

- **Parameter:**

WCardType : [In] 0: OME-A-822L 1: OME-A-822H  
 fBuf : [Out] Starting address of the data buffer (floating format)  
 The user must allocate spaces for this buffer and send the address into the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.

The buffer size  
 = Total-Channels \* wNumPerCh \* sizeof(float)

wNumPerCh : [In] Number of A/D conversions will be performed for every channel.

- **Return:**

Please refer to "[Section 2.2 Error Code](#)" for the detail information.



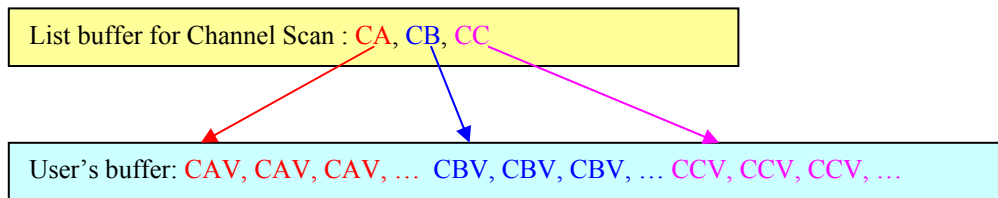
## 3.7 AD INTERRUPT, CHANNEL SCAN FUNCTION

---

---

### 3.7.1 Introduction

The user can specify channels into a list buffer. Then user uses functions to perform the ADC to get the data. Then they read the list buffer to change to next channel and set to specify configuration code.



The data will be saved into the following style:

Note:

CA= Channel A; CB= Channel B; CC= Channel C

CAV= Channel A's value; CBV= Channel B's value; CCV= Channel C's value

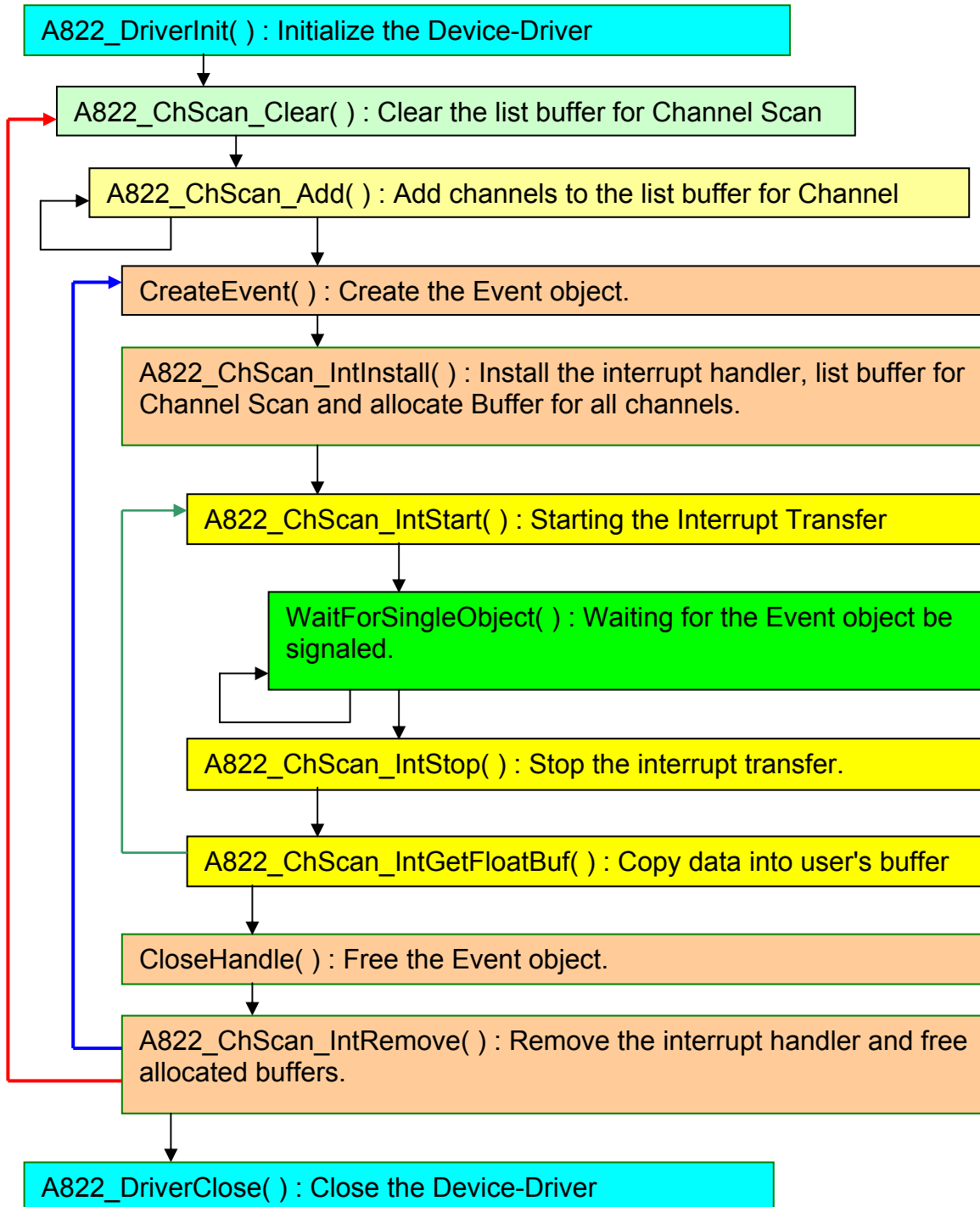
After setting the next channel and specified configuration code, **it will have to delay for period equal to the settling time before next ADC**. The interrupt service routine doesn't provide for the delay for the settling time. Thus, **to get the correct ADC data**, the user has to **slow-down the sampling-rate of interrupt**.

The sampling-rate is for all channels.

For example:

The list buffer for the Channel Scan is set to channel 2 and channel 0. The sampling rate is setting to 10 KHz. Actually the channel 2 has the sampling rate of 5KHz and the channel 0 also has the sampling rate of 5KHz.

The user program architecture should be as described here:



## 3.7.2 A822\_ChScan\_IntInstall

- **Description:**  
 This subroutine will install interrupt handler, copy the list buffer for Channel Scan into kernel-mode driver and allocate buffers for every channels. Before install the interrupt, the user has to **call the "A822\_ChScan\_Clear()" and "A822\_ChScan\_Add()" functions to setup the list buffer for Channel Scan firstly**. For more detail information regarding using interrupts please refer to **"Section 3.7.1 Introduction"**.
  - **Syntax:**  
 WORD A822\_ChScan\_IntInstall(HANDLE \*hEvent, DWORD dwNumPerCh);
  - **Parameter:**  
 hEvent : [In] The Event handle created by the user.  
 dwNumPerCh : [In] The desired A/D count for every channels to transfer.
  - **Return:**  
 Please refer to **"Section 2.2 Error Code"** for the detail information.
- 

## 3.7.3 A822\_ChScan\_IntStart

- **Description:**  
 This subroutine will clear the interrupt-counter and start the interrupt transfer for the specific A/D channels and program the gain code and sampling rate.
- **Syntax:**  
 WORD A822\_ChScan\_IntStart(WORD c1, WORD c2, WORD wCardType);
- **Parameter:**  
 c1,c2 : [In] the sampling rate is  $2M/(c1*c2)$ ; c1=Counter1, c2=Counter2  
 These counter's value only used when the Trigger-Mode is set to Internal-Trigger. Please refer to the "A822\_SetTriggerMode" function.  
 wCardType : [In] 0: OME-A-822L      1: OME-A-822H
- **Return:**  
 Please refer to **"Section 2.2 Error Code"** for the detail information.

### 3.7.4 A822\_ChScan\_IntStop

- **Description:**  
This subroutine will stop the interrupt transfer.
  - **Syntax:**  
WORD A822\_ChScan\_IntStop(void );
  - **Parameter:**  
void.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.
- 

### 3.7.5 A822\_ChScan\_IntRemove

- **Description:**  
This subroutine will remove the interrupt handler and free the buffers.
  - **Syntax:**  
WORD A822\_ChScan\_IntRemove(void );
  - **Parameter:**  
void.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detail information.
- 

### 3.7.6 A822\_ChScan\_IntGetCount

- **Description:**  
This subroutine will read the transferred count of interrupt.
  - **Syntax:**  
WORD A822\_Int\_GetCount(DWORD \*dwVal )
  - **Parameter:**  
dwVal : [Out] Returns the interrupt transferred count.
  - **Return:**  
Please refer to “[Section 2.2 Error Code](#)” for the detailed information.
-

### 3.7.7 A822\_ChScan\_IntGetHexBuf

- **Description:**

This subroutine will copy the transferred interrupted data into the user's buffer.
- **Syntax:**

WORD A822\_ChScan\_IntGetHexBuf(WORD wBuf[])
- **Parameter:**

wBuf : [Out] The address of wBuf(WORD format).  
The user must allocate spaces for this buffer and send the address in the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.  
Buffer size = Total-Channels \* dwNumPerCh \* sizeof(WORD)
- **Return:**

Please refer to "[Section 2.2 Error Code](#)" for the detail information.

---

### 3.7.8 A822\_ChScan\_IntGetFloatBuf

- **Description:**

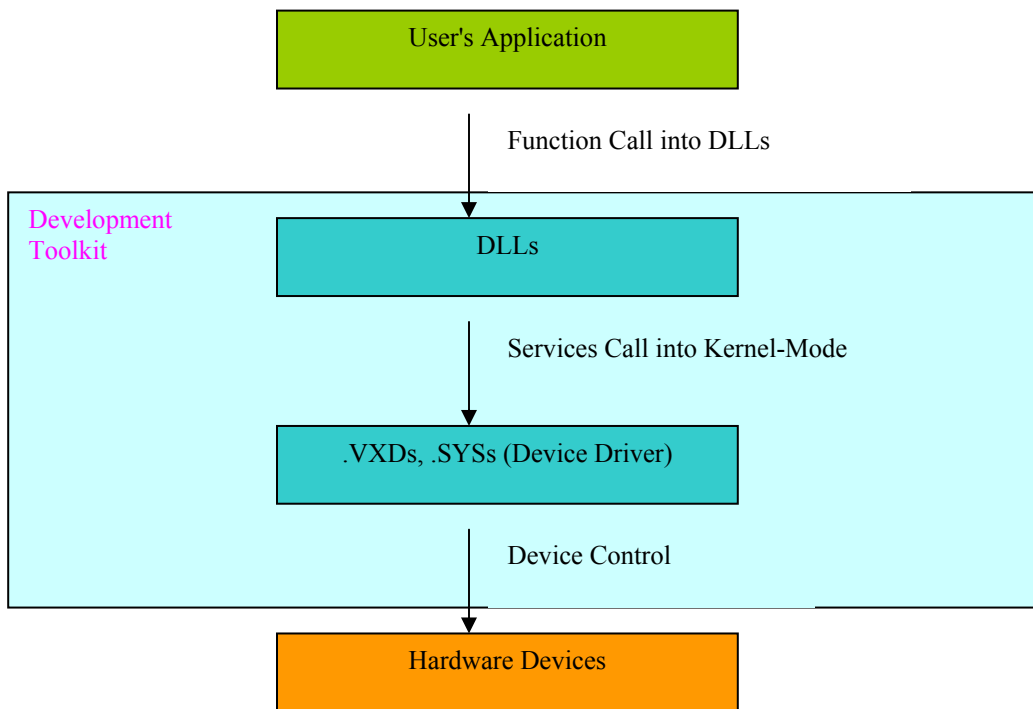
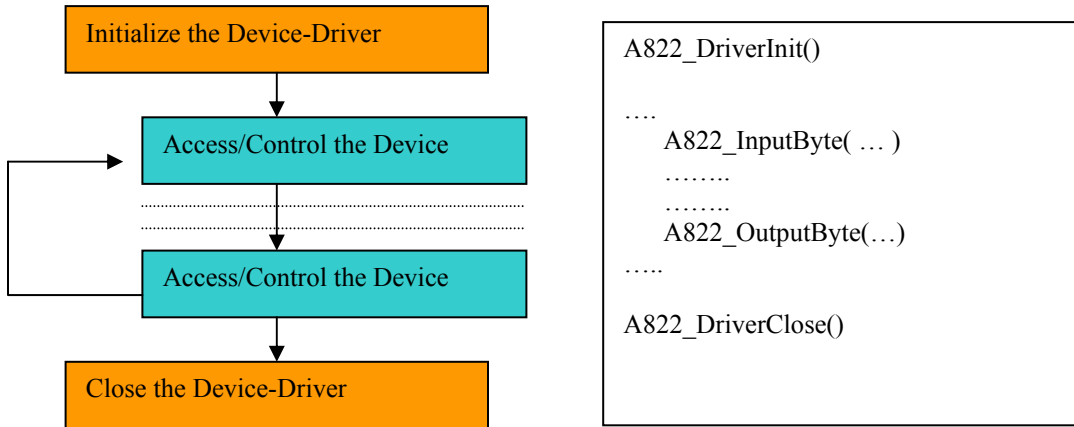
This subroutine will copy the transferred interrupted data into the user's buffer.
- **Syntax:**

WORD A822\_ChScan\_IntGetFloatBuf(float fBuf[])
- **Parameter:**

fBuf : [Out] The address of fBuf(float format).  
The user must allocate spaces for this buffer and send the address in the function. This function will fill the data into this buffer. The user can analyze this data from the buffer after calling this function.  
Buffer size = Total-Channels \* dwNumPerCh \* sizeof(float)
- **Return:**

Please refer to "[Section 2.2 Error Code](#)" for the detail information.

# 4. PROGRAM ARCHITECTURE



## 5. REPORT PROBLEMS

Technical support is available at no charge as described below. The best way to report problems is send electronic mail to **das@omega.com** on the Internet.

When reporting problems, please include the following information:

- 1) Is the problem reproducible? If so, how?
- 2) What kind and version of Operation Systems that you running? For example, Windows 3.1, Windows for Workgroups, Windows NT 4.0, etc.
- 3) What kinds of our products that you using? Please see the product's manual.
- 4) If a dialog box with an error message was displayed, please include the full text of the dialog box, including the text in the title bar.
- 5) If the problem involves other programs or hardware devices, what devices or version of the failing programs that you using?
- 6) Other comments relative to this problem or any Suggestions will be welcomed.

After we received your comments, we will take about two business days to testing the problems that you said. And then reply as soon as possible to you. Please check that we have received your comments? And please keeping contact with us.

E-mail: [das@omega.com](mailto:das@omega.com)  
Web-Site: <http://www.omega.com>

## WARRANTY/DISCLAIMER

OMEGA ENGINEERING, INC. warrants this unit to be free of defects in materials and workmanship for a period of **13 months** from date of purchase. OMEGA's WARRANTY adds an additional one (1) month grace period to the normal **one (1) year product warranty** to cover handling and shipping time. This ensures that OMEGA's customers receive maximum coverage on each product.

If the unit malfunctions, it must be returned to the factory for evaluation. OMEGA's Customer Service Department will issue an Authorized Return (AR) number immediately upon phone or written request. Upon examination by OMEGA, if the unit is found to be defective, it will be repaired or replaced at no charge. OMEGA's WARRANTY does not apply to defects resulting from any action of the purchaser, including but not limited to mishandling, improper interfacing, operation outside of design limits, improper repair, or unauthorized modification. This WARRANTY is VOID if the unit shows evidence of having been tampered with or shows evidence of having been damaged as a result of excessive corrosion; or current, heat, moisture or vibration; improper specification; misapplication; misuse or other operating conditions outside of OMEGA's control. Components which wear are not warranted, including but not limited to contact points, fuses, and triacs.

**OMEGA is pleased to offer suggestions on the use of its various products. However, OMEGA neither assumes responsibility for any omissions or errors nor assumes liability for any damages that result from the use of its products in accordance with information provided by OMEGA, either verbal or written. OMEGA warrants only that the parts manufactured by it will be as specified and free of defects. OMEGA MAKES NO OTHER WARRANTIES OR REPRESENTATIONS OF ANY KIND WHATSOEVER, EXPRESS OR IMPLIED, EXCEPT THAT OF TITLE, AND ALL IMPLIED WARRANTIES INCLUDING ANY WARRANTY OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE HEREBY DISCLAIMED. LIMITATION OF LIABILITY: The remedies of purchaser set forth herein are exclusive, and the total liability of OMEGA with respect to this order, whether based on contract, warranty, negligence, indemnification, strict liability or otherwise, shall not exceed the purchase price of the component upon which liability is based. In no event shall OMEGA be liable for consequential, incidental or special damages.**

CONDITIONS: Equipment sold by OMEGA is not intended to be used, nor shall it be used: (1) as a "Basic Component" under 10 CFR 21 (NRC), used in or with any nuclear installation or activity; or (2) in medical applications or used on humans. Should any Product(s) be used in or with any nuclear installation or activity, medical application, used on humans, or misused in any way, OMEGA assumes no responsibility as set forth in our basic WARRANTY/DISCLAIMER language, and, additionally, purchaser will indemnify OMEGA and hold OMEGA harmless from any liability or damage whatsoever arising out of the use of the Product(s) in such a manner.

## RETURN REQUESTS/INQUIRIES

Direct all warranty and repair requests/inquiries to the OMEGA Customer Service Department. BEFORE RETURNING ANY PRODUCT(S) TO OMEGA, PURCHASER MUST OBTAIN AN AUTHORIZED RETURN (AR) NUMBER FROM OMEGA'S CUSTOMER SERVICE DEPARTMENT (IN ORDER TO AVOID PROCESSING DELAYS). The assigned AR number should then be marked on the outside of the return package and on any correspondence.

The purchaser is responsible for shipping charges, freight, insurance and proper packaging to prevent breakage in transit.

FOR **WARRANTY** RETURNS, please have the following information available BEFORE contacting OMEGA:

1. Purchase Order number under which the product was PURCHASED,
2. Model and serial number of the product under warranty, and
3. Repair instructions and/or specific problems relative to the product.

FOR **NON-WARRANTY** REPAIRS, consult OMEGA for current repair charges. Have the following information available BEFORE contacting OMEGA:

1. Purchase Order number to cover the COST of the repair,
2. Model and serial number of the product, and
3. Repair instructions and/or specific problems relative to the product.

OMEGA's policy is to make running changes, not model changes, whenever an improvement is possible. This affords our customers the latest in technology and engineering.

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