
User's Guide



*<http://www.omega.com>
e-mail: info@omega.com*

OM-USCAN SERIES
Datalogger



OMEGAnetSM On-Line Service
<http://www.omega.com>

Internet e-mail
info@omega.com

**Servicing
North America:**

USA:
ISO 9001 Certified
One Omega Drive, Box 4047
Stamford, CT 06907-0047
Tel: (203) 359-1660
FAX: (203) 359-7700
e-mail: info@omega.com

Canada:
976 Bergar
Laval (Quebec) H7L 5A1
Tel: (514) 856-6928
FAX: (514) 856-6886
e-mail: canada@omega.com

**For immediate technical or
application assistance:**

USA and Canada:
Sales Service: 1-800-826-6342 /
1-800-TC-OMEGASM
Customer Service: 1-800-622-2378 /
1-800-622-BESTSM
Engineering Service: 1-800-872-9436 /
1-800-USA-WHENSM TELEX: 996404
EASYLINK: 62968934 CABLE: OMEGA

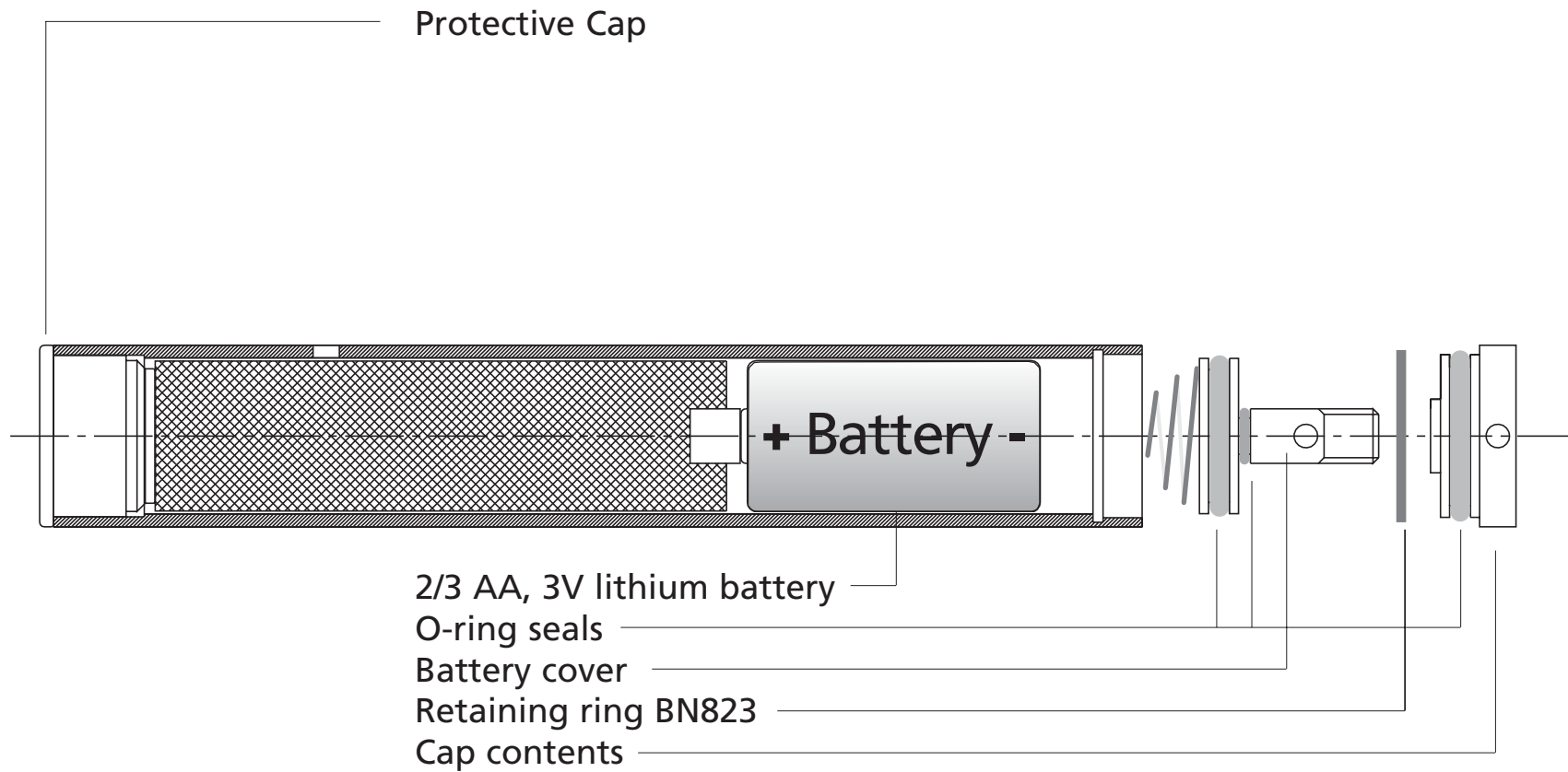
Mexico and Latin America:
Tel: (95) 800-TC-OMEGASM
FAX: (95) 203-359-7807
En Español: (203) 359-1660 ext: 2203
e-mail: espanol@omega.com

Contents

A	Datalogger Construction	4	4.8	Single-Channel Graphic	27
B	Specifications	5	4.81	Smooth and Zoom	29
C	Interface Specification	6	4.82	Display Mode	30
D	Accuracy of Measurement	7	4.821	Trace Settings	31
			4.822	Axis Settings	31
			4.823	Examples	32
1.	System Requirements	9	4.83	Inspect	33
2.	Installing the Software	9	4.84	Save ASCII	34
3.	Installing the Datalogger	10	4.9	Twin-Channel Graphic	35
			4.91	Mathem. Combinations	36
4.	Software	11	5.	Troubleshooting	37
4.1	Starting Up the Software	11	6.	Language Editor	38
4.2	Com Port	12		Index of Key Words	45
4.3	Test & Clear Data	15			
4.4	Put to Sleep	16			
4.5	Datalogger Identification	17			
4.6	Setup	20			
4.61	Active Sensor	21			
4.62	External Sensor	21			
4.63	Sampling Rate	21			
4.64	Delay	22			
4.65	Scanning	24			
4.7	Read Out	25			

A Datalogger Construction

Connection socket for interface and external sensors. We recommend that the protective cap is screwed on to protect the contacts.



B Specifications

Internal sensor	Precision high-temperature conductor (NTC) Range: -22°F to 158°F (-30°C to 70°C)
External sensor	Precision high-temperature conductor (NTC) Range: -40°F to 248°F (-40°C to 120°C) Interchangeability +/- 0.36°F (+/- 0.2°C) in the range from 32°F to 158°F (0°C to 70°C)
Memory	depth 64k words, 16 bits
Sampling interval	Single-channel: 10 seconds to 20 minutes in 9 steps Twin-channel: 20 seconds to 40 minutes in 9 steps Scan Mode: 16 seconds scanning interval
Recording period	3.87 days to 454.5 days
Time base Quartz	with ± 5 minutes/year deviation
Interface RS232	with 4800 Baud transmission speed
Data format	ASCII or binary (selectable)

Storage: 2/3 AA lithium battery, replaceable by the user.
Minimum life 2.5 years at 10 sec sampling rate.
In Sleep Mode 9 years (77°F / 25°C)

Recommended battery:
e.g. Sanyo Lithium CR 17335S, 3 V, 1700 mA at 77°F / 25°C
Working range: 32°F to 158°F (0°C to 70°C)
-40°F to 185°F (-40°C to 85°C)

Case: Stainless steel, watertight IP68, up to 10 bar pressure
above atmospheric

Shock: resistance: up to 300 g maximum

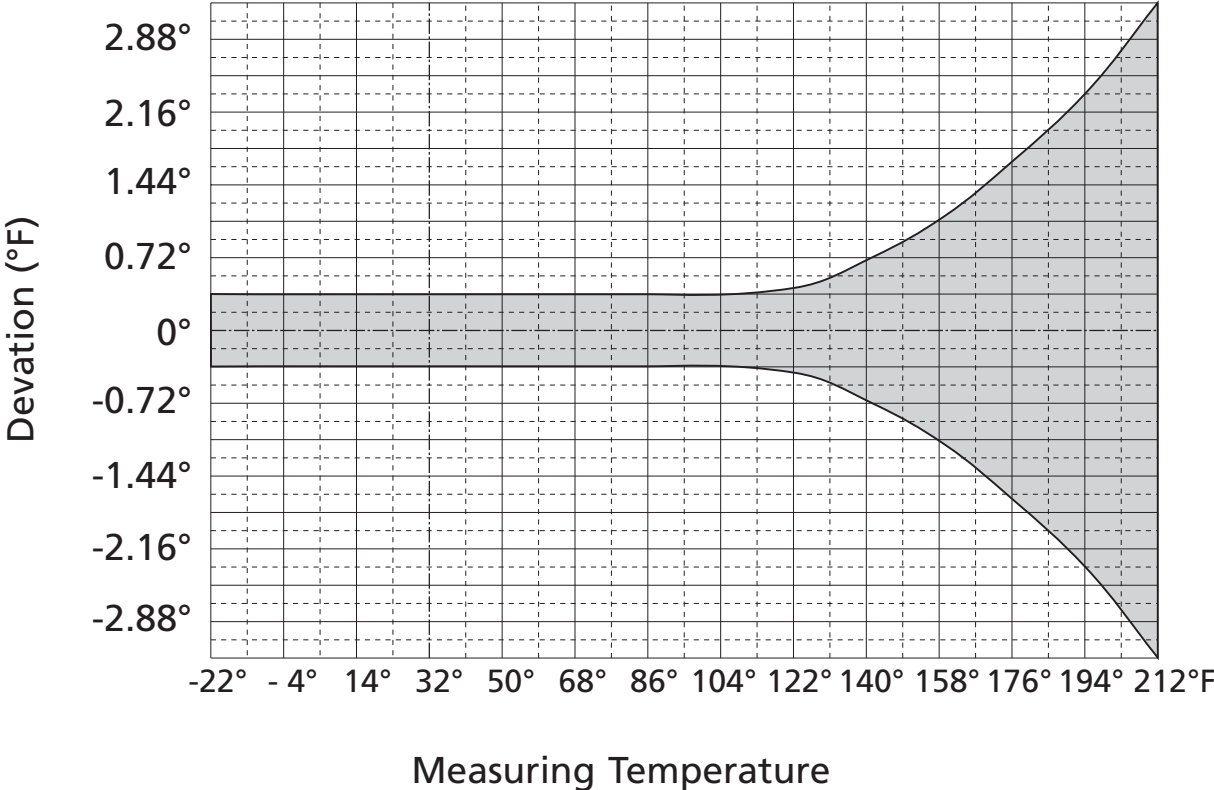
C Interface Specification

Interface: Connects to PC by 9-channel D-Sub sleeve plug

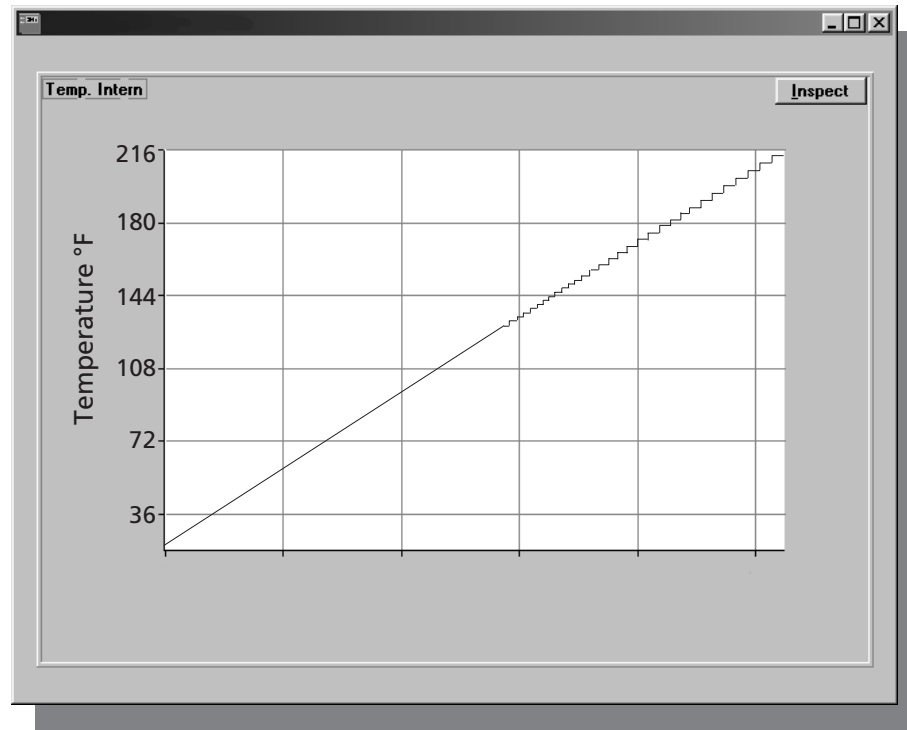
RS232: Baud rate: 4800 Baud, 8 bits, 1 stop bit, no parity
Scan Mode: 300 Baud. 8 bits, 1 stop bit, no parity

Batteries: 9 V E-Block (IEC: 6F22) alkaline or similar
Battery life 20 hours
Can run from external power source via 9 V universal
power unit regardless of the polarity.

D Accuracy of Measurement



The NTC measuring sensor is accurate to $\pm 0.36^{\circ}\text{F}$ ($\pm 0.2^{\circ}\text{C}$). Due to the negative temperature coefficients, the resistance increases exponentially at higher temperatures, and consequently even the high resolution of the data transducer is no longer sufficient to keep consistently to the accuracy of $\pm 0.36^{\circ}\text{F}$ ($\pm 0.2^{\circ}\text{C}$).



The diagram shows how resolution increases as temperature rises.

At -22°F (-30°C), the resistance is $177\text{k}\Omega$ and at 248°F (120°C) only $0.38\text{k}\Omega$. A change of temperature of 18°F (10°C) at -22°F (-30°C) causes a change of resistance of $80\text{k}\Omega$ and at 248°F , only $0.057\text{k}\Omega$.

1. System Requirements

IBM PC compatible PC 80386/33 or higher with minimum 8 MBytes RAM (Pentium with 16 MBytes recommended):

- SVGA graphics board, 640x480
- At least 5 MBytes available space on the hard disk
- a free communication port: COM1, COM2, COM3 or COM4 (RS232 port)
- Mouse to run the program easily
- Microsoft Windows 3.1 / Windows 95 / Windows 98 / Windows NT 4.0.

If using Microsoft Windows 3.11, please use the updated "Serial.386 Driver for Windows/TM for Workgroups Rev. Date 3/94".

2. Installing the Software

Windows 3.1x:

Start Windows. Open Program Manager and click on "File". In the "File" window, select "Run ...". Now insert the program floppy disk into drive A or B. In the "Run ..." command window write "A:setup" or, correspondingly, "B:setup" and confirm the entry with the "OK" button. If you are not selecting any other directory, confirm the directory recommended. Installation now proceeds automatically.

Windows 95 / 98 / NT4.0:

Start Windows. Click on "Start" and choose "Run". Insert floppy disk into drive A or B. In the "Run" command window write "A:\setup.exe" or "B:\setup.exe" and confirm the entry with the "Enter" key. If you are not selecting any other directory, confirm the directory recommended. Installation now proceeds automatically.

3. Installing the *Datalogger*

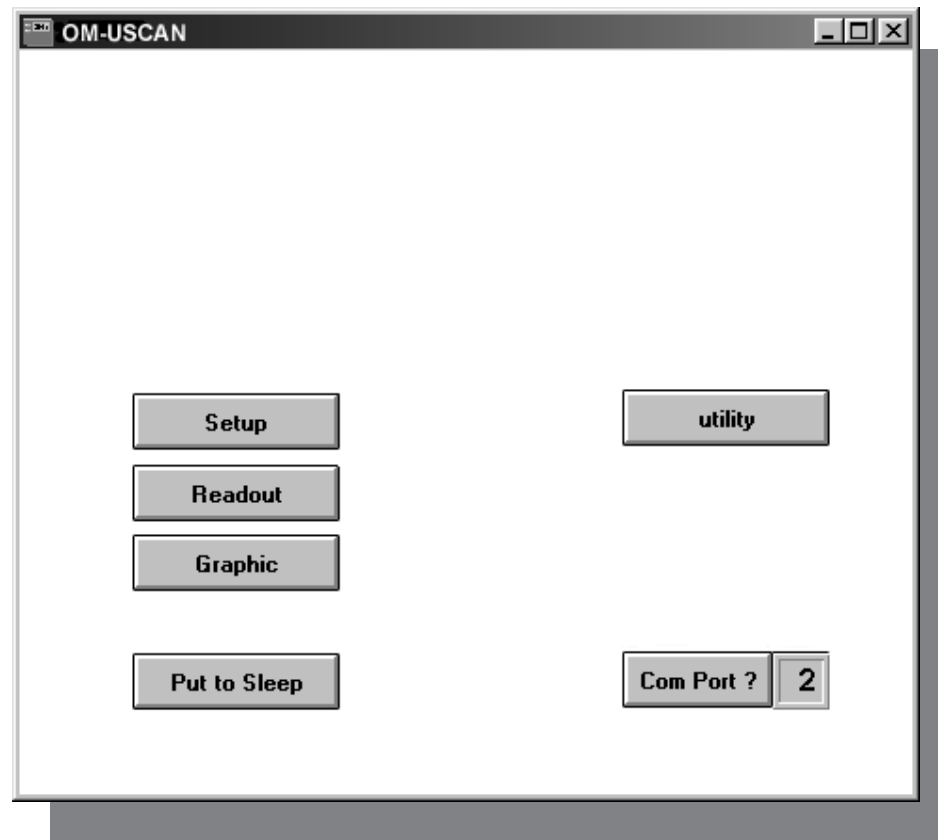
The *datalogger* can only be connected to the computer via the interface supplied. The interface ensures fast, reliable communication between the *datalogger* and the computer and does not take power from the *datalogger* battery. Connect the interface to a free Com Port using the cable supplied. Note the Com Port number to enable you to select it in the software. If your Com Port has a 25-channel plug, you will need a 25 to 9-pin D-Sub adapter, obtainable from any computer retailer.

N.B.: When you have connected the interface to the computer, switch the interface ON. The function is displayed by the red LED. Be sure to switch on the interface before connecting the *datalogger* to the interface. If you have already connected the *datalogger* by mistake, remove it and reconnect it with the interface switched on. If you do not follow this sequence, the *datalogger* battery is drained unnecessarily and communication between the computer and the *datalogger* is not possible. By following the setup sequence described, the *datalogger* is switched to its normal state when connected, and is thus ready for communication. In addition, the *datalogger* is supplied with power by the interface to meet the requirements of the interface.

4. Software

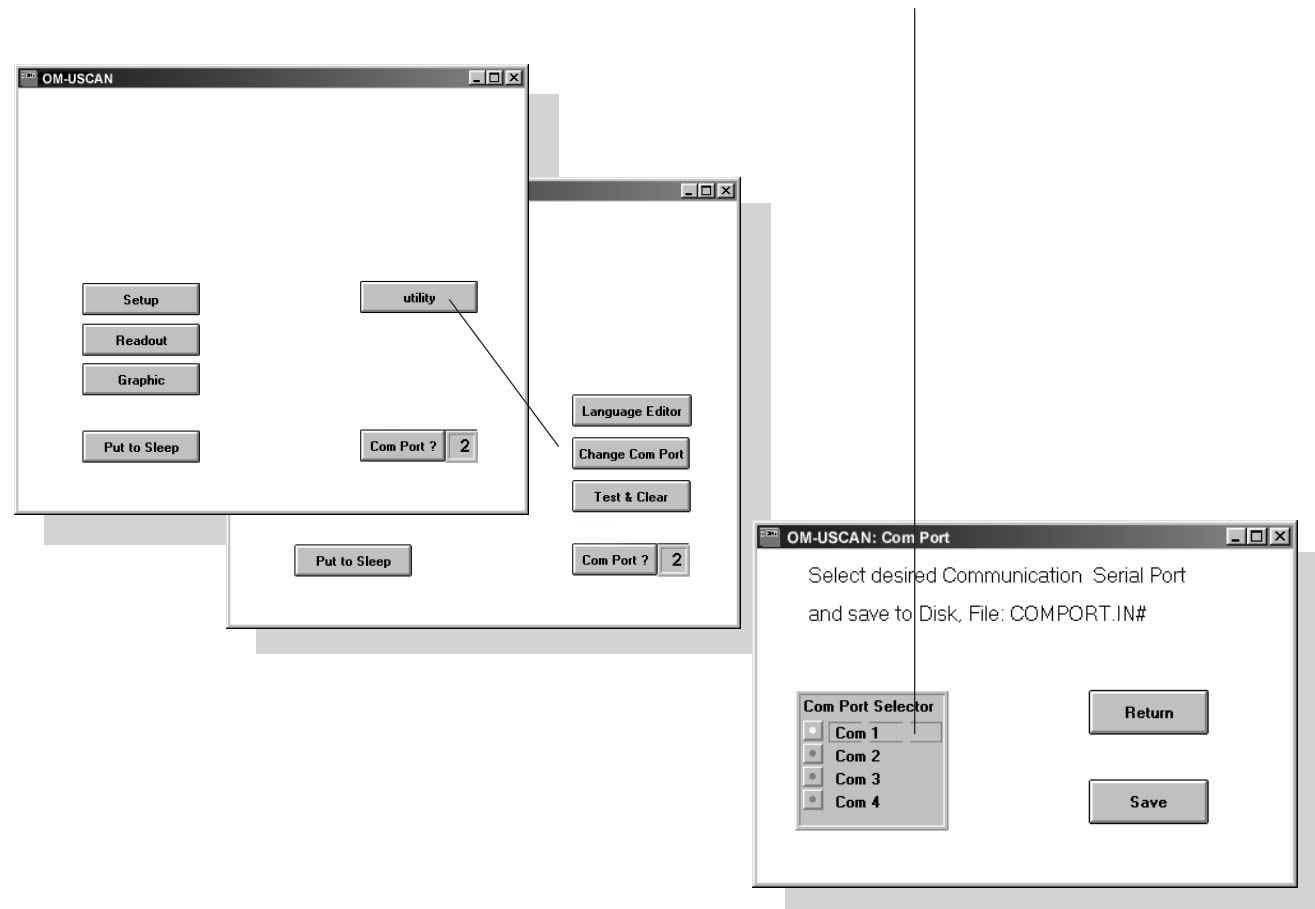
4.1 Starting Up the Software

When installing the software, the software opens a new program group in your Windows program with its own icon. Start the software by clicking twice on the icon. Once the software has been loaded, the software will display the following opening menu:

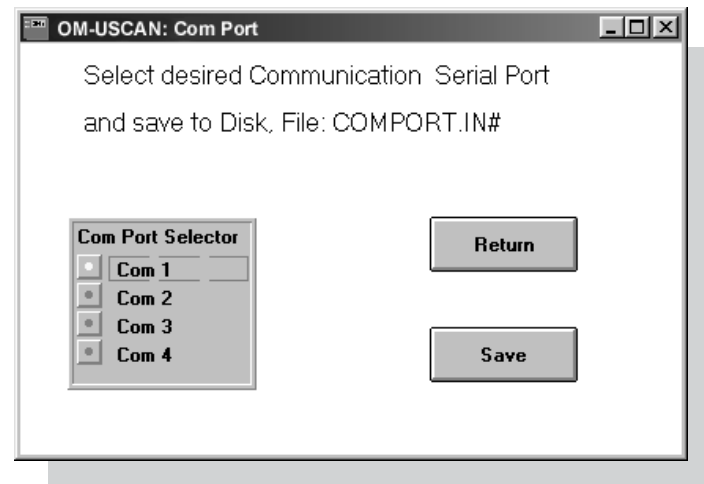


4.2 Com Port

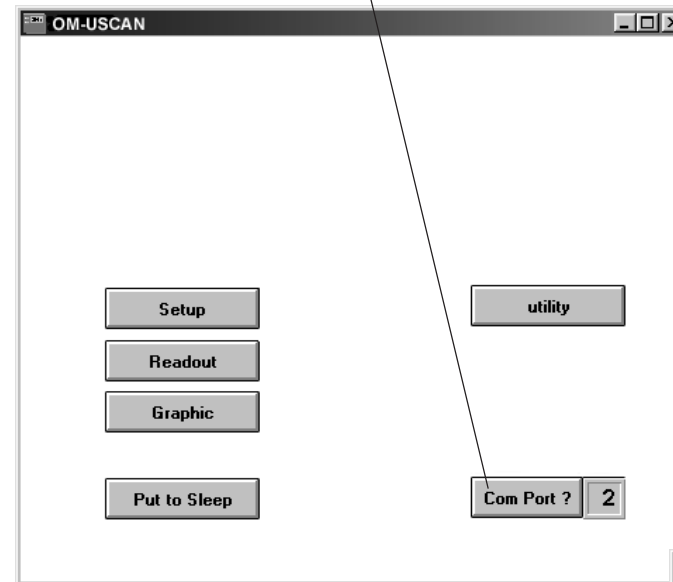
First select the Com Port to which you have connected the interface. To do this, move the mouse pointer to the appropriate "utility" key. This key will show you a new key "Change Com Port". Move again the mouse pointer to the "Change Com Port" key and activate the port by clicking with the mouse.



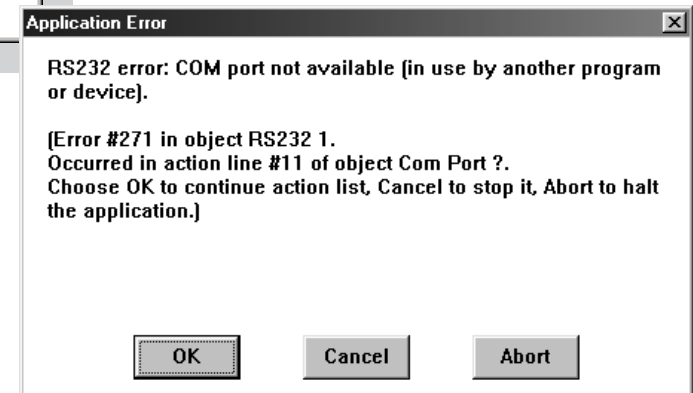
Save the selected Com Port by clicking on the "Save" key.



Return to the main window and activate the new Com Port by moving the mouse cursor to the "Com Port?" key and click on with the mouse.

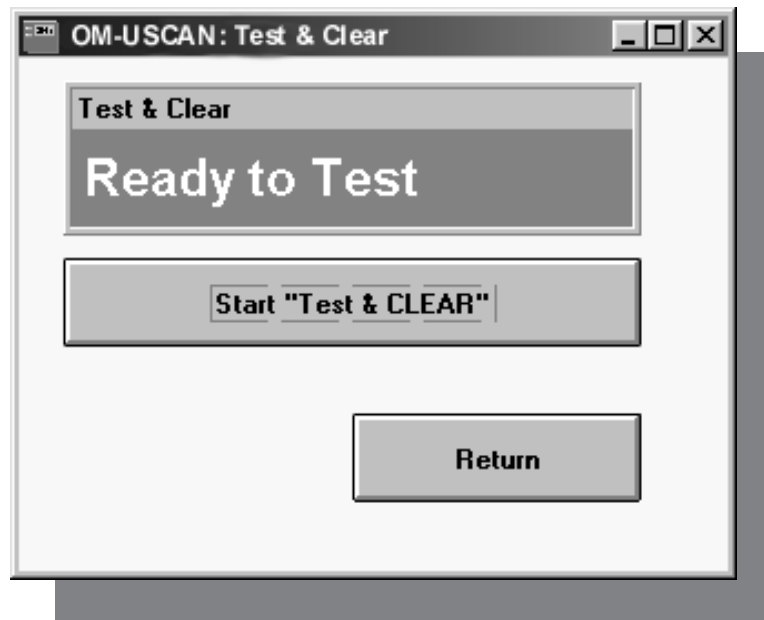


An error occurs, if the port is in use by another program or device. Please repeat the steps again and select the correct port.



4.3 Test & Clear Data

By clicking with the mouse on the “Test & Clear” key, you will start a ***datalogger*** test program, which tests the internal function of the ***datalogger***. This tests and then clears all the memory cells. Never use this program after capturing data with the ***datalogger***, because it would then be lost before evaluation. Start the program by clicking with the mouse on the “Test & Clear” key. The display shows the test status. Exit the test by clicking on the “Return to Main” key.



4.4 Put to Sleep

If you do not use the ***datalogger*** for some time, select the Sleep Mode to conserve the battery. When in Sleep Mode, the ***datalogger*** uses less than 17 μA . Start this program by activating the "Put to Sleep" key in the Main Menu and pressing this key again in the Submenu. Then disconnect the ***datalogger*** from the interface and put it aside.



To awake the ***datalogger*** again, reconnect it to the interface. The connection process reactivates the ***datalogger*** ready for communication.

4.5 Datalogger Identification

To start using the **datalogger**, the Setup program has to be started. Do this by clicking with the mouse on the "Setup" key in the Main Menu. This will open the "**OM-USCAN Setup**" window. This window contents two parts. One part is the **datalogger** identification with the serial number of the **datalogger**.

The screenshot shows the "OM-USCAN: SETUP" window. It is divided into two main sections: "OM-USCAN Identification" and "Recording Setup".

OM-USCAN Identification:

- Header1 (25Chr): [Text Input Field]
- Header2 (12Chr): [Text Input Field]
- Header3 (20Chr): [Text Input Field]
- Header4 (30Chr): [Text Input Field]
- Buttons: "Go to Main", "OM-USCAN S/N", "Accept Input"

Recording Setup:

- Sensor:** Radio buttons for Internal, External, Both, Scan.
- Ext. Sensor:** Radio buttons for No Sensor, [Empty].
- Meas. Intervall:** Radio buttons for 10 s (3.78), 20 s (7.57), 30 s (11.3), 1 min (22.7), 2 min (45.4), 5 min (113.6), 10 min (227.2), 15 min (340.8), 20 min (454.5).
- Current Day:** [Text Input Field]
- Start Delay:** Days (radio buttons <6, <4, <2, <0) and Hour (radio buttons <20, <10, <0).
- Buttons: "OM-USCAN Status" (with dots), "Start OM-USCAN"

The flexibility of the **datalogger** software allows you to create your own application header to indentify after data recording unequivocal your **datalogger**. (Please refer to part 6 Language Editor.) As an application example we created a header as follow:

First line: **Company**
Second line: **Driver**
Third line: **Container No.**
Fourth line: **Destination**

In the blank field on the right side you can enter now your desired infor-mation. Don't use the character "&", this character is used as a control character and will terminate any further input.

blank fields for data entry

OM-USCAN: SETUP

OM-USCAN Identification

Header1 (25Chr)

Header2 (12Chr)

Header3 (20Chr)

Header4 (30Chr)

Go to Main

OM-USCAN S/N

Accept Input

Recording Setup

Sensor

- Internal
- External
- Both
- Scan

Ext. Sensor

- No Sensor

Meas. Intervall

10 s	3.78
20 s	7.57
30 s	11.3
1 min	22.7
2 min	45.4
5 min	113.6
10 min	227.2
15 min	340.8
20 min	454.5

Current Day

Start Delay

Days

- +6
- +4
- +2
- +0

Hour

- +20
- +10
- +0

OM-USCAN Status

Start OM-USCAN

Example:

Meas. Intervall	
10 s	3.78
20 s	7.57
30 s	11.3
1 min	22.7
2 min	45.4
5 min	113.6
10 min	227.2
15 min	340.8
20 min	454.5

confirm entry

To charge the **datalogger** with the header information you have to click with the mouse on the "Accept Input" key. If you start the **datalogger** without confirmation, the old header is kept in memory. To test the content of a previous header please go to the "Readout" menu. This menu will show you the present header. If you like to keep it unchanged, go directly to the **datalogger** setup menu without confirmation by the "Accept Input" key. The software charges now the **datalogger** with the data and afterwards reads out the data for correctness test.

4.6 Datalogger Setup

The second part of the setup window is intended to charge the **datalogger** with recording parameters as sampling-time-intervals, kind of sensor used, start delay and timing mark.

To select the setup conditions you will find the corresponding information under following items:

4.61 Active Sensor

4.62 External Sensor

4.63 Sampling Rate

4.64 Start Delay in Days
start Hour

The screenshot shows the 'OM-USCAN: SETUP' window. It is divided into two main sections: 'OM-USCAN Identification' and 'Recording Setup'.

OM-USCAN Identification:

- Header1 (25Chr): Company
- Header3 (20Chr): Container No.
- Header2 (12Chr): Driver
- Header4 (30Chr): Destination
- Buttons: 'Go to Main', 'Accept Input', and 'Start OM-USCAN'.
- OM-USCAN S/N: 100123
- OM-USCAN Status:

Recording Setup:

- Sensor:** Radio buttons for Internal, External, Both, and Scan. 'Internal' is selected.
- Ext. Sensor:** Radio buttons for No Sensor and Scan. 'No Sensor' is selected.
- Meas. Intervall:** A list of options with corresponding values:

10 s	3.78
20 s	7.57
30 s	11.3
1 min	22.7
2 min	45.4
5 min	113.6
10 min	227.2
15 min	340.8
20 min	454.5
- Current Day:** Time 09 : 57 : 58
- Start Delay:** Two spinners for 'Days' (range 0 to 16) and 'Hour' (range 0 to 20). Both are set to 0.
- Buttons: 'Start OM-USCAN'.

4.61 Active Sensor

The ***datalogger*** can operate either with the built-in sensor or an external sensor or with both sensors in parallel. If data are recorded by two sensors, the memory capacity is halved and the sampling intervals doubled.

Use the "Active Sensor" window to select whether you want to measure with the built-in sensor or an external sensor. The external sensor should be connected to the plug after starting up the ***datalogger***. If you want to measure with both at once, use the mouse to select the "Both" key.

You will find information about the "Scanning Mode" under 4.65

4.62 External Sensor

If you are working with two sensors at the same time, the "External Sensor" window will offer "Temperature".

4.63 Sampling Rate

Use this window to select the measuring interval, i.e. the intervals of time at which you want to record data. The total recording time (in days) may be read alongside the Sampling Rate. Measuring can be halted at any time, however.

4.64 Delay

A "Start Delay" can be selected by using the Sliders for "Start Hour" and "Day Delay". As starting time the next full time period of the indicated actual time will be used. If you select for example 12 as "Start Hour" and the "Actual Time" is 09:20:54, the "Start Delay" will be 02:39:06. If the value of "Start Hour" is less than the "Actual Time", no start delay will be added. In this case, 1 day must be added.

OM-USCAN Identification

Header1 (25Chr)
Company

Header3 (20Chr) Container No. Header2 (12Chr) Driver

Header4 (30Chr)
Destination

OM-USCAN S/N
100123

Go to Main

Accept Input

Recording Setup

Sensor
 Internal
 External
 Both
 Scan

Ext. Sensor
 No Sensor

Meas. Intervall

<input type="radio"/> 10 s	3.78
<input type="radio"/> 20 s	7.57
<input type="radio"/> 30 s	11.3
<input type="radio"/> 1 min	22.7
<input type="radio"/> 2 min	45.4
<input type="radio"/> 5 min	113.6
<input type="radio"/> 10 min	227.2
<input type="radio"/> 15 min	340.8
<input type="radio"/> 20 min	454.5

Current Day
Time 09 : 57 : 58

Start Delay

Days
Slider: 0 to 16 (value: 0)

Hour
Slider: 0 to 20 (value: 0)

OM-USCAN Status
.....

Start OM-USCAN

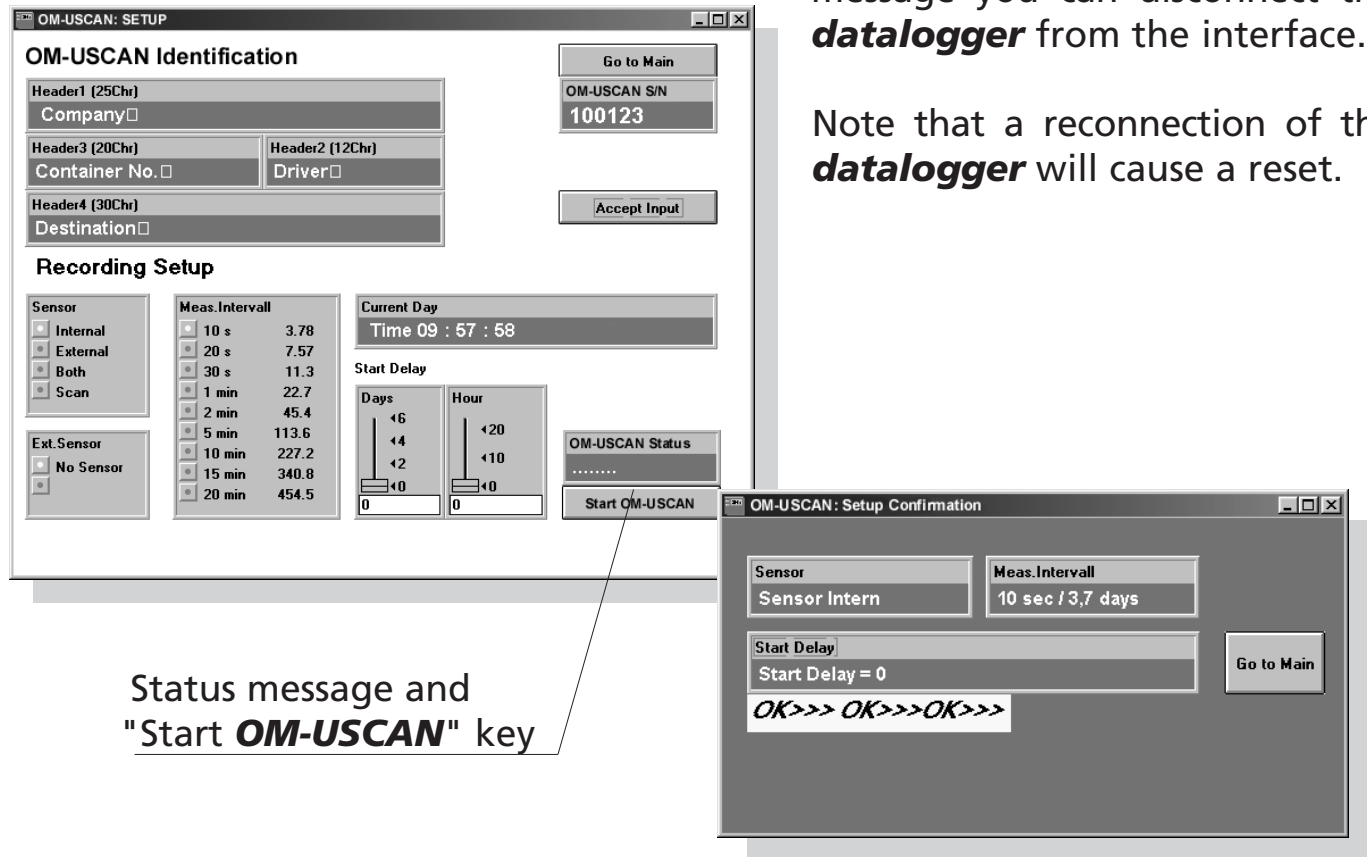
Start Delay in Days

Start Hour

Once you have checked all the inputs, the **datalogger** can be programmed and started by means of the "Start **OM-USCAN**" key. To be quite sure that the communication and start sequence has been successful, the **datalogger** software shows you the status of communication and state of the **datalogger**. When the **datalogger** is in measuring mode a window opens and show the "**OM-USCAN** Setup confirmation". The display indicates "OK>>>OK>>>OK>>>....". After this message you can disconnect the

datalogger from the interface.

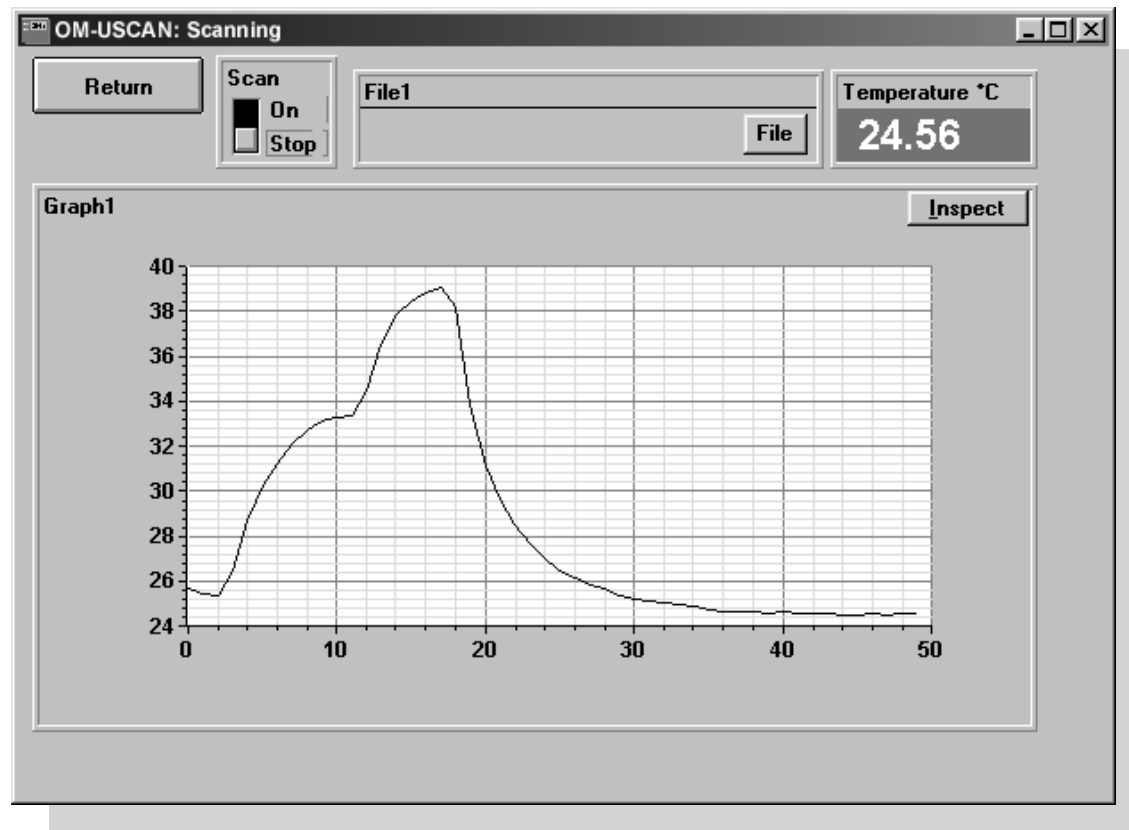
Note that a reconnection of the **datalogger** will cause a reset.



Status message and "Start **OM-USCAN**" key

4.65 Scanning

Direct scanning of data is possible by using an external sensor. In this mode the **datalogger** must be connected to the interface and the sensor must be linked up to the corresponding socket. The scanning program communicates directly to the **datalogger** by using a baud rate of 300 baud. The sampling interval is 16 seconds. Please use the "Scan Stop" switch to halt scanning. The **datalogger** can be resetted by reconnection.



4.7 Read Out

When measuring has been completed or is halted, you can read out the data by means of this part of the program and store it on hard disk or floppy.

The screenshot shows a window titled "OM-USCAN: READOUT" with the following content:

OM-USCAN Identifications Data

Header1		Serial No.	Return
<input type="checkbox"/> Company		100123	
Header2	Header3		
Driver	Container No.		
Header4			
Destination			

OM-USCAN Setup Conditions

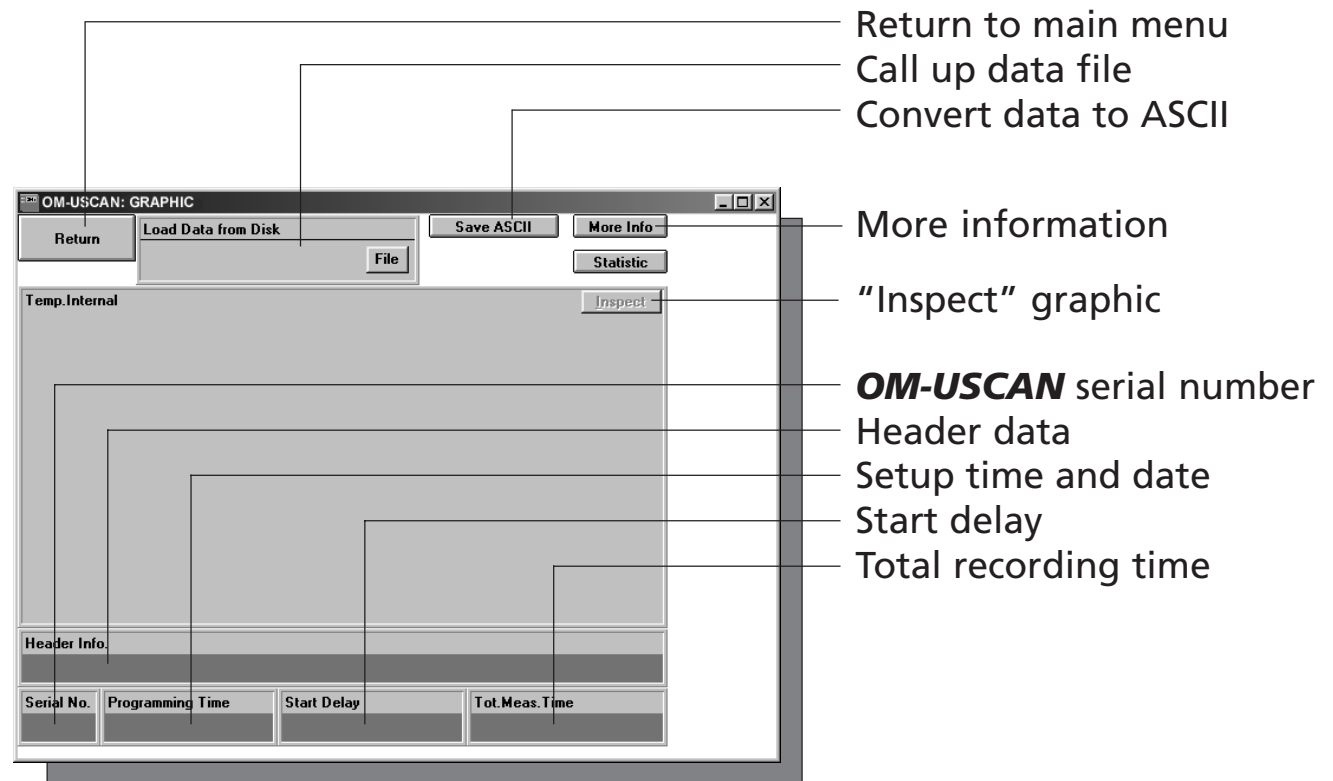
Sensor	Ext. Sensor	Save Data
Internal	Temperature	
Setup Time	Sampl. Interval	File
10:59:06 23/04/99	10 s	
Start Delay		
0		

The "Read Out" window gives you details of the **datalogger** identification, the recording mode and start of measuring.

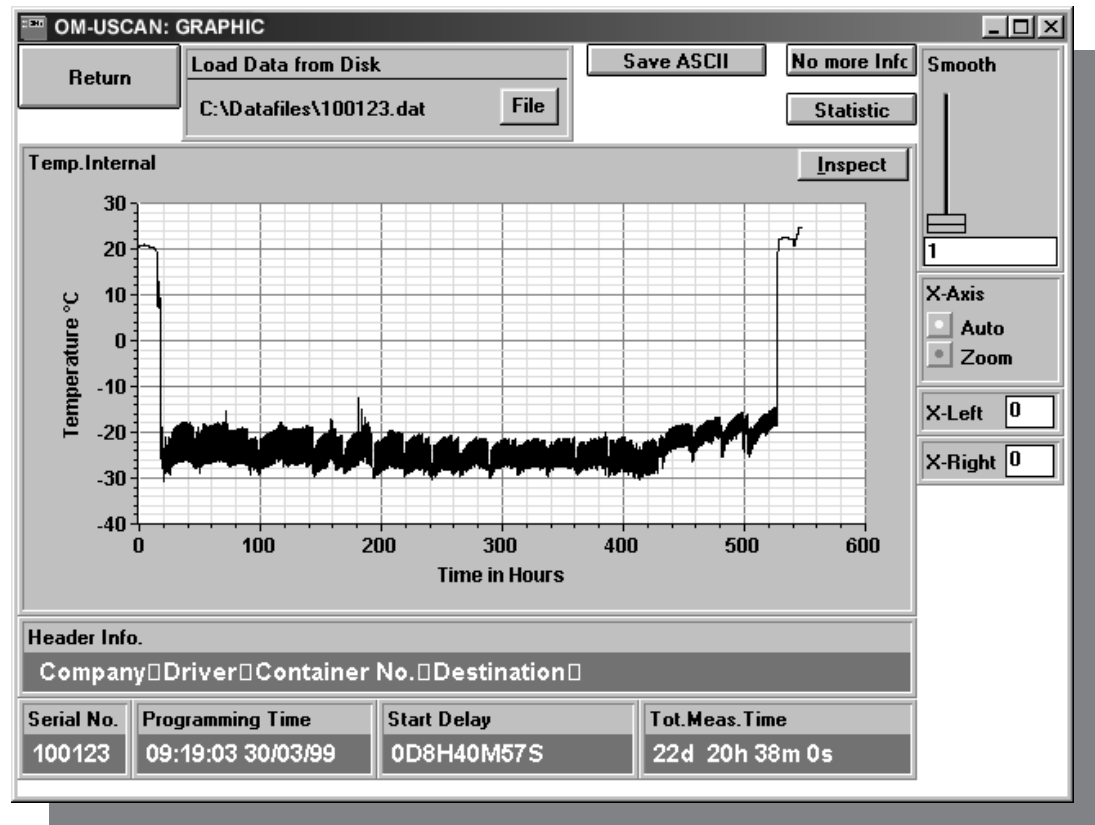
If you want to transfer and store data from the ***datalogger***, click with the mouse on the "File" key. Give the recorded trace a name under which you will be able to find it again easily in Graphic. As soon as the PC starts the read out process, the green LED on the interface lights up, indicating that data are being output by the ***datalogger***. Data transfer may take up to 10 minutes, depending on the quantity of data. When the green LED goes out, transfer is completed. You can only proceed the evaluation by clicking with the mouse on the "Graphic" key.

4.8 Single-Channel "Graphic"

The Graphic program allows you to represent the data stored beforehand graphically. The main operating features with a single-channel display are shown in the illustration below. (see 4.8 for two-channel display)

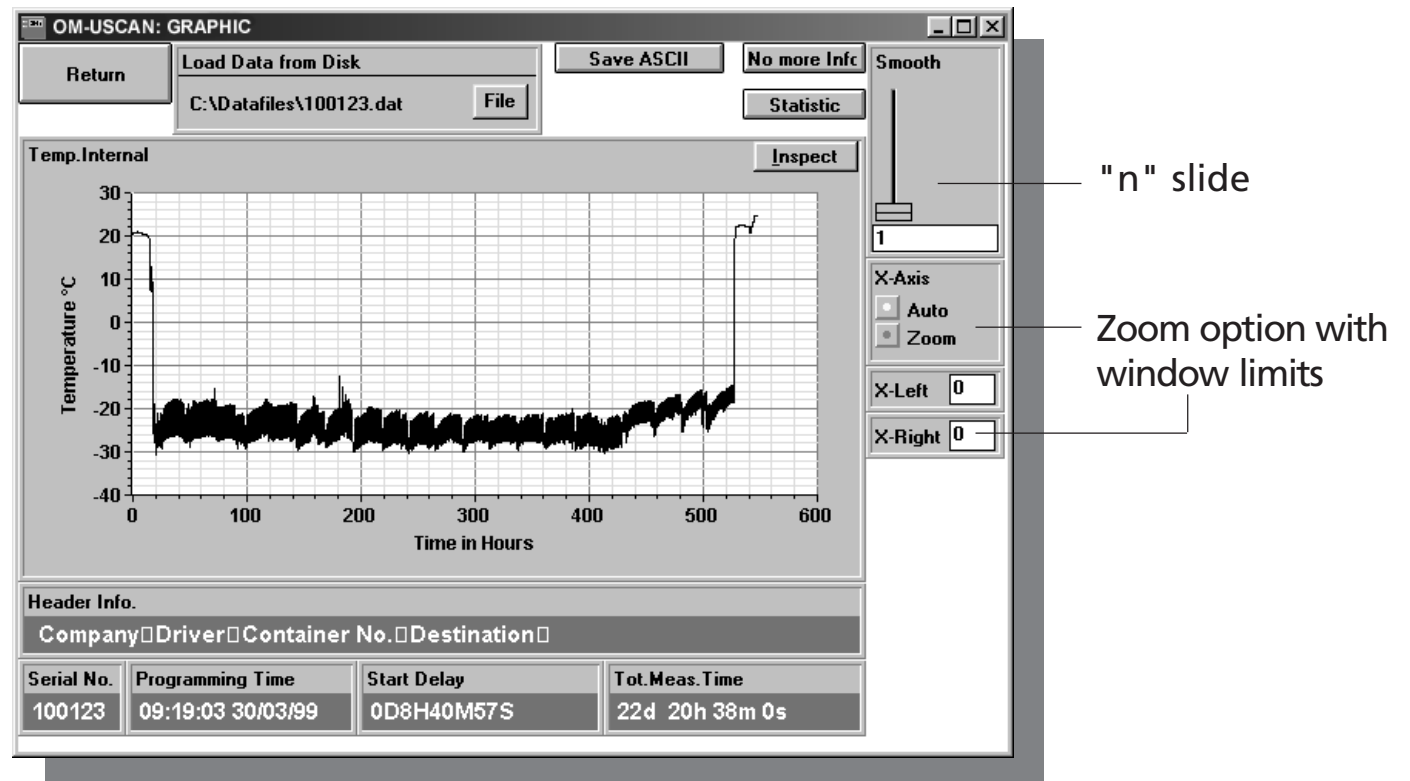


Click with the mouse on the File window and select a Data File. This may take some time, depending on the quantity of data. If the raw data have been linearized, the following screen will appear:



4.81 Smooth and Zoom

The Smooth function allows you to smooth the data. This is done by using "n" points around the actual point to form an average. Use the mouse to move the slide between n=1 and 100. The smooth function will not be activated until you call up the data file again. Same worth for the zoom function. Select the zoom button and the zoom limits as a window and recall the file.

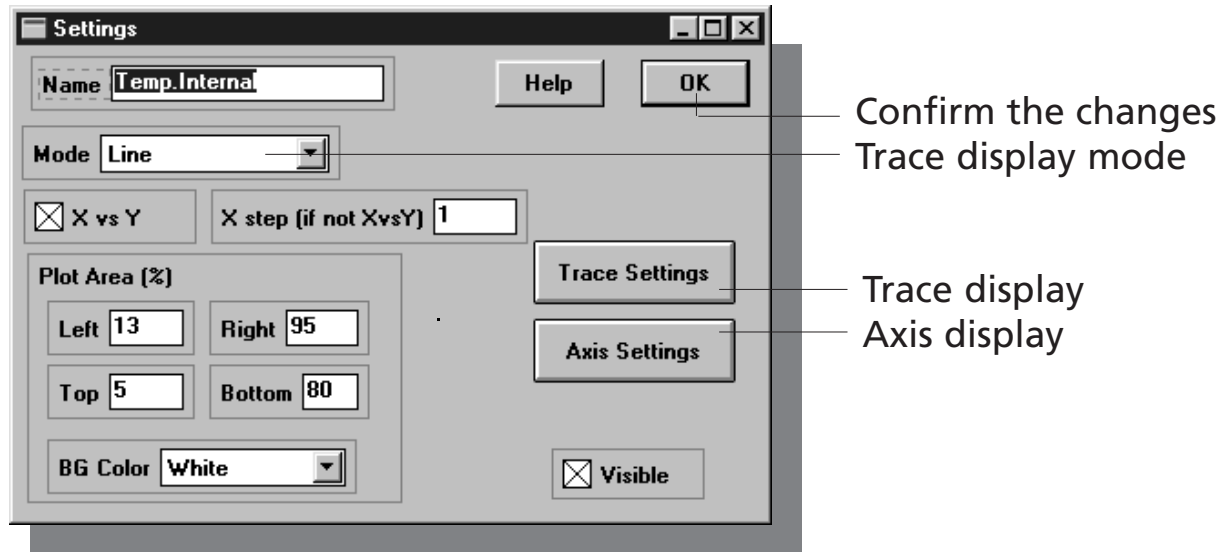


"n" slide

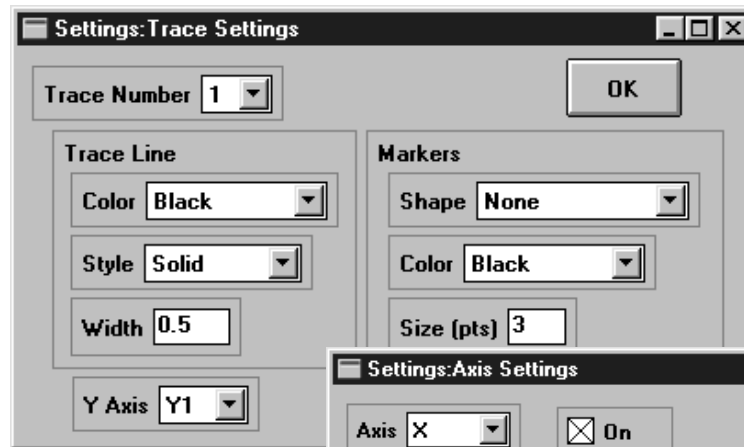
Zoom option with window limits

4.82 Display Mode

By clicking twice on Graphic you can change various display parameters:

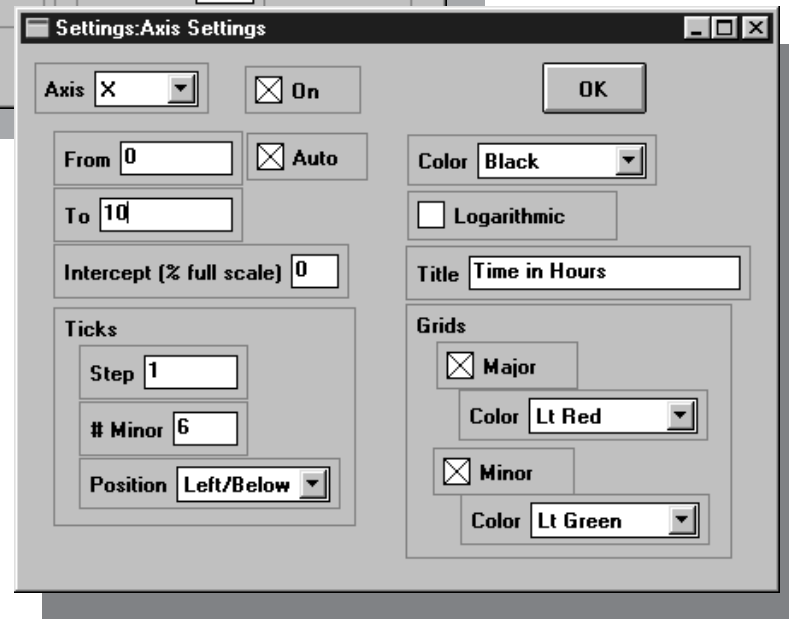


4.821 Trace Settings

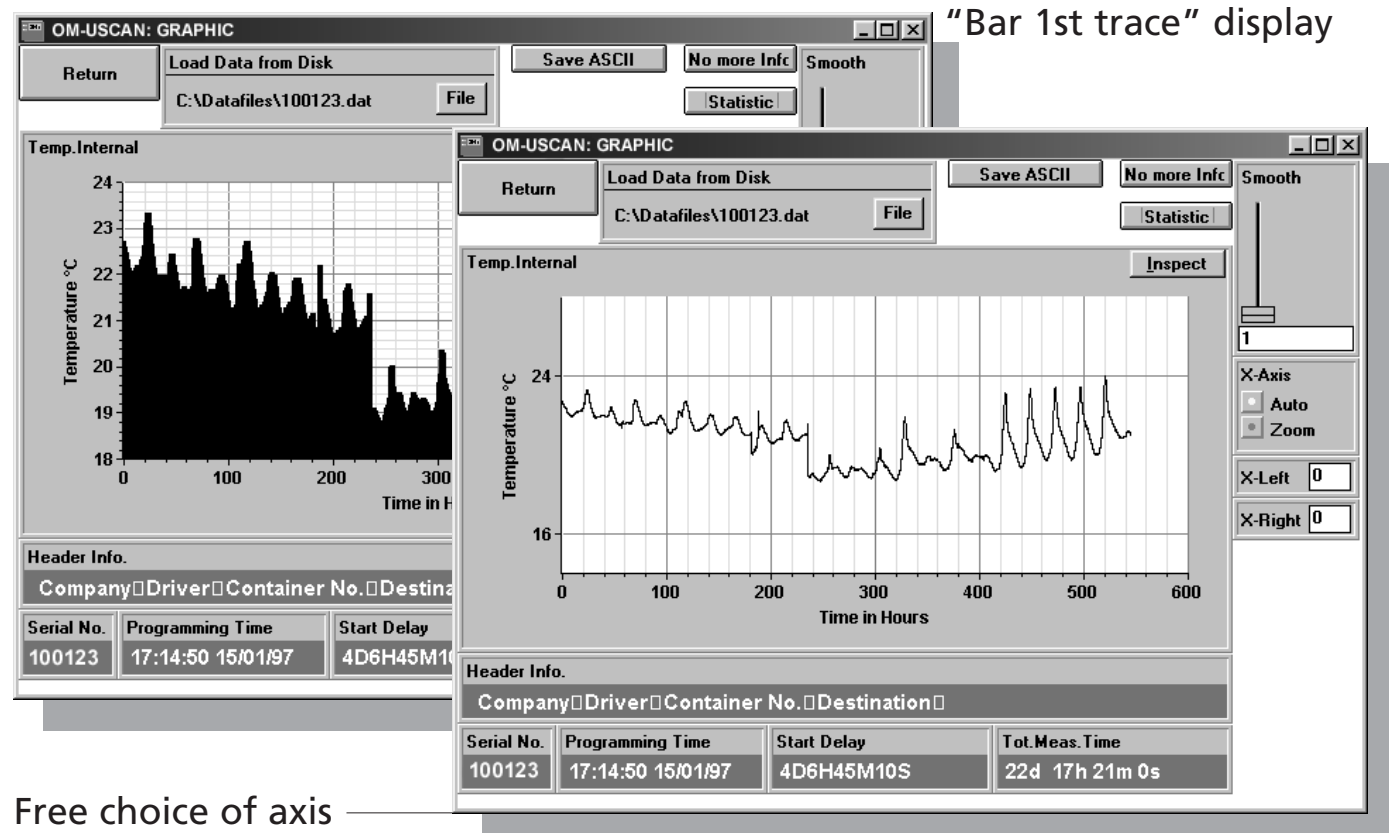


These windows allow you to change the colour of the axes and traces and also the grid interval and trace section.

4.822 Axis Settings



4.823 Examples



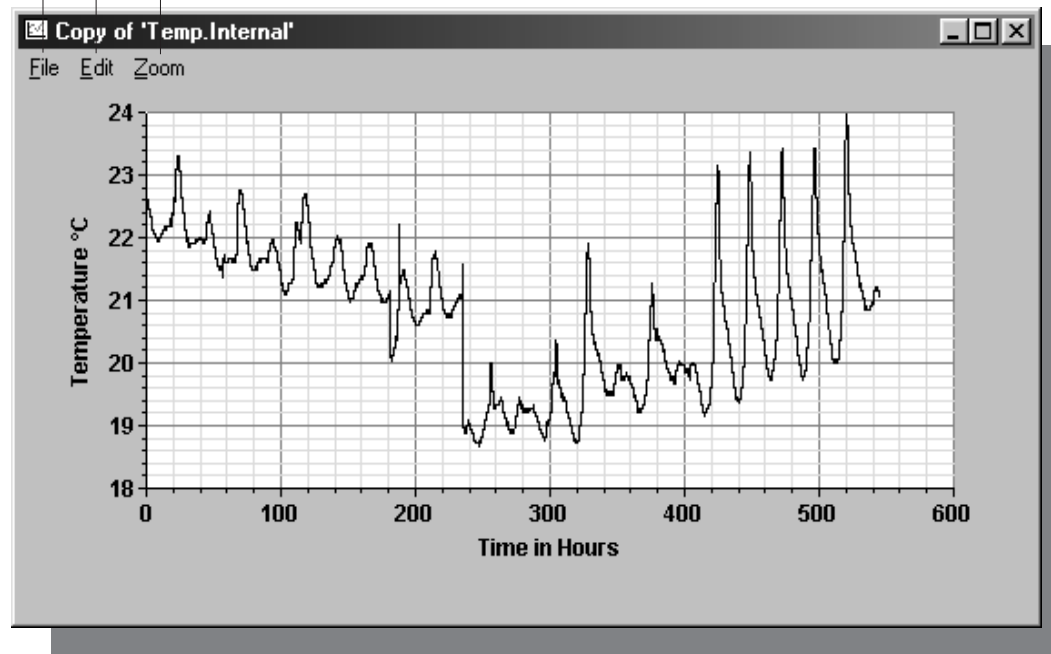
4.83 "Inspect"

The "Inspect" window allows you to enlarge and reduce sections.

"File": print the diagram

"Edit": export the diagram

"Zoom": enlarge and reduce the section



4.84 "Save ASCII"

This function linearizes the raw data and stores them in ASCII, allowing these data to be further processed by any programs. The first few lines look like this:

Single-channel

X	Y
0.05	5.038
0.053	5.199
0.056	5.362
0.058	5.519
0.061	5.626
0.064	5.764
0.067	5.88
0.069	5.961
0.072	6.035
0.075	6.138
0.078	6.197
0.081	6.243
0.083	6.303
0.086	6.34
0.089	6.37
0.092	6.416
0.094	6.446
0.097	6.469
0.1	6.521

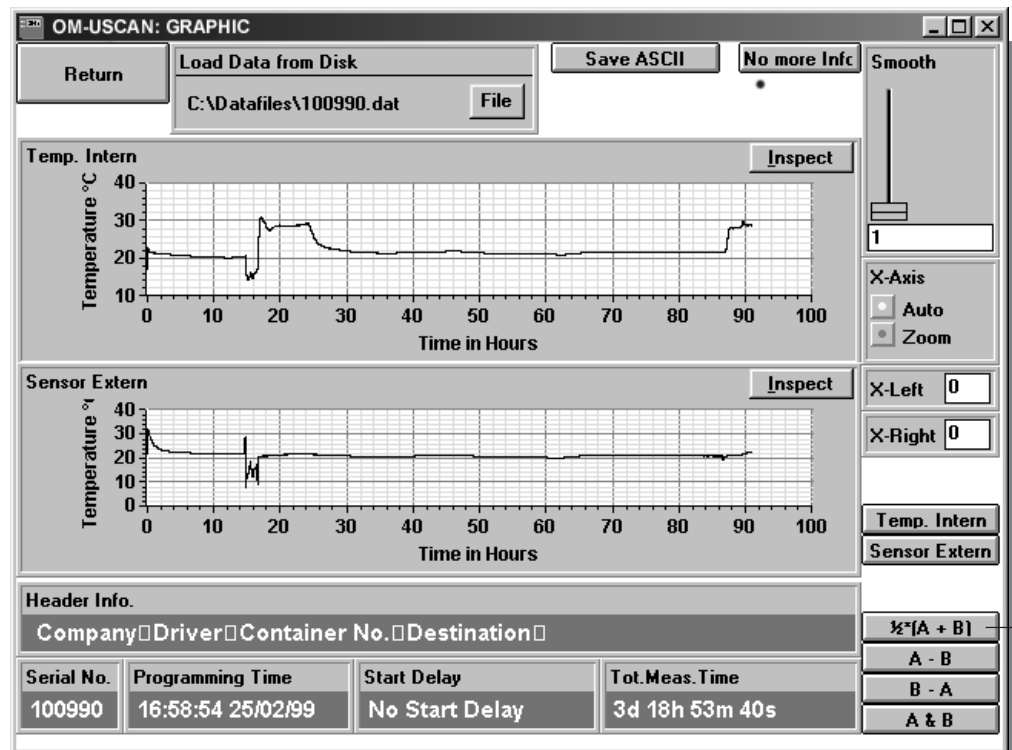
X = time axis in hours
Y = ordinate in °C

Twin-channel

X	Y1	Y2
0.003	26.234	25.368
0.006	26.396	25.375
0.008	26.485	25.375
0.011	26.567	25.375
0.014	26.567	25.298
0.017	26.485	25.298
0.019	26.485	25.222
0.022	26.485	68.745
0.025	26.508	70.381
0.028	26.59	68.745
0.031	26.598	72.141
0.033	26.688	78.259
0.036	26.793	88.388
0.039	26.922	82.412
0.042	26.412	5.795
0.044	24.61	-4.578
0.047	22.803	-9.084
0.05	20.825	-11.265
0.053	18.91	-12.442

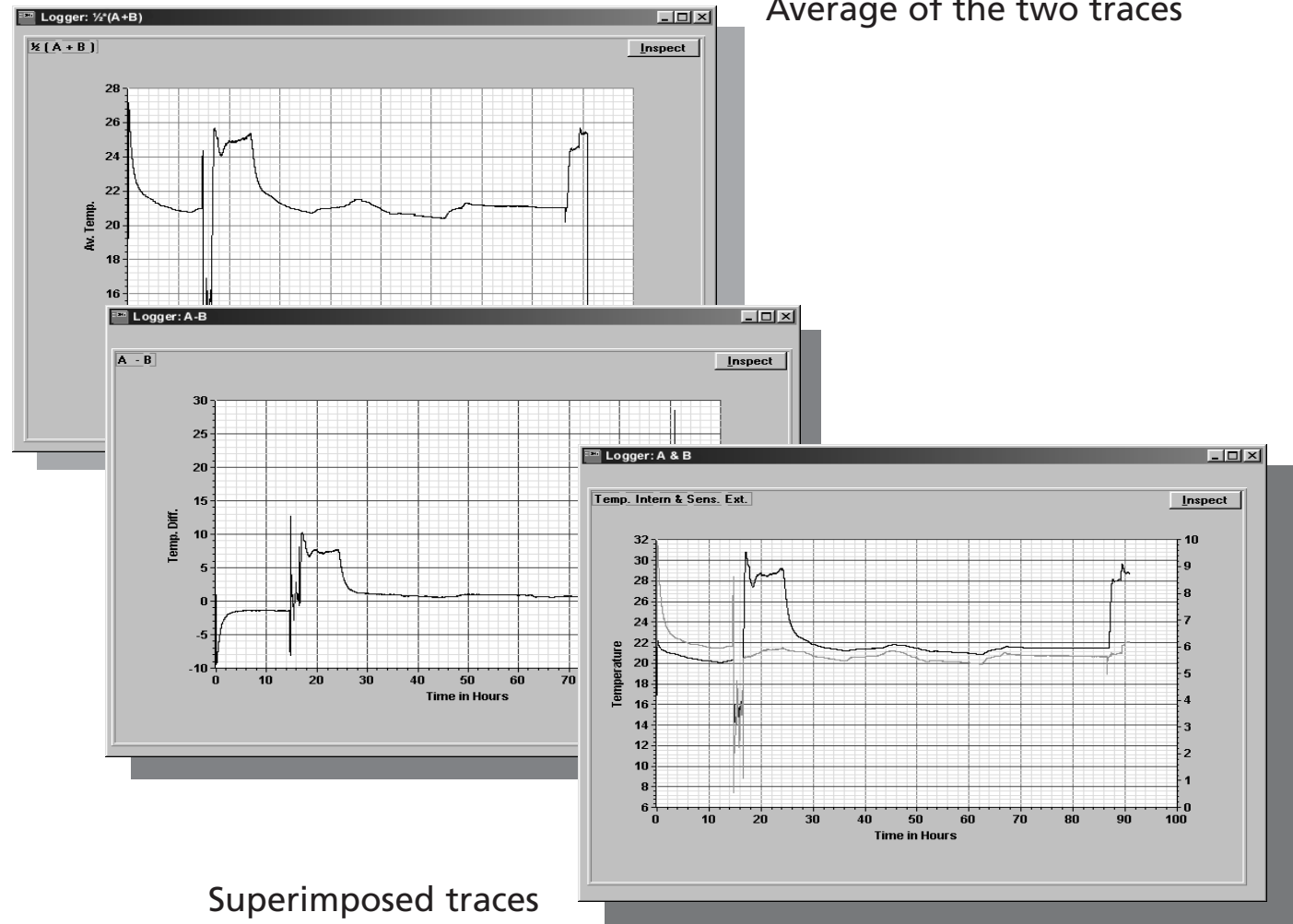
4.9 Twin-Channel "Graphic"

If you have recorded data with both, the internal and the external sensor, Graphic will automatically display them in two separate diagrams. The operating features are different from those in the single-channel display and mathematical combinations for the two traces have been added to allow connections to be made visible.



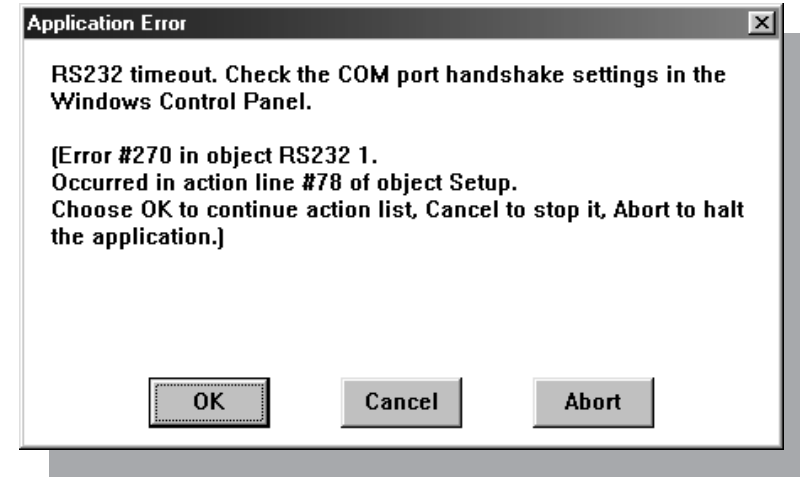
Operation for
mathematical
combinations.

4.91 Mathematical Combinations



5. Troubleshooting

Wrong Com Port.
Time Out Delay: 10 seconds



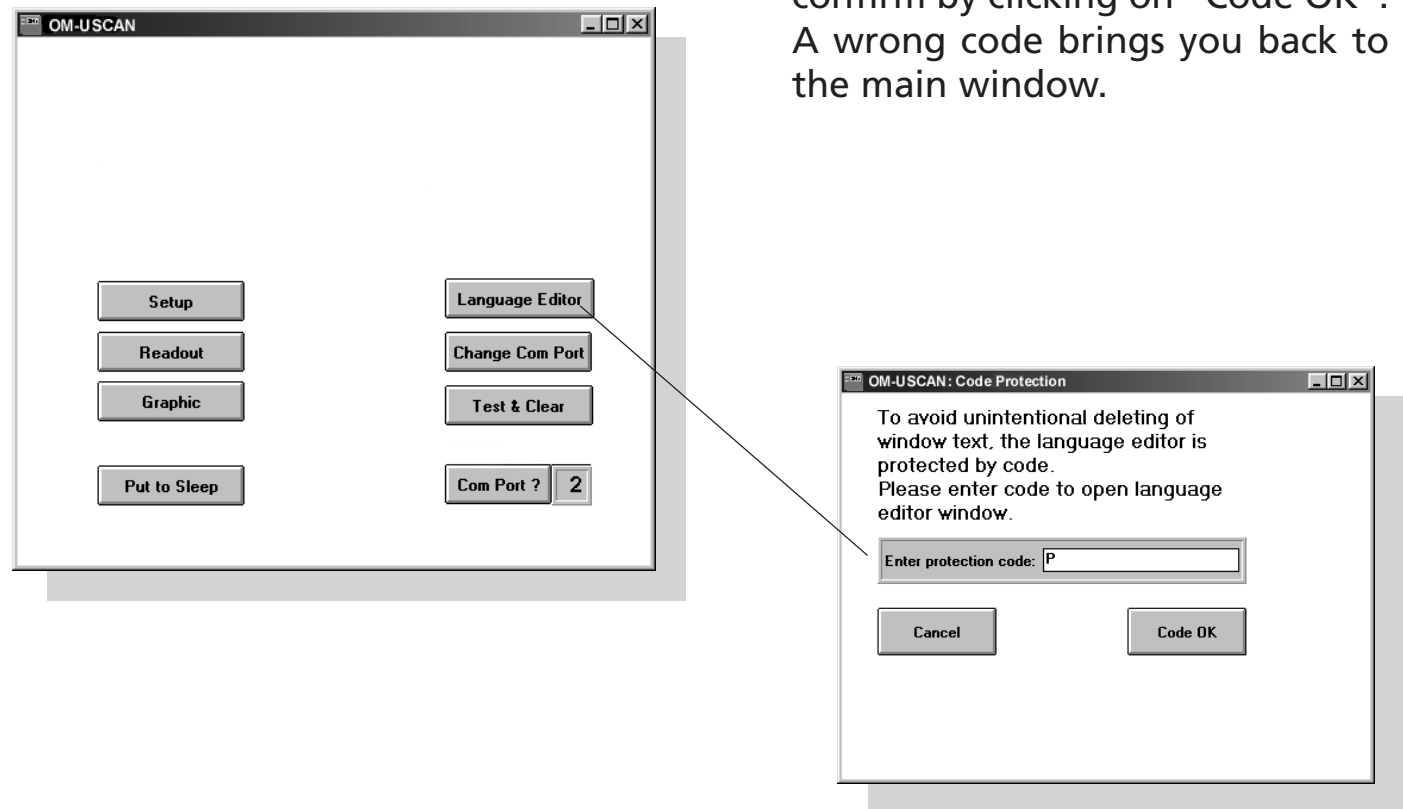
This message appears if the PC cannot communicate with the ***datalogger***.
The reasons may be the following:

- Wrong COM Port selected:
 - => check the COM Port
 - => check the RS232 cable

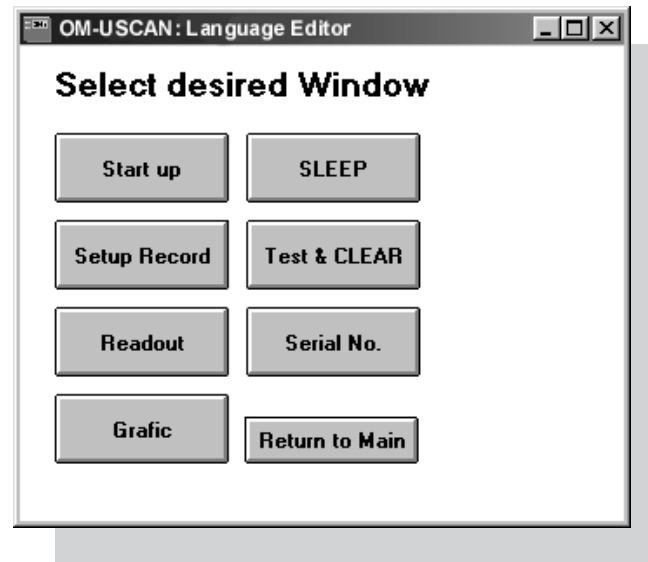
- The ***datalogger*** is not in communication mode:
 - => check if the interface is switched on and reconnect the ***datalogger*** to the interface for resetting.
 - => check the 9 Volt Battery of the interface.

6. Language Editor

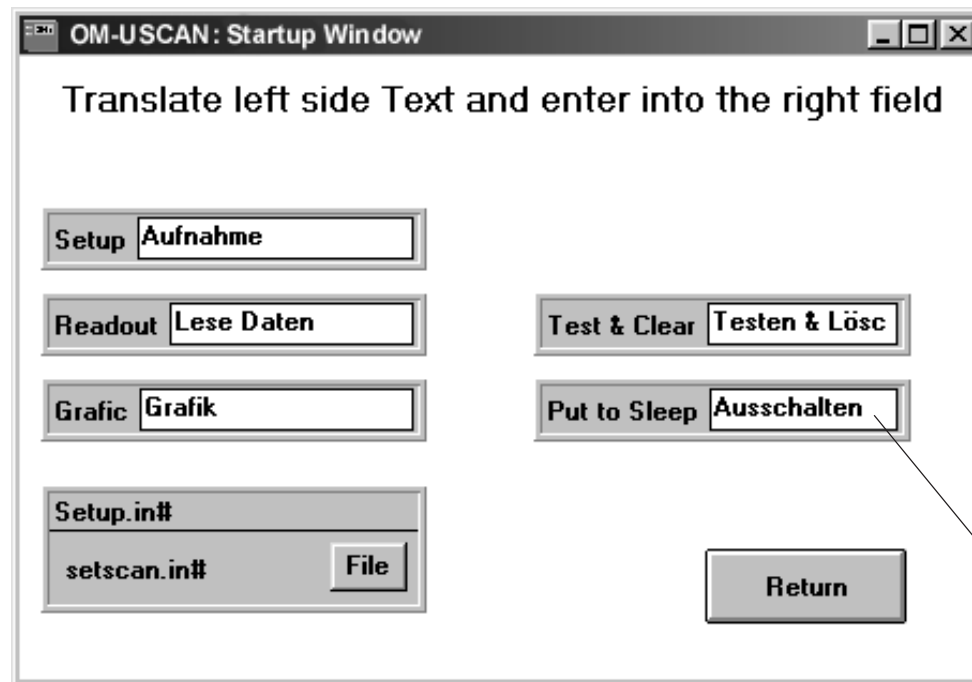
The **OM-USCAN** Software give you the possibility to change the key words in any window. So you can adapt the program exactly to your needs. The language editor can only be opened by a protection code in order to prevent any unauthorized and unintentional manipulation of existing key words. Open the language editor by the appropriate key word and confirm by clicking on "Code OK". A wrong code brings you back to the main window.



The right code opens a new window where you can select the window you like to modify.



When you open for example the Startup window you can see several blank fields right of the English key words. In this field you can enter now your desired key words. Do not terminate your entry by a carriage return, change only with the mouse to the next field. Blank fields will be displayed in the window as blank. If you only like to make correction on some fields, please use an ordinary text editor. After all fields have been labeled, move the mouse cursor to "File".

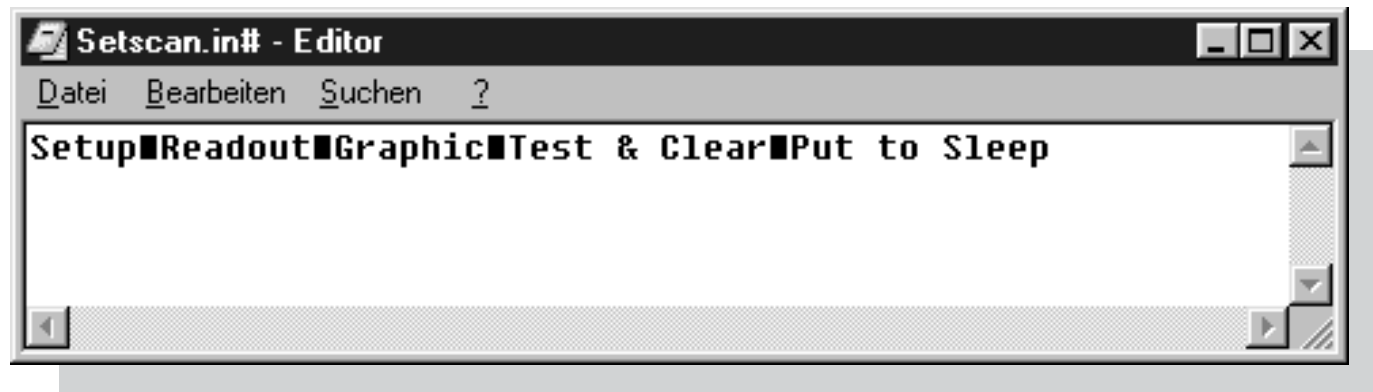


The data will be saved under "setscan.in#". Do not change the file name.

Now you can test the setup window by clicking with the mouse on the "Return" key in order to go back to the main window.

Any text and language can be entered into these fields.

If you find now any error in the text it is unnecessary to go back to the language editor and fill out all fields again. A simpler way is to use the editor from Windows. Change to the Program-Manager and click twice on the "Editor" icon. Open the directory, where you have installed the **OM-USCAN** software. Open the file "setscan.in#".



Now you can modify and correct all text between the "█". Do not clear the "█" control characters. After correction please save the data under same file. Then go back to the **OM-USCAN** software and test the changes.

The language editor is subdivided into the following windows:

Window	Use
- Start up	Main-Window
- Setup Record	Setup the <i>datalogger</i> for data recording
- Readout	Readout the recorded data from <i>datalogger</i>
- Graphic	Show the recorded data in a graphic
- Sleep	Put <i>datalogger</i> into sleep mode to save power
- Test & Clear	Test <i>datalogger</i> communication and function

For each window a separated data file exists. This enables simpler handling of language data. The relation between the different windows and data files is as follows:

Window	File
- Start up	setscan.in#
- Setup Record	record.in#
- Readout	readout.in#
- Graphic	grafic.in#
- Sleep	sleep.in#
- Test & Clear	t&c.in#

As you have seen you can modify and correct any **OM-USCAN** window and translate to the destination language. The most important window is the setup window where you can adapt your needs for header. Four lines are available for the header. If you use the language editor all lines must be filled in. But if you only like to modify "Header 1" to "Header 4", it's simpler to use the Windows Editor to change the four lines.

Header 1
Header 2
Header 3
Header 4

The screenshot shows the 'OM-USCAN: SETUP' window. It is divided into two main sections: 'OM-USCAN Identification' and 'Recording Setup'.

OM-USCAN Identification: This section contains four text input fields labeled 'Header1 (25Chr)', 'Header2 (12Chr)', 'Header3 (20Chr)', and 'Header4 (30Chr)'. To the right of these fields are three buttons: 'Go to Main', 'OM-USCAN S/N', and 'Accept Input'.

Recording Setup: This section is further divided into several sub-sections:

- Sensor:** A group box containing radio buttons for 'Internal', 'External', 'Both', and 'Scan'.
- Ext. Sensor:** A group box containing radio buttons for 'No Sensor'.
- Meas. Intervall:** A list of measurement intervals with corresponding values:

10 s	3.78
20 s	7.57
30 s	11.3
1 min	22.7
2 min	45.4
5 min	113.6
10 min	227.2
15 min	340.8
20 min	454.5
- Current Day:** A text input field.
- Start Delay:** Two vertical sliders for 'Days' and 'Hour'. The 'Days' slider has values 0, <2, <4, <6. The 'Hour' slider has values 0, <10, <20.
- OM-USCAN Status:** A group box containing a status indicator (dots) and a 'Start OM-USCAN' button.

To modify the four header lines, please open the "record.in#" file.
In this file you see, where the header information is placed:

Header 4 _____
Header 3 _____
Header 2 _____
Header 1 _____

```
OM-USCAN Identification█Company█Driver█Container No.█Destination█  
OM-USCAN Setup Condition█Sensor█Interval,External,Both,Scan Mode█  
Ext. Sensor█No Sensor, ;Temperature,Humidity;Ext.only, ;█Return█  
OM-USCAN Serial No.█Actual Date/Time█Start Delay█Days█Start Hour█  
No Delay█OM-USCAN Status█Waiting█Measuring█Input O.K.█Set Start Delay█  
Sampl.Interval█
```

Now change with the editor the header info, for example:

```
OM-USCAN Identification█User Name█Street█City█Country█  
OM-USCAN Setup Condition█Sensor█Interval,External,Both,Scan Mode█  
Ext. Sensor█No Sensor, ;Temperature,Humidity;Ext.only, ;█Return█  
OM-USCAN Serial No.█Actual Date/Time█Start Delay█Days█Start Hour█  
No Delay█OM-USCAN Status█Waiting█Measuring█Input O.K.█Set Start Delay█  
Sampl.Interval█
```

Do not touch any " , ; █ " . They are used as controlling characters.
Finally save the file and restart the software.

Index of Key words

- A**
Accuracy of measurement 7
Active sensor 20, 21
Actual time 22
Awake the Datalogger 16
Axis display 30
Axis settings 31
- B**
Batteries 6
Battery 10
Battery cover 4
Blank fields for data entry 18
- C**
Call up data file 27
Case 6
Change Com Port 12
Character "&" 18
Code 39
Com Port 10, 12
Com Port? 14
Confirm the changes 30
Connection socket 4
Construction 4
- Contents 3
Convert data to ASCII 27
Correct all text 41
- D**
Data format 5
Day delay 22
Delay 22
Difference 36
Direct scanning 24
Display mode 30
Display parameters 30
Driver for Windows 9
- E**
Editor from Windows 41
Enlarge and reduce the section 33
Export the diagram 33
External Sensor 5, 20, 21
- G**
Grafic.in# 42
Graphic, grafic.in# 42
Graphic program 27
Grid 31
- H**
Header 18, 43
Header data 27
Header information 19
- I**
Identification 25
Input O.K. 19
Inspect 33
Inspect graphic 27
Installing the Datalogger 10
Installing the software 9
Interchangeability of sensor 5
Interface 6
interface light 26
Interface RS232 5
Interface specification 6
Internal sensor 5
- L**
Language editor 38
- M**
Manipulation of existing key words 38
Mathematical combinations 35, 36

Measuring interval 21
Memory 5
Moisture 21
More information 27

O

O-ring seals 4

P

Parameters 30
Polarity 6
Previous header 19
Print the diagram 33
Program manager 9
Protective cap 4
Put to sleep 16

Q

Quartz 5

R

Read out 25
Readout, readout.in# 42
Readout.in# 42
Record.in# 42, 44
Recording period 5

Recording time 21
Resistance 8
Retaining ring 4
RS232 6

S

Sampling interval 5, 21, 24
Sampling Rate 20, 21
Sampling-time-interval 20
Save ASCII 34
Scan mode 5
Scan stop 24
Scanning 24
Select a data file 28
Serial number 17, 27
Serial. 386 driver 9
Setscan.in# 42
Setup 20
Setup record, record.in# 42
Setup time and date 27
Shock 6
Single-channel 5
Single-channel display 27
Single-channel "Graphic" 27
Sleep, sleep.in# 42

Sleep Mode 16
Sleep.in# 42
Smooth and zoom 29
Smooth function 29
Software 11
Specification 5
Start delay 22, 27
Start delay in days 20
Start hour 20, 22
Start up, setscan.in# 42
Starting up the software 11
Status message 23
Storage 6
Strip Chart display 32
Superimpose 36
System requirements 9

T

t&c.in# 42
Temperature 21
Test & clear, t&c.in# 42
Test & clear data 15
Time base 5
Total recording time 27
Trace display 30

Trace display mode 30
Trace settings 31
Transfer and store data 26
Troubleshooting 37
Twin-channel "Graphic" 35
Twin-channel: 5

U

Universal power unit 6

W

Wrong Com Port 37

Z

Zoom button 29

WARRANTY/DISCLAIMER

OMEGA ENGINEERING, INC. warrants this unit to be free of defects in materials and workmanship for a period of **25 months** from date of purchase. OMEGA Warranty adds an additional one (1) month grace period to the normal **two (2) year product warranty** to cover handling and shipping time. This ensures that OMEGA's customers receive maximum coverage on each product.

If the unit should malfunction, it must be returned to the factory for evaluation. OMEGA's Customer Service Department will issue an Authorized Return (AR) number immediately upon phone or written request. Upon examination by OMEGA, if the unit is found to be defective it will be repaired or replaced at no charge. OMEGA's WARRANTY does not apply to defects resulting from any action of the purchaser, including but not limited to mishandling, improper interfacing, operation outside of design limits, improper repair, or unauthorized modification. This WARRANTY is VOID if the unit shows evidence of having been tampered with or shows evidence of being damaged as a result of excessive corrosion; or current, heat, moisture or vibration; improper specification; misapplication; misuse or other operating conditions outside of OMEGA's control. Components which wear are not warranted, including but not limited to contact points, fuses, and triacs.

OMEGA is pleased to offer suggestions on the use of its various products. However, OMEGA neither assumes responsibility for any omissions or errors nor assumes liability for any damages that result from the use of its products in accordance with information provided by OMEGA, either verbal or written. OMEGA warrants only that the parts manufactured by it will be as specified and free of defects. OMEGA MAKES NO OTHER WARRANTIES OR REPRESENTATIONS OF ANY KIND WHATSOEVER, EXPRESSED OR IMPLIED, EXCEPT THAT OF TITLE, AND ALL IMPLIED WARRANTIES INCLUDING ANY WARRANTY OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE HEREBY DISCLAIMED. LIMITATION OF LIABILITY: The remedies of purchaser set forth herein are exclusive and the total liability of OMEGA with respect to this order, whether based on contract, warranty, negligence, indemnification, strict liability or otherwise, shall not exceed the purchase price of the component upon which liability is based. In no event shall OMEGA be liable for consequential, incidental or special damages.

CONDITIONS: Equipment sold by OMEGA is not intended to be used, nor shall it be used: (1) as a "Basic Component" under 10 CFR 21 (NRC), used in or with any nuclear installation or activity; or (2) in medical applications or used on humans. Should any Product(s) be used in or with any nuclear installation or activity, medical application, used on humans, or misused in any way, OMEGA assumes no responsibility as set forth in our basic WARRANTY/DISCLAIMER language, and additionally, purchaser will indemnify OMEGA and hold OMEGA harmless from any liability or damage whatsoever arising out of the use of the Product(s) in such a manner.

Where Do I Find Everything I Need for Process Measurement and Control? OMEGA...Of Course!

TEMPERATURE

- ☑ Thermocouple, RTD & Thermistor Probes, Connectors, Panels & Assemblies
- ☑ Wire: Thermocouple, RTD & Thermistor
- ☑ Calibrators & Ice Point References
- ☑ Recorders, Controllers & Process Monitors
- ☑ Infrared Pyrometers

PRESSURE, STRAIN AND FORCE

- ☑ Transducers & Strain Gauges
- ☑ Load Cells & Pressure Gauges
- ☑ Displacement Transducers
- ☑ Instrumentation & Accessories

FLOW /LEVEL

- ☑ Rotameters, Gas Mass Flowmeters & Flow Computers
- ☑ Air Velocity Indicators
- ☑ Turbine/Paddlewheel Systems
- ☑ Totalizers & Batch Controllers

pH/CONDUCTIVITY

- ☑ pH Electrodes, Tester & Accessories
- ☑ Benchtop/Laboratory Meters
- ☑ Controllers, Calibrators, Simulators & Pumps
- ☑ Industrial pH & Conductivity Equipment

DATA ACQUISITION

- ☑ Data Acquisition & Engineering Software
- ☑ Communications-Based Acquisition Systems
- ☑ Plug-in Cards for Apple, IBM & Compatibles
- ☑ Datalogging Systems
- ☑ Recorders, Printers & Plotters

HEATERS

- ☑ Heating Cable
- ☑ Cartridge & Strip Heaters
- ☑ Immersion & Band Heaters
- ☑ Flexible Heaters
- ☑ Laboratory Heaters

ENVIRONMENTAL MONITORING AND CONTROL

- ☑ Metering & Control Instrumentation
- ☑ Refractometers
- ☑ Pumps & Tubing
- ☑ Air, Soil & Water Monitors
- ☑ Industrial Water & Wastewater Treatment
- ☑ pH, Conductivity & Dissolved Oxygen Instruments

M - 3327

Servicing Europe:

Benelux:

Postbus 8034, 1180 LA Amstelveen,
The Netherlands
Tel: (31) 20 6418405 FAX: (31) 20 6434643
Toll Free in Benelux: 06 0993344
e-mail: nl@omega.com

Czech Republic:

Ostravska 767, 733 01 Karvina
Tel: 42 (69) 6311899 FAX: 42 (69) 6311114
e-mail: czech@omega.com

France:

9, rue Denis Papin, 78190 Trappes
Tel: (33) 130-621-400 FAX: (33) 130-699-120
Toll Free in France: 0800-4-06342
e-mail: france@omega.com

Germany/Austria:

Daimlerstrasse 26, D-75392
Deckenpfronn, Germany
Tel: 49 (07056) 3017 FAX: 49 (07056) 8540
Toll Free in Germany: 0130 11 21 66
e-mail: germany@omega.com

United Kingdom: ISO 9002 Certified

- 25 Swannington Road, Broughton Astley,
Leicestershire, LE9 6TU, England
Tel: 44 (1455) 285520 FAX: 44 (1455) 283912
 - P.O. Box 7, Omega Drive, Irlam,
Manchester, M44 5EX, England
Tel: 44 (161) 777-6611 FAX: 44 (161) 777-6622
- Toll Free in England: 0800-488-488
e-mail: uk@omega.com

It is the policy of OMEGA to comply with all worldwide safety and EMC/EMI regulations that apply. OMEGA is constantly pursuing certification of its products to the European New Approach Directives. OMEGA will add the CE mark to every appropriate device upon certification.

The information contained in this document is believed to be correct but OMEGA Engineering, Inc. accepts no liability for any errors it contains, and reserves the right to alter specifications without notice.

WARNING: These products are not designed for use in, and should not be used for, patient connected applications.

RETURN REQUESTS / INQUIRIES

Direct all warranty and repair requests/inquiries to the OMEGA Customer Service Department. BEFORE RETURNING ANY PRODUCT(S) TO OMEGA, PURCHASER MUST OBTAIN AN AUTHORIZED RETURN (AR) NUMBER FROM OMEGA'S CUSTOMER SERVICE DEPARTMENT (IN ORDER TO AVOID PROCESSING DELAYS). The assigned AR number should then be marked on the outside of the return package and on any correspondence.

The purchaser is responsible for shipping charges, freight, insurance and proper packaging to prevent breakage in transit.

FOR WARRANTY RETURNS, please have the following information available BEFORE contacting OMEGA:

1. P.O. number under which the product was PURCHASED,
2. Model and serial number of the product under warranty, and
3. Repair instructions and/or specific problems relative to the product.

FOR NON-WARRANTY REPAIRS, consult OMEGA for current repair charges. Have the following information available BEFORE contacting OMEGA:

1. P.O. number to cover the COST of the repair,
2. Model and serial number of product, and
3. Repair instructions and/or specific problems relative to the product.

OMEGA's policy is to make running changes, not model changes, whenever an improvement is possible. This affords our customers the latest in technology and engineering.

OMEGA is a registered trademark of OMEGA ENGINEERING, INC.

© Copyright 1996 OMEGA ENGINEERING, INC. All rights reserved. This document may not be copied, photocopied, reproduced, translated, or reduced to any electronic medium or machine-readable form, in whole or in part, without prior written consent of OMEGA ENGINEERING, INC.
