CONTROLS

Instruction Manual

For DC Input Variable Speed Controls



omegamation.com

P.0. Box 10 5000 W. 106th Street Zionsville, Indiana 46077

Phone (317) 873-5211 Fax (317) 873-1105 www.dartcontrols.com

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WARRANTY

Dart Controls, Inc. (DCI) warrants its products to be free from defects in material and workmanship. The exclusive remedy for this warranty is DCI factory replacement of any part or parts of such product which shall within 12 months after delivery to the purchaser be returned to DCI factory with all transportation charges prepaid and which DCI determines to its satisfaction to be defective. This warranty shall not extend to defects in assembly by other than DCI or to any article which has been repaired or altered by other than DCI or to any article which DCI determines has been subjected to improper use. DCI assumes no responsibility for the design characteristics of any unit or its operation in any circuit or assembly. This warranty is in lieu of all other warranties, express or implied; all other liabilities or obligations on the part of DCI, including consequential damages, are hereby expressly excluded.

NOTE: Carefully check the control for shipping damage. Report any damage to the carrier immediately. Do not attempt to operate the drive if visible damage is evident to either the circuit or to the electronic components.

All information contained in this manual is intended to be correct, however information and data in this manual are subject to change without notice. DCI makes no warranty of any kind with regard to this information or data. Further, DCI is not responsible for any omissions or errors or consequential damage caused by the user of the product. DCI reserves the right to make manufacturing changes which may not be included in this manual.

WARNING

Improper installation or operation of this control may cause injury to personnel or control failure. The control must be installed in accordance with local, state, and national safety codes. Make certain that the power supply is disconnected before attempting to service or remove any components!!! If the power disconnect point is out of sight, lock it in disconnected position and tag to prevent unexpected application of power. Only a qualified electrician or service personnel should perform any electrical troubleshooting or maintenance. At no time should circuit continuity be checked by shorting terminals with a screwdriver or other metal device.

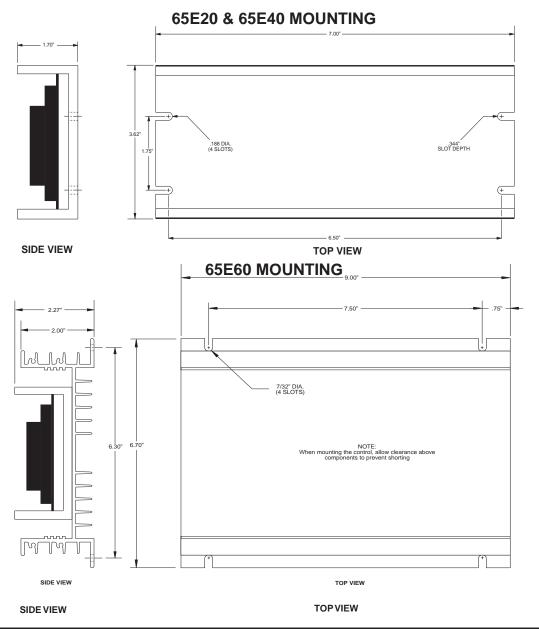
STANDARD FEATURES

- Provides smooth variable speed capability for mobile equipment
- Maintains variable speed control as batteries discharge
- Adjustable maximum speed, minimum speed, current limit, I.R. compensation, and accel
- Inhibit terminal permits optional start-stop without breaking battery lines
- Speed potentiometer, knob, and dialplate included
- Increases range or running time of battery operated equipment through high efficiency
- 65E40 and 65E60 series only Automatic current limit foldback decreases current limit to 50% of setpoint when heatsink temperatures reach 80° C. - provides protection from overheating

CONTROL DIMENSIONS

| MODEL | WIDTH | LENGTH | DEPTH | WEIGHT |
|-------|----------------------|------------|-------------|------------|
| | inches (centimeters) | | | oz. (gms.) |
| 65E20 | 3.7 (9.40) | 7.0 (17.8) | 1.70 (4.32) | 10.5 (297) |
| 65E40 | 3.7 (9.40) | 7.0 (17.8) | 1.70 (4.32) | 13.4 (379) |
| 65E60 | 6.7 (17.1) | 9.0 (22.9) | 2.27 (5.77) | 34.0 (962) |

MOUNTING DIMENSIONS



Caution: Do not mount controller where ambient temperature is outside the range of -10° C (15° F) to 45° (115° F).

INSTALLATION

Before attempting to wire the control, make sure all power is disconnected. Recheck code designation to assure proper voltage is present for the control. Caution should be used in selecting proper size of hook-up wire for current and voltage drop. Note: the battery and armature wire size on 65E models must be a minimum of 12 gauge.

HOOK-UP DIAGRAMS

WARNING:

DO NOT REVERSE POSITIVE AND NEGATIVE BATTERY LEADS. THIS WILL DAMAGE THE CONTROL. TO CHANGE MOTOR DIRECTION, INTERCHANGE THE POSITIVE AND NEGATIVE ARMATURE LEADS.

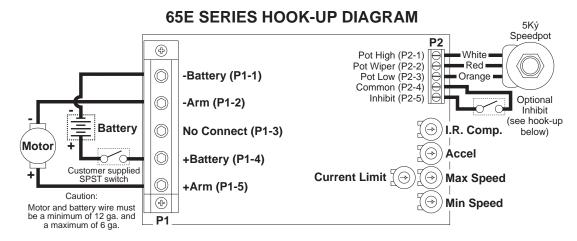
Refer to the wiring diagrams below for proper connection of **DC Voltage**, **Armature**, and **Speedpot wiring** to the control.

CAUTION!! TURN POWER OFF WHILE MAKING CONNECTIONS.

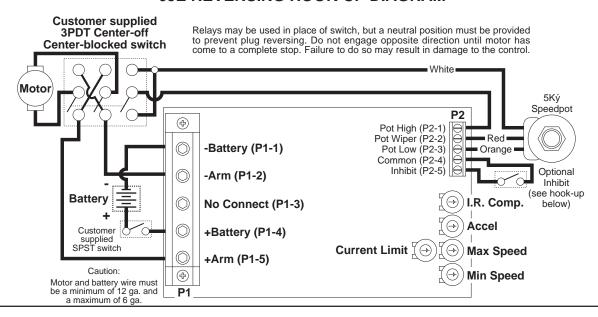
To properly adjust the CURRENT LIMIT setting, a DC ammeter should be placed in series with the armature line. This meter can be removed after the control is adjusted.

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(continued)



65E REVERSING HOOK-UP DIAGRAM



INHIBITING THE CONTROL

Using inhibit input - provide fast startstop by bypassing accel/decel circuit

Inhibit via speedpot - provides starting and stopping through accel/decel parameters



Note: Always use a shielded cable when connecting to the inhibit terminal. The shield of the cable should connect to the Common terminal of the control.

TRIMPOT ADJUSTMENTS

Before the power is applied, the speed potentiometer and trimpots should be preset as follows:

TRIMPOT PRESET

1. Preset speedpot fully CCW, preset Max trimpot CW 1/2 way, preset Current Limit trimpot fully CW, preset Min trimpot fully CCW, preset Accel trimpot CW 1/2 way, preset I.R. trimpot fully CW.

DC power can now be applied to the system and the control adjusted as directed below:

TRIMPOT ADJUSTMENT

- 2. Increase the MIN trimpot in a clockwise direction until the desired minimum speed is reached.
- 3. Turn the Speedpot fully clockwise and adjust the MAX trimpot until the desired maximum speed is reached.

- 4. Adjust the ACCEL trimpot to achieve the desired soft start time. CW rotation will increase accel time.
- 5. Rotate the **CURRENT LIMIT** trimpot fully CCW until the motor begins to stall. Apply a full load to the motor. While motor is stalled adjust the **CURRENT LIMIT** trimpot CW until a desired current setting is obtained.
- 6. Adjust I.R. trimpot CW 1/2 way. If motor RPM is inconsistent (jumpy), rotate I.R. trimpot CCW until rotation is stable.

IN CASE OF DIFFICULTY

If a newly installed control will not operate, it is likely that a terminal or connection is loose. Check to make sure connections are secure and correct. If the control is still inoperative, refer to the following chart for reference:

| PROBLEM | POSSIBLE CAUSE(S) | CORRECTIVE ACTION |
|----------------------------------|---|--------------------------------------|
| Motor doesn't run | Incorrect or no power | Install proper service |
| | Speedpot set at zero | Rotate speedpot fully CW |
| | Worn motor brushes | Replace motor brushes |
| | Current limit set too low | Adjust current limit trimpot CW |
| Motor "hunts" | Max trimpot set too high | See "Trimpot Adjustments" - page 3-4 |
| | I.R. Comp. trimpot set too high | See "Trimpot Adjustments" - page 3-4 |
| Motor runs at "full speed" | Loose speedpot connections | Secure all connections |
| uncontrollable | Min. or Max. trimpots not properly adjusted | See "Trimpot Adjustments" - page 3-4 |
| | Possible control failure | Send to Dart Controls, Inc. |
| Motor rotates in wrong direction | Motor armature hooked up backwards | Reverse armature + and - leads |
| Motor stalls under a light load | Current limit trimpot improperly adjusted | See "Trimpot Adjustments" - page 3-4 |

MODEL SELECTION

| INPUT VOLTAGE | OUTPUT VOLTAGE | CONTINUOUS CURRENT | MODEL NUMBER |
|---------------|----------------|--------------------|--------------|
| 12 VDC ± 15% | 0 - 12 VDC | 20 amps D.C. | 65E20-12 |
| 12 VDC ± 15% | 0 - 12 VDC | 40 amps D.C. | 65E40-12 |
| 12 VDC ± 15% | 0 - 12 VDC | 60 amps D.C. | 65E60-12 |
| 24 VDC ± 15% | 0 - 24 VDC | 20 amps D.C. | 65E20* |
| 24 VDC ± 15% | 0 - 24 VDC | 40 amps D.C. | 65E40* |
| 24 VDC ± 15% | 0 - 24 VDC | 60 amps D.C. | 65E60* |
| 36 VDC ± 15% | 0 - 36 VDC | 20 amps D.C. | 65E20* |
| 36 VDC ± 15% | 0 - 36 VDC | 40 amps D.C. | 65E40* |
| 36 VDC ± 15% | 0 - 36 VDC | 60 amps D.C. | 65E60* |

^{* 24} volt and 36 volt units with the same current ratings are interchangeable (ie. 24 volt unit will operate with 36 volt input and a 36 volt unit will operate with 24 volt input, same current rating).

SPECIFICATIONS

| | 65E20 | 65E40 | 65E60 |
|------------------------------|---|---------|---------|
| Load current (continuous) | 20 amps | 40 amps | 60 amps |
| Speed adjustment | 5K Ω potentiometer or 0 to +10VDC input signal | | |
| Speed range | 30:1 | | |
| Overload capacity | 200% for 10 seconds; 150% for one minute | | |
| Current limit | adjustable100% to 200% of full motor load, up to continuous current rating (page 4) | | |
| Acceleration | adjustable - 0 to 10 seconds | | |
| Deceleration | non-adjustable - 0.5 seconds | | |
| Maximum speed | adjustable - 50 to 100% of base speed | | |
| Minimum speed | adjustable - 30% of max speed | | |
| Connections | barrier terminal block (12Ga. to a maximum 6 Ga.) | | |
| Speed regulation | 1% of base speed via adjustable I.R. Compensation trimpot | | |
| Operating temperature | -10°C to +45°C (14°F to 113°F) | | |
| Package configuration | black anodized aluminum extrusion | | |
| Internal operating frequency | approximately 1.6K Hertz | | |
| Thermal protection | N/A Current foldback at 80° C. heatsink temperature | | |

65E40 / 65E60 PART PLACEMENT & LIST

RESISTORS CAPACITORS C1 C2 C3 .1μF 63V .1μF 63V .22μF 100V 300& 5W R1 R2 R3 R4 R5 R6 R7 R8 R9 R10 R11 47K 470& .22µF 100V .1µF 63V .1µF 63V .22µF 100V .1µF 63V .01µF 100V .01µF 100V 47µF 16V 47K 470& C4 C5 10K 20K MAX Č6 C7 C8 C9 C10 C11 C12 220K 47K 10K 1000μF 50V 1000μF 50V R12 100K .1μF 63V .1μF 63V .01μF 100V R13 10K C13 R14 180K C14 R15 R16 R17 R18 250K ACCEL 20K 1/4W 1% 470K DIODE 300K R19 47K 5K MIN R20 D1 1N4005 D2 D3 D4 D5 1N4005 10K R22 R23 4.7K 1N963B 1N914B R24 R25 6.8K 10K D6 D7 1N5233B 1N914B R26 4.7K R27 47K R28 R29 300K **ACTIVE** R30 20K CUR. LIM. R31 R32 R33 R34 4.7K **DEVICES** 5K I.R. COMP 100K 47K 2.7K 22& R35 R36 Q2 Q3 Q4 Q5 Q6 Q7 Q8 IRFZ44 IRFZ44 R37 R38 IRFZ44 228 **IRF744** R39 R40 22& 22& IRFZ44 IRFZ44 IRFZ44 R41 R42 R43 22& 47K Q9 Q1 IRFZ44 IRFZ44 1.2M R44 R45 R46 R47 150& 5K SPEEDPOT* 22K 680K **IC PACKAGES** R48 R49 40106 IC LM324 IC LM324 IC LM358 IC U1 U2 U3 U4 100K R50 R51 15K

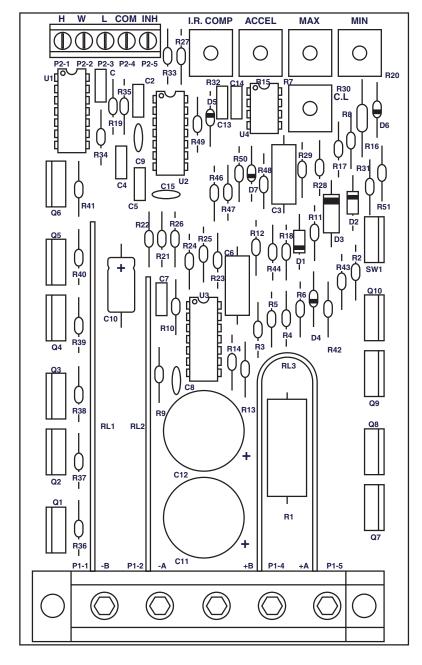
MISCELLANEOUS

-4-2519B PRINTED CIRCUIT BOARD 5 POS. TERMINAL BLOCK 5 POS. BARRIER TERMINAL STRIP RLB2508X RAIL

P1 (-1 thru -5) P2 (-1 thru -5) RL1 RL2 RL3 SW1 RLPRN910 RAIL RLB25011XB RAIL 67F080 TEMP .SWITCH

| 65E20 |
|---------|
| HANGES: |
| |

| C12 Q1 Q2 Q3 Q4 Q7 Q9 Q10 R1 R6 R28 R31 R35 R42 | DELETE DELETE DELETE DELETE DELETE DELETE DELETE DELETE 10& 1W 22K 4.7K 2.2K 1K 22K | C12 Q1 Q2 Q3 Q4 Q7 Q9 Q10 R48 | DELETE DELETE DELETE DELETE DELETE DELETE DELETE DELETE 1K |
|--|---|---|--|
| R48 | 1K | | |

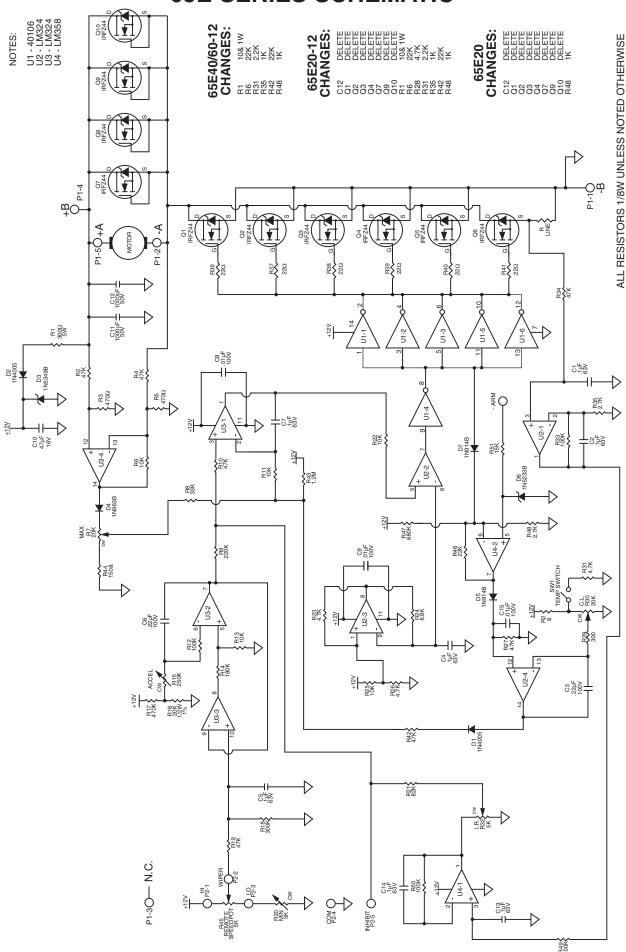


65E40/60-12 **CHANGES:**

* SPEEDPOT IS MOUNTED REMOTE

NOTE: ALL RESISTORS 1/8W UNLESS NOTED OTHERWISE

65E SERIES SCHEMATIC



REPAIR PROCEDURE

In the event that a Product manufactured by Dart Controls Incorporated (DCI) is in need of repair service, it should be shipped, freight paid, to: Dart Controls, Inc., 5000 W. 106th Street, Zionsville, IN. 46077, ATTN: Repair Department. Please include Name, Shipping Address (no P.O. Box), Phone Number and if possible, e-mail address.

Those orders received from anyone without an existing account with DCI must specify if they will be paying COD or Credit Card (Master Card/Visa/American Express). This information is required before work will begin. If you have an account with Dart your order will be processed according to the terms listed on your account. Products with Serial Number date codes over 5 years old will automatically be deemed Beyond Economical Repair (BER). A new, equivalent device will be offered at a substantial discount.

Completed repairs are returned with a Repair Report that states the problem with the control and the possible cause. Repair orders are returned via UPS Ground unless other arrangements are made. If you have further questions regarding repair procedures, contact Dart Controls, Inc. at 317-873-5211.

YOUR MOTOR SPEED CONTROL SOLUTIONS PROVIDER



125D SERIES AC INPUT - VARIABLE DC OUTPUT 1/50 HP through 1.0 HP



250G SERIES AC INPUT - VARIABLE DC OUTPUT 1/50 HP through 2.0 HP



65 SERIES
DC INPUT - VARIABLE DC OUTPUT
CURRENT RATINGS OF 20, 40, AND
60 AMPS



700/COMMUTROL SERIES

DC BRUSHLESS

5 & 20 Amp for

12,24,& 36VDC Inputs



MDP SERIES PROGRAMMABLE CLOSED LOOP DC SPEED CONTROL



DM SERIES
FIELD PROGRAMMABLE
DIGITAL TACHOMETER

Dart Controls, Inc. is a designer, manufacturer, and marketer of analog and digital electronic variable speed drives, controls, and accessories for AC, DC, and DC brushless motor applications.

Shown above is just a sampling of the expanded line of Dart controls that feature the latest in electronic technology and engineering. Products are manufactured in the U.S.A. at our Zionsville (Indianapolis,

Indiana) production and headquarters facility - with over 2,000,000 variable speed units in the field.

In addition to the standard off-the-shelf products, you can select from a wide variety of options to customize controls for your specific application. For further information and application assistance, contact your local Dart sales representative, stocking distributor, or Dart Controls, Inc.

www.dartcontrols.com
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Dart Controls, Inc.

Manufacturer of high quality DC and AC motor speed controls and accessories since 1963.

P.O. Box 10 5000 W. 106th Street Zionsville, Indiana 46077 Phone: (317) 873-5211 Fax: (317) 873-1105

