OMEGAT User's Guide

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CN6201

Program Temperature Controller



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Please read through this user's manual to ensure correct usage of the controller and keep it handy for quick reference.

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■ Checking Package Contents

Before using the product, check that its model & suffix codes are as you ordered.

Model and Suffix Codes

Model Suffix code		Description				
CN6201		Program Temperature Controller				
Control output for standard typ	-R -DC -F	Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID) 4 to 20mA output (continuous PID)				
Option	-DI -PV -C4 -LV -AL	RUN/RESET switching, and HOLD program/cancel HOLD program switching by external contacts (Note1) PV retransmission output in 4 to 20mA Communication function (MODBUS, PC-Link, Ladder) (Note1) (Note2) Power Supply 24V DC / 24V AC Dual Alarms				

Note1: /RS option and /EX option cannot be specified at the same time.

Note2: When specifying the /RS option, be sure to order the required number of copies of Communication Functions User's Manual separately.

- Mounting bracket · · · · · 1
- User's manual

1. NOTICE

The following safety symbol is used both on the product and in this user's manual.



This symbol stands for "Handle with Care." When displayed on the product, the operator should refer to the corresponding explanation given in the user's manual in order to avoid injury or death of personnel and/or damage to the product. In the manual the symbol is accompanied by an explanation of the special care that is required to avoid shock or other dangers that may result in injury or loss of life.

The following symbols are used in this manual only.



Indicates that operating the hardware or software in a particular manner may lead to damage or result in system failure.



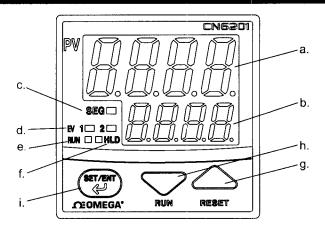
Draws attention to information that is essential for understanding the operation and/or features of the product.

■ Exemption from Responsibility

Make sure that all of the precautions are strictly adhered to. Omega assumes no liability for any damage resulting from use of the instrument in contradiction to the precautions.

Also, Omega assumes no liability to any party for any loss or damage, direct or indirect, caused by the use or any unpredictable defect of the instrument.

2. WHAT IS ON THE FRONT PANEL?



■ Monitoring Parts

	Name	Function
a.	PV display (red)	Indicates PV (measured value) and character information such as parameter codes and error codes. Indicates PV and "AT" alternately during Auto-tuning.
b.	SP display (green)	Indicates SP (target setpoint), segment no., remaining segment time and parameter setpoints on SP display.
c.	SEG lamp (green)	Lit when the value of segment no. or remaning segment time is displayed.
d.	EV1, EV2 lamps (red)	EV1: Lit when event 1 (PV event 1 or Time event 1) is activated. EV2: Lit when event 2 (PV evnet 2 or Time evnet 2) is activated.
e.	RUN lamp (orange)	Lit while the operation mode is "RUN". Flashing while the operation mode is "WAIT".
f.	HLD (hold) lamp (green)	Lit while the operation mode is "HOLD".

■ Operating Parts (See 7. Key operations)

	Name	Function
g.	Data change key (or Reset key)	 Pressing this key for more than 1 second (in operating display) stops (resets) the program operation. Changes the program setpoints(SP) and the parameter setpoints. Pressing this key increases the parameter setpoint. Holding down the key will gradually increase the speed of changes.
h.	Data change key (or Run key)	 Pressing this key for more than 1 second (in operating display) starts (runs) the program operation. Changes the program setpoins(SP) and the parameter setpoints. Pressing this key decreases the parameter setpoint. Holding down the key will gradually decrease the speed of changes.
i.	SET/ENT key (data registering key) SET/ENT	 Switches the operating displays ①, ② and ③. Registers the data value changed using the data change keys. Switches between parameter setting displays sequentially. Pressing the key for 3 seconds or longer in the operating display retrieves the operating parameter setting display. Pressing the key for 3 seconds or longer in operating, setup or program parameter setting display transfers back to operating display ①.

3. INSTALLING THE CONTROLLER



To prevent electric shock, the source of power to the controller must be turned off when mounting the controller on to a panel.



To install the controller, select a location where:

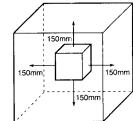
- 1. No-one may accidentally touch the terminals;
- 2. Mechanical vibrations are minimal;
- 3. Corrosive gas is minimal;
- 4. The temperature can be maintained at about 23°C with minimal fluctuation;
- 5. There is no direct heat radiation;

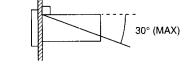
- 6. There are no resulting magnetic disturbances;
- 7. The terminal board (reference junction compensation element, etc.) is protected from wind;
- 8. There is no splashing of water; and
- 9. There are no flammable materials.

Never place the controller directly on flammable items.

If the controller has to be installed close to flammable items or equipment, be sure to enclose the controller in shielding panels positioned at least 150mm away from each side. These panels

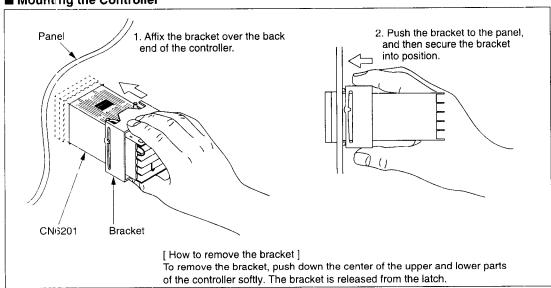
should be made of either 1.43mm thick metal-plated steel plates or 1.6mm thick uncoated steel plates.





●Mount the controller at an angle within 30° from horizontal with the screen facing upward. Do not mount it facing downward.

■ Mounting the Controller



4. PANEL CUTOUT DIMENSIONS AND EXTERNAL DIMENSIONS

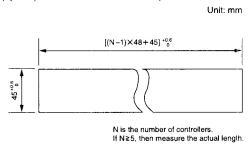


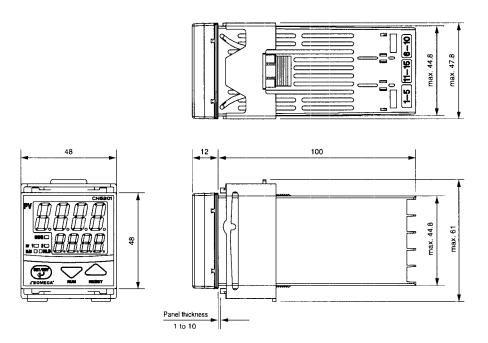
Splesh-proof construction is not available when the side-by-side close mounting method shown in the following figures, is chosen for any of the controller.

1. General Mounting

2. Side-by-side Close Mounting

(Splash-proof construction is unavailable)





WIRING



- 1) Before you start wiring, turn off the power source and use a tester to check that the controller and cables are not receiving any power in order to prevent electric shock.
- 2) For safety, be sure to install a circuit breaker switch (of 5A and 100V AC or 220V AC, and that conforms to IEC60947) near the instrument so as to be operated easily, and clearly indicate that the device is used to de-energize the instrument.
- 3) Wiring should be carried out by personnel with appropriate electrical knowledge and experience.



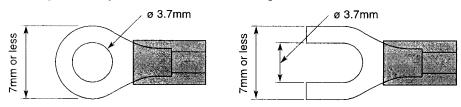
- 1) Use a single-phase power source. If the source has a lot of noise, use an isolation transformer for the primary side and a line filter (we recommend TDK's ZAC2205-00U product) for the secondary side. When this noise-prevention measure is taken, keep the primary and secondary power cables well apart. Since the controller has no fuse, be sure to install a circuit breaker switch (of 5A and 100V AC or 220V AC, and that conforms to IEC standards) and clearly indicate that the device is used to de-energize the controller.
- 2) For thermocouple input, use shielded compensating lead wires. For RTD input, use shielded wires which have low resistance and no resistance difference between the 3 wires. See the table given later for the specifications of the cables and terminals and the recommended products.
- 3) The control output relay cannot be replaced even though it has a limited service life (100,000 relay contacts for the resistance load). Thus, an auxiliary relay should be used so that the load can be turned on and off
- 4) When using an inductive load (L) such as an auxiliary relay and solenoid valve, be sure to insert a CR filter (for AC) or diode (for DC) in parallel as a spark-rejecting surge suppressor to prevent malfunctions or damage to the relay.
- 5) When there is the possibility of being struck by external lightening surge, use the arrester to protect the insturment.

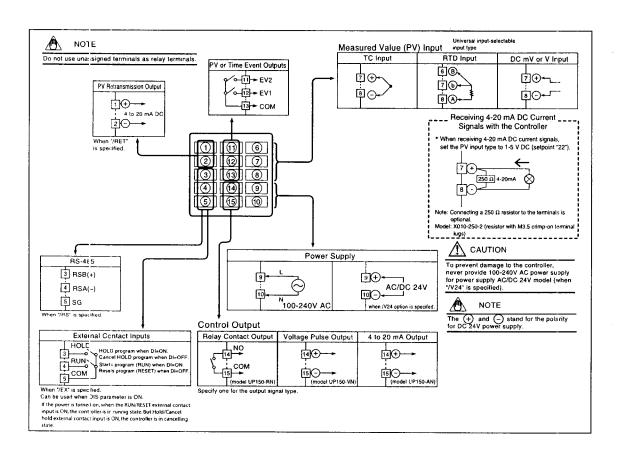


Always fix a terminal cover bracket to the CN6201 program temperature controller before wiring if an opt onal anti-electric-shock terminal cover (part number: L4000FB) is used.

Recommended Terminals

Use M3.5 screw-compatible crimp-on terminals with an insulating sleeve, as shown below.





HARDWARE SPECIFICATIONS

Measured Value (PV) Input

- Input: 1 point
- Input type: Universal; can be selected by software
- Input accuracy (at 23 ±2°C ambient temperature) • Thermocoup.e: ±2°C ±1digit
- ±4°C for thermocouple input −200 to −100°C
- ±3°C for thermocouple input -100 to 0°C
- ±5°C for types R and S (±9°C for 0 to 500°C)
- ±9°C for type B (accuracy is not guaranteed for 0 to 400°C)
 RTD: ±1°C ±1digit
- •Voltage(mV, V): ±0.3% ±1digit
- Sampling period for measured value input: 500ms
 Burn-out detection: Functions for thermocouple or RTD input
- (burn-out upsca e only: cannot be switched off)
- Input resistance: IMΩ or greater for thermocouple or DC mV input Approx. IMΩ for DC V input
 Maximum allowable signal source resistance:
- 250Ω for thermocouple or DC mV input $2k\Omega$ for DC V input
- Maximum allowable wiring resistance for RTD input:
- IMΩ/wire (The resist unce values of three wires must be the same.)

 ◆ Allowable input voltage: ±10V DC for thermocouple or DC mV input ±20V DC for DC V input
- Noise rejection retio: Normal mode noise: Min. 40dB (50/60Hz)
 Common mode noise: Min. 120dB (Min. 90dB for DC V input)
- Error of reference j metion compensation:±1.5°C (at 15-35°C)

±2.0°C (at 0-50°C) The reference junction compensation cannot be switched off.

Applicable standards

Thermocouple and resistance temperature detector(RTD) JIS/IEC/DIN (IT:90)

Manual Setting (SP) Output

SP (target setpoi it) will be output in 3 seconds

- Output: 1 point
- Output type: Current output Output signal: 4 to 20mA current output Maximum load resistance: 600Ω Output accuracy $\pm 0.3\%$ of span (at $2.\pm 2^{\circ}C$ imbient temperature)

Alarm Functions

■ Alarm Functions

 Alarm types: 22 types (waiting action can be set by software): PV high limit, PV low limit, Deviation high limit, Deviation low limit, De-energized on deviation high limit, De-energized on deviation low limit, Deviation high and low limits, Deviation within high and low limits, Deenergized on PV high limit, De-energized on PV low limit, Fault diagnosis output, FAIL output

Alarm output: 2 relay contacts Relay contact capacity: 1A at 240V AC or 1A at 30V DC (with resistance load) (COM terminal is common) Note: The alarm output relays cannot be replaced by users

Retransmission Output

- Output signal: Measured value in 4-20mA DC.
- Maximum load resistance: 600Ω
- Output accuracy: ±0.3% of span (at 23±2°C ambient temperature)

Safety and EMC Standard

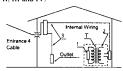
Safety: Compliant with IEC/EN61010-1: 2001, approved by CSA1010, approved by

Installation category: CAT. II (IEC/EN61010, CSA1010) Pollution degree: 2 (IEC/EN61010, CSA1010) Measurement category: I (CAT. I:

IEC/EN61010) Rated measurement input voltage: 10V DC max.(across terminals), 300V AC max.(across

ground)
Rated transient overvoltage: 1500V (Note) Note: It is a value on the safety standard which is assumed by IEC/EN61010-1 in measurement category I, and is not the value which guarantees

an apparatus performance. Caution: This equipment has Measurement category I, therefore do not use the equipment for measurements within measurement categories II, III and IV.



	isurement ategory	Description	Remarks			
1	CAT.1	For measurements performed on circuits not directly connected to MAINS.				
2	CAT.2	For measurements performed on circuits directly connected to the low voltage installation.	Appliances, portable equipments, etc.			
3	CAT.3	For measurements performed in the building installation.	Distribution board, circuit breaker, etc.			
4 CAT.4		For measurements performed at the source of the low-voltage installation.	Overhead wire, cable systems, etc.			

 EMC standards: Complies with EN61326. The instrument continues to operate at a measuring accuracy of within ±20% of the range during tests.

Power Supply and Isolation

■Power Supply

Power supply	Voltage	Rated at 100-240VAC (±10%) AC/DC 24V, 20 to 29V of allowable range when "/V24" is specified.				
	Frequency	50 or 60Hz				
Maximum	power consumption	BVA max. (4W max.) 3W max. when "/V24" is specified.				
Memory		Non-volatile memory				
Withstanding voltage	Between primary terminals and secondary terminals (See Notes 1 and 2.)	1500V AC for 1 minute				
Insulation resistance	Between primary terminals and secondary terminals (See Notes 1 and 2.)	20MΩ or more at 500V DC				

Note 1: The primary terminals are the power supply terminals and alarm output terminals

The secondary terminals are the analog input and output terminals Note 2: AC/DC 24V terminals are secondary terminals.

Isolation

The bold lines below indicate reinforced isolation, and the broken line indicator functional isolat

me broken tine matean	is functional isolation.					
• Power supply terminals (100-240V AC)	Power supply terminals AC/DC 24V (When "/V24" is specified)					
(100-240 V AC)	Measured value input terminals Internal circuit					
• Alarm output terminals (2 relay contacts)	• Manual setting output terminals: 4-20 mA • Retransmission output terminals: 4-20 mA					

Note: The measured value input terminals is isolated from the internal circuit.

Construction, Mounting, and Wiring

• Construction: Dust-proof and drip-proof front panel conforming to IP65. For side-by-side close installation the controller loses its dust-proof and drip-proof

- protection.

 Casing: ABS resin and polycarbonate
 Case color: Black
- Weight: UD310 approx. 200g
- UD320 approx. 300g UD350 approx. 400g Mounting: Flush panel mounting
- Wiring: Screw terminals

Environmental Conditions

■Normal Operating Conditions

- Warm-up time: At least 30 minutes
- Ambient temperature:0-50°C (0-40°C when mounted side-by-side)
- Rate of change of temperature: 10°C/h or less
- Ambient humidity: 20-90% RH (no condensation allowed)
 Magnetic field: 400A/m or less
- Continuous vibrations of 5 to 14Hz: Amplitude of 1.2mm or less
 Continuous vibrations of 14 to 150Hz: 4.9m/s² (0.5G) or less
- Short-period vibrations: 14.7m/s² (1.5G) for 15 seconds or less
- Shock: 98m/s² (10G) for 11 milliseconds or less Mounting angle: Upward incline of up to 30
- degrees; downward incline is not allowed. ◆ Altitude: 2000m or less above sea level
 ■ Maximum Effects from Operating Conditions

(1) Temperature effects

- Thermocouple, DC mV and DC V input: ±2μV/°C or ±0.02% of F.S./°C, whichever is larger
- Resistance temperature detector: ±0.05°C/°C
- Analog output: ±0.05% of F.S./°C
- (2) Effect from fluctuation of power supply voltage
- (within rated voltage range)
 Analog input: ±0.2μV/V or ±0 002% of F.S./V, whichever is larger
- Analog output: ±0.05% of F.S. /V
 Transportation and Storage Conditions Talisportation and Ctong
 Temperature: -25 to 70°C
 Humidity: 5 to 95% RH (no condensation allowed)

- Shock: Package drop height 90cm (when packed in the dedicated package)

7. KEY OPERATIONS



To prevent electric shock, the controller should be mounted on the panel so as not to accidentally touch the terminals when power is being applied.

- (1) You can move between the parameters in each parameter setting display using the key
- (2) To change the parameter setpoint,
 - (i) Change the display value with the or near key (the period flashes).
 - (ii) Press the key to register the setpoint.
- (3) In the operating display ①, ② or ③. pressing the key for at least 3 seconds retrieves the operating parameter setting display.
- (4) In the operating parameter setting display, pressing the key for at least 3 seconds transfers back to the operating display (1).
 - Registering the parameter PRG to "1" retrieves the program parameter setting display.
 - Registering the key-lock parameter LOC to "-1" retrieves the setup parameter setting display.
- (5) In the setup parameter setting display, pressing the key for at least 3 seconds transfers back to the operating display
- (6) In the program parameter settling display, pressing the key for at least 3 seconds transfers back to the operating d splay (1).

CN6201 Measured Input Ranges

	nput type	Range (°C)	Range code (°C)	Range (°F)	Range code (°F)	1
	Juspecified		OFF	runge (17	mange code ()	
		−270 to 1370°C	1	-300 to 2500°F	31	
	К	0.0 to 600.0°C	2	32.0 to 999.9°F	32	
	I.	0.0 to 400.0°C	3	32.0 to 750.0°F	33	
		-199.9 to 200.0°C	4	-300 to 400°F	34	PV CN6201
وا	J	199.9 to 999.9°C	5	-300 to 2100 °F	35	
Thermocouple	TT	-199.9 to 400.0°C	6	-300 to 750°F	36	
18	E	_199.9 to 999.9°C	7	-300 to 1800°F	37	
ĮĚ	R	0 to 1700°C	8	32 to 3100°F	38	M CONS
j,e	S	0 to 1700°C	9	32 to 3100°F	39	
	В	0 to 1800°C	10	32 to 3200°F	40	ASOMEON. MAN N IT
	N	-200 to 1300 °C	11	-300 to 2400°F	41	THOMESA THE TOTAL PARTY OF THE
	L	–199.9 to 900.0°C	12	-300 to 1600°F	42	1 1/2
	U	−199.9 to 400.0°C	13	-300 to 750°F	43	l (* ' <i>' </i>
_	Platinel 2	0 to 1390°C	14	32 to 2500 °F	44	1
ĺ		-199.9 to 850.0°C	15	-199.9 to 999.9°F	45	
	Pt100	0.0 to 400.0 °C	16	32.0 to 750.0 °F	46	For example, to select
RTD	11100	-199.9 to 200.0°C	17	-300 to 400°F	47	thermocouple type J (°F)
_		-19.9 to 99.9°C	18	-199.9 to 999.9°F	48	
_	JPt100	−199.9 to 500.0°C	19			set the range code to 35.
voltage	0 to 100mV	0.0 to 100.0	20			
15	0 to 5V	0.000 to 5.000 User-scalable	. 21			
ان	11037	1.000 to 5.000	22			
DC	0 to 10V	0.00 to 10.00	23			



At power-on, the program temperature controller displays the operating display ①, but if the measured input type setting remains OFF, "IN" appears. In this case, press the key to display the measured input range code you want to use, then press the key to register it. (Refer to the flowchart on page 12 and 13.)

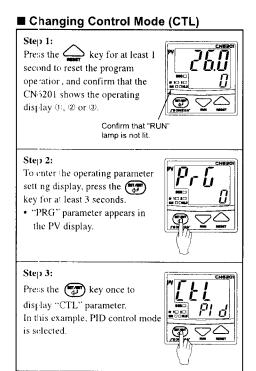


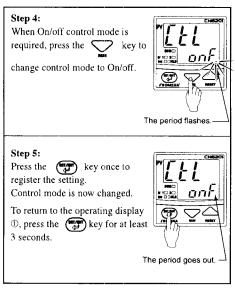
The controller is shipped with the parameters set at the factory-set defaults. Check the default values against the "Parameter Lists" in the page 14 and 15, and change the parameter setpoints that need to be changed.

This section explains how to set and register parameter values.

The procedure for changing Control Mode (CTL) can be found on "Changing Control Mode (CTL)." You can set the other parameters in the same way.

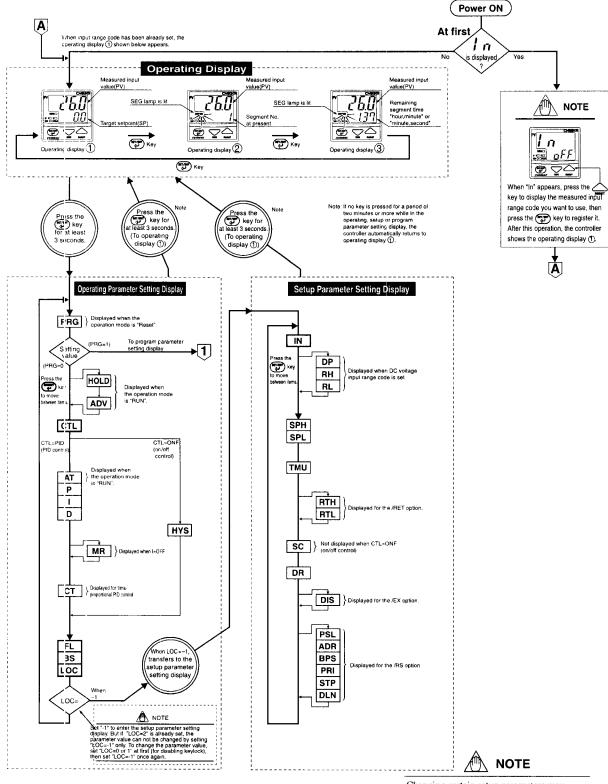
There are no parameter displays for parameters specific to functions, such as the optional external contact inputs functions, if they were not selected at ordering.





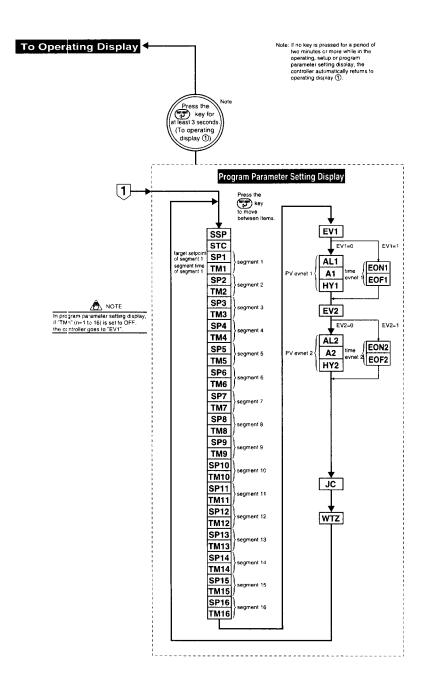


Changing certain setup parameter may atomatically initialize the operating parameters. Therefore, after you change the setup parameters, always check the operating parameter setpoints to find out if appropriate values have been set for them. If the operating parameters have been initialized, set them to their appropriate values.



Changing certain setup parameters may automatically initialize the operating parameters. Therefore, after you change the setup parameters, always check the operating parameter settings to find out if appropriate values have been set for them. If the operation parameters have been initialized, set them to their appropriate values.

11



■ Parameter Lists

LOC

Parameter Lists
Parameters changed rather frequently during operation.
When creating a program, set the prameter PRG=1 to display the program parameter setting display.

Numbers in () are the parameter setpoints that apply when the communication function is used Ex. OFF(0), ON(1)

User setting Setting range and unit Default Code Name 0: Go to "CTL" setting display.
1: Enter the program parameter setting display (Displayed when a program operation is stpped.)

OFF(0): Cancel Hold PRG Fr [Program 0 parameter setting HOLD ON(1): Hold OFF(0) Program hold (Displayed when a program operation is started.) OFF(0): Not execute advance Segment OFF(0) ON(1): Execute advance advance (Displayed when a program operation is started.) CTL [LL ONF(0): On/off control Control mode PID(1) PID(1): PID control OFF(0): Stop auto-tuning AL ON(1): Start auto-tuning (Displayed when a program operation is started.) OFF(0) Auto-tuning 1°C/°F to the temperature that corresponds to 100% of the 5% of measured input Proportional measured input range (scale) span range (scale) span P band 1 to 3600 seconds; Integral time 240 seconds OFF(0): No integral action I to 3600 seconds: Derivative 60 seconds OFF(0): No derivative action Ũ time MR_FTF 50.0% Manual reset -100 to 100% 0.5% of measured HYS **H**45 Hysteresis for 0°C/°F to the temperature that corresponds to 100% of the input range (scale) on/off control measured input range (scale) span span Control output 1 to 240 seconds 30 seconds cycle time OFF(0) PV input filter OFF(0), 1 to 120 seconds FL 0% of measured input PV input bias -100 to 100% of measured input range (scale) span range (scale) span BS 0: No key lock (Note)
1: No key lock (Note)
2: Pre-ents all parameter changing operations
2: Pre-ents all parameter changing operations
-1: Set '-1' to enter the setup parameter setting display.
But if "LOC=1" or 2" is already set, the parameter value can
not be changed by setting "LOC=1" only. To change the
parameter value, set "LOC=4" at first (for disabling keylock),
then set "LOC=-1" once again.
(Note) Both 0 and 1 are No key lock. Lo[0 Key lock

(2) Setup Parameters Parameter rarely changed in normal use after once having been set.

Code Name Setting range and unit Default	
type (If no measured input type is specified at the time of ordering, you must set the measured input type.) Decimal point position of measured input type is specified at the time of ordering, you must set the measured input type.) Decimal point position of it. No decimal place (nnnn) (Displayed at voltage input) 2: Two decimal places (nn.nn) 3: Three decimal places (nn.nn) Maximum value of measured (RL + 1) to 9999 (Displayed at voltage input) 100.0	
DP : One decimal place (nn.n.n) 2 Two decimal places (nn.n.n) 3 Three decimal places (nn.n.n) 3 Three decimal places (nn.n.n) (Displayed at voltage input) (RL + 1) to 9999	
of measured (RL + 1) to 9999 (Stophylot at 10th g mpm) 100.0	
RL input scale	
RI. Minimum value of measured input scale (Displayed at voltage input) 0.0	
SPH Maximum value of program setting range (SPL+1digit) to max. value of measured input range (scale). Min value of measured input range (scale) to (SPH-1digit) measured input range (scale). Min value of measured input range (scale). Min value of measured input range (scale).	•
SPL 5FL Minimum value of program setting range within the measured input range (scale) to prevent a program setpoint from being setting range beyond the limits of setting range by mistake. Note that SPL-SPH Place limits on the program setting range within the measured input range (scale) to prevent a program setpoint from being beyond the limits of setting range by mistake.	e
TMU Program time unit of a program. 0: hour,minute 1: minute,second O O O O O O O O O O O O O	
Temperature input: Within measured input range Voltage input: (RTL+1digit) to max. value of measured input scale (RH) Maximum value of retransmission of retransmission output Min. value of measured input scale (RL) to (RTH-1digit) Moneyer. RTL <rth (scale)="" (scale)<="" input="" maximum="" measured="" minimum="" of="" range="" th="" value=""><th></th></rth>	
RTL Minimum value of retransmission output of retransmission output (Factor)-set default) PV retransmission range (Factor)-set default) PV retransmission range (After scaling) PV retransmission output (Scale)	e
SUPER function OFF(0): Uses the SUPER function OFF(0) OFF(0): Does not use SUPER function	
Direct/reverse action 1: Direct action 0	
DI-function selection OFF(0):Function of /EX does not work ON(1):Terminals (3)-(5) Hold when DI=ON Cancel hold when DI=OFF Terminals (4)-(5) Start program operation when DI=OFF Note: When DIS=ON, the operation mode can not be changed by key operation. However, only the RESET key is operable.	
Protocol selection Protocol selection 0: PC-link communication 1: PC-link communication 2: Ladder communication 3: MODBUS in ASCII mode 4: MODBUS in RTU mode	
ADR PLI Controller address 1 to 99 However, the number of controllers that can be connected per host device is 31 at the maximum.	
BPS LF 5 Baud rate 2.4(0): 2400 bps 4.8(1): 4800 bps 9.6(2): 9600 bps 9.6(2): 9600 bps	
PRI Parity NON(0): Disabled EVN(1); Even parity ODD(2): Odd parity EVN(1)	
STP 5LP Stop bit 1 or 2 bits 1 bit	
DLN Data length 7 or 8 bits • 8 bits when ladder, MODBUS (RTU) • 7 bits when MODBUS (ASCII) 8 bits	

Code	Name	Setting range and unit	Default	User setting
SSP 550	Starting target setpoint	0 to 100% of measured input range (scale) span Unit: $^{\circ}\text{C}/^{\circ}\text{F}$	Min. value of measured input range (scale)	
src 5 <i>E</i> C	Start code	0:Program operation begins with the starting target setpoint. 1:Ramp-prioritized PV start (program operation begins with the PV value by giving priority to the ramp of segment 1) 2:Time-prioritized PV start (program operation begins with the PV value by giving priority to the time of segment 1)	0	
SP1 5 67 1	Target setpoint 1	0 to 100% of measured input range (scale) span Unit:°C/°F	Min. value of measured input range (scale)	Use the table blow
TMI Eril	Segment time 1	OFF(-1) or 0.00 to 99.59 (hour,min. or min,second) Time unit is to be set in "TMU" parameter.	OFF(-1)	Use the table blow
*Note				
SP16 5F 15	Target setpoint 16	0 to 100% of measured input range (scale) span Unit:°C/°F	Min. value of measured input range (scale)	Use the table blow
TM16 E 7 15	Segment time 16	OFF(-1) or 0.00 to 99.59 (hour.min. or min.second) Time unit is to be set in "TMU" parameter.	OFF(-1)	Use the table blow
EV1 E !	Event 1 type	0: PV event 1: Time event	0	
ALI RL I	PV event 1 type	OFF(0) or 1 to 10 (see the table of PV event function list in User's Manual for Programming/Operation)	1	
A1 # 1	PV event 1 setpoint	PV alarm: Min. value of measured input range (scale) to Max, value of measued input range (scale) Deviation alarm: -100 to 100% of measured input range (scale) span Unit: °C/°F Unit: °C/°F	Max. value of measured input range (scale) (PV alarm)	
HY1 H'- } 1	PV event 1 hysterisis	0 to 100% of measured input range (scale) span Unit:°C/°F	0.5% of measured input range (scale) span	
EONI E CIN 1	Time event I on time	OFF(-1) or 0.00 to 99.59 (hour,min. or min,second) Time unit is the same as that of the program.	OFF(-1)	
EGFI E CIF 1	Time event 1 off time	OFF(-1) (Note) or 0.00 to 99.59 (hour,min. or min, second) Note: Time event 1 does not stop when "OFF" is set.	OFF(-1)	
EV2 EU 2	Event 2 type	0: PV event 1: Time event	0	
	PV event 2 type	OFF(0) or 1 to 10 (see the table of PV event function list in User's Manual for Programming/Operation)	2	
A2 Ac 7	PV event 2 setpoint	PV alarm: Min. value of measured input range (scale) to Max. value of measued input range (scale) Deviation alarm: -100 to 100% of measured input range (scale) span Unit: °C/°F Unit: °C/°F	Max. value of measured input range (scale) (PV alarm)	
HY2 H 117	PV event 2 hysterisis	0 to 100% of measured input range (scale) span Unit:°C/°F	0.5% of measured input range (scale) span	
EON2 EON2	Time event 2 on time	OFF(-1) or 0.00 to 99.59 (hour,min. or min,second) Time unit is the same as that of the program.	OFF(-1)	
EOF2 E CIF C	Time event 2 off time	OFF(-1) (Note) or 0.00 to 99.59 (hour,min. or min, second) Note: Time event 2 does not stop when "OFF" is set.	OFF(-1)	
IC II.	Junction code	0: Reset 1: Hold 2: Repeat (repeat endlessly)	0	
wtz L. I	Wait zone	OFF(0) or 0 to 10% of measured input range (scale) span	OFF(0)	

^{*}Note: • The setting range (scale) and unit of SPn (n=2 to 15) are same as those of SP1 (and SP16)
• The setting range (scale) and unit of TMn (n=2 to 15) are same as those of TM1 (and TM16)

■ User Setting Table of Target SP and Segment time

Oser Setting i	Oser Setting Table of Target St. and Segment time															
	n=1	n=2	n=3	n=4	n=5	n=6	n=7	n=8	n=9	n=10	n=11	n=12	n=13	n=14	n=15	n=16
SP n (n=1 to 16)											·					
TM n (n=1 to 16)																

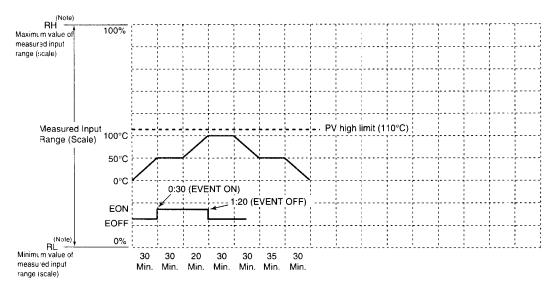
■ Description of Parameters

Parameter	Function	Parameter	Function					
Control moce	UP150 has two control mode. Select one from the following: a. PID control (PID)	Decimal point of measured input	For DC voltage input, the input signal can be scaled for the particular engineering unit. For example, if you set the input					
Manual rese:	b. On/off control (ONF) You can set this parameter only for control	DP	type (IN) at range code 22, the initial range is 0.0 to 100.0. a. Using DP, set the decimal point position fit for the engineering unit you want to use. (In the example below,					
	without an integral action (when registered as CTL=PID and I=OFF). The controller outputs the		the 2 digits to the right of the decimal point) b. Next, register the scale values of the measured input scale using					
MR	manual reset (MR) value when PV=SP. For example, if you set MR=50%, the controller outputs (OUT) 50% when PV=SP.	Maximum/minimum value of measured input scale	RH and RL (In the example below, RH=10.00 and RL=0.00) 0.0 (1V)					
Hysteresis for on/off control	For on/off control (CTL=ONF), you can set a hysteresis around the on/off point (SP) to prevent chattering.	RH, RL	Measured Input scale 0.00 (RL) (after being scaled) 10.00 (RH) Register the decimal point position using DP.					
HYS	On/off point (Program SP) OFF Hysteresis	SUPER function selection	The SUPER function is effective in the following cases: a. An overshoot must be suppressed. b. The rise-up time needs to be shortened. c. The load often varies. Note 1: The SUPER function will not work when on/off control is selected, or I or D					
Control output cycle time	The cycle time is the period of on/off repetitions of a relay or voltage pulse output in time proportional PID control. The ratio of the ON time to the cycle time is proportional to the control output value.	sc	constants is set at OFF in PID control. Note 2: For some types of systems, the SUPER function may not be so useful. If this is the case, turn off the function.					
	Cycle time	DI-function selection	When DIS=ON, Mode can be switched by only external contact input signal.					
СТ	ton		3 ON: HOLD, OFF: Cancel HOLD 4 ON: RUN, OFF: RESET					
PV input filter	This function should be used when the PV display value may fluctuate greatly, for example, when the measured input signal contains noise. The filter is of the first-order lag type, and FL sets the time constant. If a larger time constant is set, the filter can remove more noise.	DIS	In order to switch the Mode by key operation, OFF must be set at DIS. Note: UP150 can be switched into "RESET" mode by key operation even if DIS=ON.					
FL	Input 2-seconds filter 10-seconds filter	Hysteresis for PV evnets 1 and 2	The PV events are output as relay outputs. Since a relay has a limited service life, excessive on/off actions will shorten the life of a relay. To prevent this, you can set a hysteresis band for both PV evnets 1 and 2 to moderate excessive on/off					
PV input bias	This function adds a bias value to the measured input value, and the result is used for display and control computation. Vi value unside the controller =	HY1, HY2	actions .					
BS	This function is useful for carrying out fine adjustment when the PV value is within the required accuracy but it differs from the value	Time event n* on time n*=1 or 2	The time event feature begins countdown when a program starts running, and after the clapse of a preset time, output an on-time event signal (contact output ON) or off-time event signal					
	obtained by other equipment.	EON1 EON2	(contact output OFF).					
		Time event n* off time n*=1 or 2	SEG1 SEG2 SEG3 SEG4 SEG5 Program pattern					
		EOF1 EOF2	Time					
			Time OFF time Time Event Diagram					

8. PROGRAMMING

To operate the controller using a program, first create the program. The CN6201 have one program pattern.

Program operation is based on a program pattern consisting of up to 16 segments as shown in the figure below. To create a program pattern, set the target setpoint to be reached and segment time for each segment. Tow PV events and/or two time events can be set for a program.



(Note) Disp ayed only for DC voltage input.

Starting target setpoint value (SSP)	0 °C					
Start code (STC)	0 (program operation begins with the starting target setpoint)					
Junction code (JC)	0 (reset)					

Segment No.		i	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Target setpoint (S	6P)	50°C	50°C	100°C	100°C	50°C	50°C	0°C									
Segment time (T! (hour rinute or minu Use the TMU setup p the time unit.	te second)	0:30	0:30	0:20	0:30	0:30	0:35	0:30									
Time event I	EON1	0:30							•								
(EV l=1)	(E:V1=1) EOF1 1:20																
54	ALI	\															
PV event 1 (EV I=0)	Al	C	an not	be use	d in th	is exa	nple b	ecause	Even	t1 isι	ised as	time	event.				
	HY1	7						,									
Time event 2	EON2	1	an not	ho use	nd in th	ic ova	mnle h	003116	o Ever	st 2 ic 1	read a	c DV e	vent				
(EV2=1)	EOF2	Can not be used in this example because Event 2 is used as PV event.															
DI 2	AL2	1(PV	high li	imit)													
PV event 2 (EV2=0)	A2	110°	С														
, - /	10°C																

Example of Program Pattern Settings

■ Program Pattern Setting Table

Device name	
Program name	
Model name	
Serial No.	

RH													
Maximum value of	100%	 , ! !					 		 				
measured input range (scale)		 			¦		 		 				
		 			; !		 		 	!			
					:								
		 ,			† ! !								
		 			<u> </u>		 		 				
Meası re	d Input	į			i !								
Range (S	Scale)	! !			! !	1					((
		 1) !	• 		+ ! !	• • • • • • 	 • • • • • • • • • • • • • • • • • • •		 	• ! !	(
		 			; 	 	 		 		, ,	·	
		1 1 1			! !	 				4 4 1	1 6 1		
					; :		 		 	, ! !	 !		
		 			i !		 		 	; !	; !		
(No:e), RL — Minimum value of	0%	 			<u></u>		 		 		<u>:</u> !		
Minimum value of measured input range (scale)													

(Note) Displayed only for DC voltage input.

Starting target setpoint value (SSP)

Start code (STC)

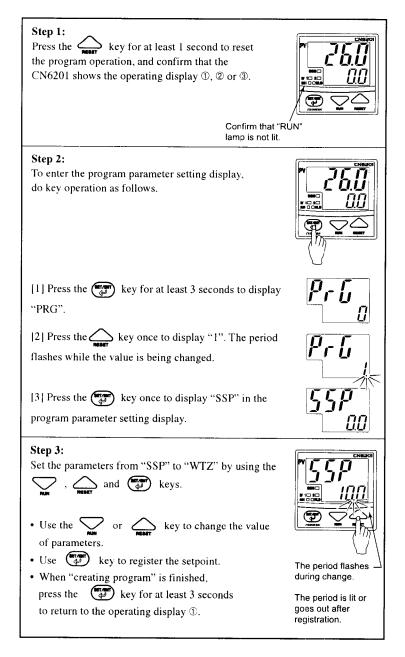
Junction code (JC)

Segment No.	Segment No.			3	4	5	6	7	8	9	10	11	12	13	14	15	16
Target setpoint (SP)																
Segment time (TM) (hour.minute or minute.second) Use the TMU sotup parameter to set the time unit																	
Time event 1	EON1																
(EV1=1)	(EV1=1) EOF1											·					
DV	ALI											·		·			
PV event 1 (EV1=0)	Al																
	HY1																
Time event 2	EON2										'						
(EV2=1)	(EV2=1) EOF2																
DIV.	AL2																
PV event 2 (EV2=0)	A2																
	HY2																

■ Creating the Program



Before creating the program, reverify the Measured Input Type (IN), Maximum Value of Measured Input Scale (RH), Minimum Value of Measured Input Scale (RL), and Control Mode (CTL) parameters.



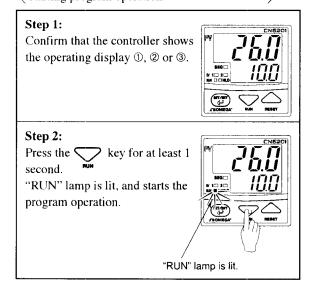
■ Deleting the Program Segment

To delete a part of the program pattern, set the segment time of the segment to be deleted ("TMn" n=1 to 16) to OFF, referring to "■ Creating the program."

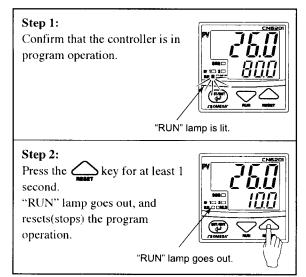
Note: If the segment time of the halfway segment is set to OFF, all of the following segment will not be displayed. Be careful!

■ Start Program Operation

"Creating the program" must be finished before starting program operation.



■ Reset (Stop) Program Operation



Note:

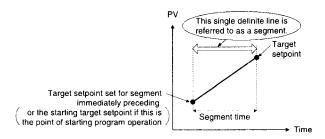
- The "Program operation" mode can be changed (run/reset) by key operation, communication or external contact input signal.
- ² When the program operation is reset (stopped), control action is also stopped, and the control output is to be 0% or OFF.

■ Programming

Before you begin programming, determine whether your programs are created using the time unit of "hour and minute" or "minute and second." The controller is factory-set to the "hour and minute" time unit. To create programs using the "minute and second" time unit, change the setpoint of the TMU (Time Unit of Program) setup parameter to "1".

Creating programs by setting target setpoint and segment time

As shown in the figure below, this method creates programs by setting a segment time and a target setpoint on a segment-by-segment basis.



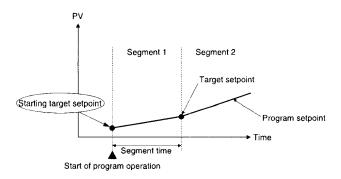
■ Conditions for Starting Program

1. Letting the controller run from a starting target setpoint

A starting target setpoint refers to a setpoint from which program operation begins. The controller operates in such a manner that the setpoint changes to the target setpoint over the segment time set for segment 1, irrespective of what the PV value is.

Controller Settings

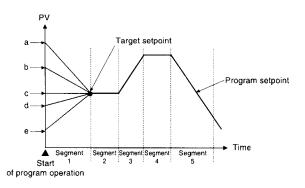
Set the STC (Start Code) program parameter to "0".



2.Letting the controller start from the current PV and run according to time settings defined for segment 1

Controller Settings

Set the STC (Start Code) program parameter to "2".



Starting Point of Operation	Controller Behavior
a	Begins to run from point a according to the time setting defined for segment 1.
b	Begins to run from point b according to the time setting defined for segment 1.
c	Begins to run from point c according to the time setting defined for segment 1.
d	Begins to run from point d according to the time setting defined for segment 1.
c	Begins to run from point e according to the time setting defined for segment 1.

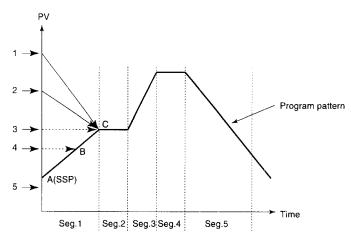
3. Letting the controller start from the current PV and run according to ramp settings defined for segment 1

Controller Settings

Set the STC (Start Code) program parameter to "1".

(1) If segment 2 is a soak segment

Program operation starts from any of the points A (SSP) to C. For other information, see the following table.



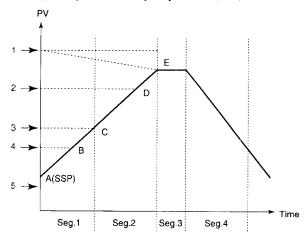
Example Where Segment 2 is a Soak Segment

The starting point of program operation is determined by where the measured input value (PV) is located at the time the operation starts.

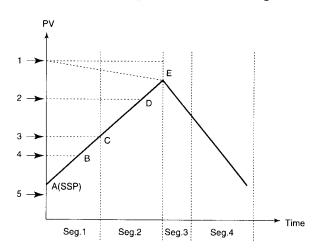
Measured input value (PV) at startup of program operation	Starting point of program operation				
1	С				
2	С				
3	C				
+	В				
5	A (SSP)				

(2) If segment 3 is a soak segment:

The starting point of program operation is any of points A (SSP) to E.



Example Where Segment 3 is a Soak Segment

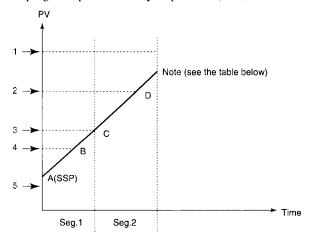


Example With No Soak Segment

The starting point of program operation is determined by where the measured input value (PV) is located at the time the operation starts.

Measured input value (PV) at startup of program operation	Starting point of program operation				
1	Ŀ				
2	D				
3	C				
4	В				
5	A (SSP)				

(3) If the segment consists of an ascending gradient (ramp) only: The starting point of program operation is any of points A (SSP) to D.



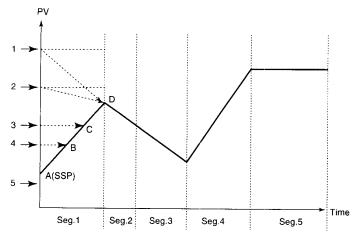
Example Where the Segment Consists of an Ascending Gradient (Ramp) Only

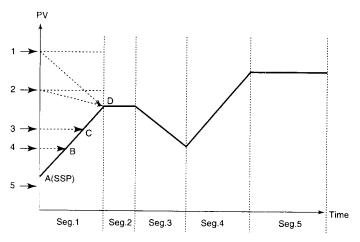
The starting point of program operation is determined by where the measured input value (PV) is located at the time the operation starts.

Measured input value (PV) at startup of program operation	Starting point of program operation
1	Program operation does not start up.
2	D
3	С
4	В
5	A (SSP)

(4) In the case of other program pattern is set.

The starting point of program operation is any of points A (SSP) to D.





The starting point of program operation is determined by where the measured input value (PV) is located at the time the operation starts.

Measured input value (PV) at startup of program operation	Starting point of program operation				
i	D				
2	1)				
3	C				
4	В				
5	A (SSP)				

■ PV Event Function List

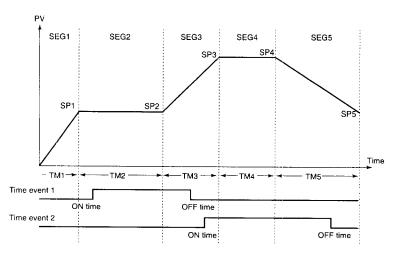
PV event is the function to output the PV or deviation alarm related to the created program.

DV	Action /"Opn" and "Cls" indicate that \		event code		Action /"Opn" and "Cls" indicate that \		event code
PV event (alarm) type	the relay contact is opened and closed; "(on)" and "(off)" indicate that the lamp is on and off; and white triangles indicate temperature control setpoints.	amp is on contact contact (alarm)		the relay contact is opened and closed; "(on)" and "(off)" indicate that the lamp is on and off; and white triangles indicate temperature control setpoints.	Closed contact during PV event (alarm)	Open contact during PV event (alarm)	
No alarm		0	FF		Hysteresis	/	
P\/ high imit	Opn (off) Measured value Alarm setting	1		De-energized on deviation low limit	Opn (on) Deviation setting Temperature setpoint Cls (off) Measured value		6
P\/ low I mit	Cls (on) Opn (off) Alarm setting Measured value	2		Deviation high and low limits	Hysteresis Hysteresis Cls Opn (off) Cls (on) Deviation setting Measured value Temperature setpoint	7	
Deviation high∃imit	Opn (off) A Measured value Temperature selpoint Cls (on) Deviation setting	3		Deviation within high and low limits	Hysteresis Hysteresis Opn (off) Opn (off) Deviation setting Terr perature selpoint	8	
Deviation low limit	Cls (on) Deviation setting A Deviation setting A Measured value Temperature setpoint	4		De-energized on PV high limit	Cls Opn (on) Measured value Alarm setting		9
De-energized on deviation high imit	Cls (off) Opn (on) Measured value Deviation setting		5	De-energized on PV low limit	Opn (on) Cls (off) Alarm setting Measured value		10

■ Time Event

The time event feature begins countdown when a program starts running, and after the elapse of a preset time, output an on-time event (contact output ON) or off-time event (contact output OFF).

The time of time event is not elapsed during "Hold" or "Wait" status. When the "Advance" is executed, remaining time in the segment is canceled.



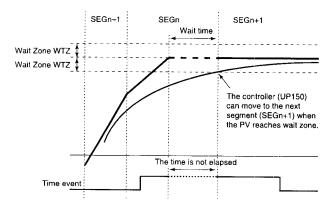
A NOTE

- (1) When you don't want "event-OFF" at the end of program operation, set "OFF" to time event 1 or 2 off time (EOF1 or EOF2) of segment.
- (2) When you want "event-ON" at the start of program operation, set "0.00" to time event 1 or 2 on time (EON1 or EON2) of final segment 1.
- (3) When the time of events on/off time exceeds the setting time of program, these events do not work.
- (4) Digital (Contact) output is OFF, when controller is in RESET mode.
- (5) The previous event status are kept when controller is in Hold mode.

■ Wait Operation

During a segment transition, wait operation brings the transition to be next segment into a wait (standby) state, using the wait zone, until the deviation is canceled. The wait zone is a span of deviation that determines to what degree a PV input is tracked.

Wait operation is available only at a segment junction that transfers from ramp to soak.



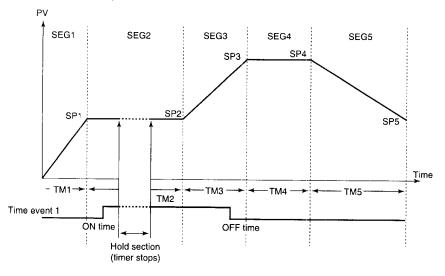
During the "wait", the timer for the program pattern progress stops, so that time event (EVn) is held. (RUN lamp flashes.)

The PV event does not stop even if the controller is in the "wait".

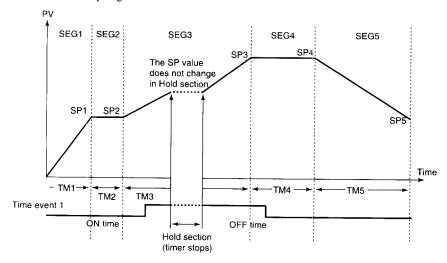
■ HOLD Function

During program operation, the time of "segment time" can be stopped by "HOLD function". When the controller is in "Hold", the time of time events are also stopped. (PV events do not stop at this time.) When program operation is held, time event and segment time are extended only by amount of the hold.

(1) "Hold" in soak segment

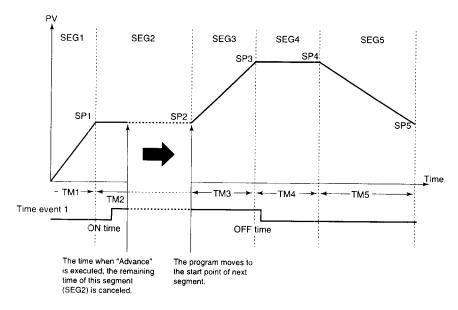


(2) "Hold" in ramp segment



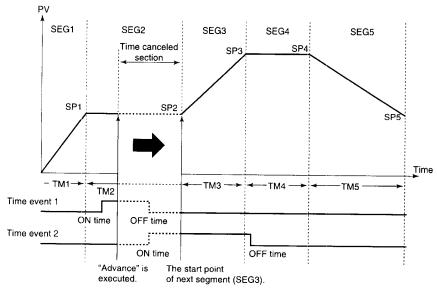
■ Advance Function

Advance (moving program pattern forward 1 segment) can be executed by key operation or via communication. If advance is executed at the final segment, the system operates according to the set junction code. If advance is executed during hold, hold is released. When advance is executed, time and event move forward.



Effect on time events

When the ON/OFF action of time events is set in "time canceled section", the status of time events are changec, and these are kept in the next segment.

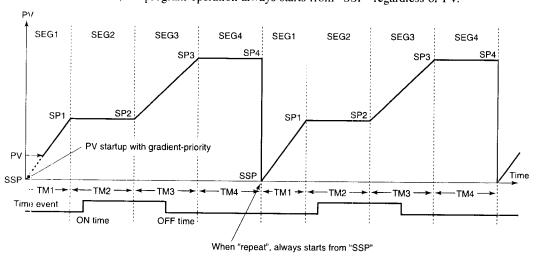


■ Junction Code

The operation at the end of program pattern can be specified by junction code (JC).

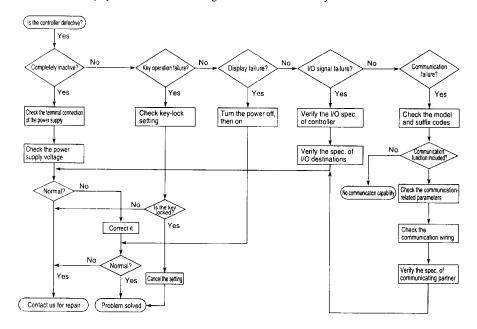
- (1) Reset termination (JC = 0)
 At program termination, the controller enters reset status. At this time, control output becomes 0% or OFF, and event status is OFF.
- (2) Hold termination (JC = 1)
 At program termination, the system enters hold status. At this time, control output and time event status are held (PV events do not stop at this time). The hold status continues until canceled by key operation or external contact input (digital input). When hold status is canceled, control output becomes 0% or OFF, and event status is OFF.
- (3) Repeat (JC = 2)

 At the program termination, the controller repeats execution of same program pattern. At th start of program operation, PV starts up with gradient-priority. At the start of second time or later where the repeat action is activated, the program operation always starts from "SSP" regardless of PV.



9. TROUBLESHOOTING

In the event of an abnormality, perform the following checks as outlined by the flowchart.



■ Error Display During Operation

(1) If the controller displays one of the following, carry out the appropriate remedy for the particular error.

Displa	y	Error content	Remedy
P.Er	P.Er	The parameter is abnormal	Check the settings of all the parameters and set them at their proper values.
b . o	B.o	Input burnout	Check the sensor wiring and correct it.
000	000	PV over-scale (PV exceeds its effective range.)	Check the input type and scale settings and correct them.
UUU	UUU	PV under-scale (PV falls below its effective range.)	
Flashing period		Communication failure (for /RS option only)	Press any key to stop the flashing.

(2) The controller needs to be repaired if any of the indications in the table below appear.

In these cases, do not try to repair the controller yourself. Order a new controller or contact us for repair.

Display	Error content
Unknown (at power-on)	CPU failure
All extinguished (at power-on)	Power source failure
"Err" (at power-on)	Calibration abnormal
Flashing "Err" (at power-on)	RAM or ROM failure
Flashing "Err" (during operation)	A/D converter failure, RJC failure, or EEPROM failur

■ When Power Failure Occurred During Operation

- Momentary power failures shorter than 20ms (or shorter than 1ms for "/V24") have no effect on the controller operation (i.e., normal operation continues).
- For power failures of 20ms or longer (or of 1ms or longer for "/V24"), however the status will be as follows.

(The controller action at power recovery is the same as at power-on.)

- Alarm (PV event) action: Continues
- Setting parameters: Maintained
- Auto-tuning: Canceled

WARRANTY/DISCLAIMER

OMEGA ENGINEERING, INC. warrants this unit to be free of defects in materials and workmanship for a period of **13 months** from date of purchase. OMEGA's WARRANTY adds an additional one (1) month grace period to the normal **one** (1) **year product warranty** to cover handling and shipping time. This ensures that OMEGA's customers receive maximum coverage on each product.

If the unit malfunctions, it must be returned to the factory for evaluation. OMEGA's Customer Service Department will issue an Authorized Return (AR) number immediately upon phone or written request. Upon examination by OMEGA, if the unit is found to be defective, it will be repaired or replaced at no charge. OMEGA's WARRANTY does not apply to defects resulting from any action of the purchaser, including but not limited to mishandling, improper interfacing, operation outside of design limits, improper repair, or unauthorized modification. This WARRANTY is VOID if the unit shows evidence of having been tampered with or shows evidence of having been damaged as a result of excessive corrosion; or current, heat, moisture or vibration; improper specification; misapplication; misuse or other operating conditions outside of OMEGA's control. Components in which wear is not warranted, include but are not limited to contact points, fuses, and triacs.

OMEGA is pleased to offer suggestions on the use of its various products. However, OMEGA neither assumes responsibility for any omissions or errors nor assumes liability for any damages that result from the use of its products in accordance with information provided by OMEGA, either verbal or written. OMEGA warrants only that the parts manufactured by the company will be as specified and free of defects. OMEGA MAKES NO OTHER WARRANTIES OR REPRESENTATIONS OF ANY KIND WHATSOEVER, EXPRESSED OR IMPLIED, EXCEPT THAT OF TITLE, AND ALL IMPLIED WARRANTIES INCLUDING ANY WARRANTY OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE HEREBY DISCLAIMED. LIMITATION OF LIABILITY: The remedies of purchaser set forth herein are exclusive, and the total liability of OMEGA with respect to this order, whether based on contract, warranty, negligence, indemnification, strict liability or otherwise, shall not exceed the purchase price of the component upon which liability is based. In no event shall OMEGA be liable for consequential, incidental or special damages.

CONDITIONS: Equipment sold by OMEGA is not intended to be used, nor shall it be used: (1) as a "Basic Component" under 10 CFR 21 (NRC), used in or with any nuclear installation or activity; or (2) in medical applications or used on humans. Should any Product(s) be used in or with any nuclear installation or activity, medical application, used on humans, or misused in any way, OMEGA assumes no responsibility as set forth in our basic WARRANTY/DISCLAIMER language, and, additionally, purchaser will indemnify OMEGA and hold OMEGA harmless from any liability or damage whatsoever arising out of the use of the Product(s) in such a manner.

RETURN REQUESTS/INQUIRIES

Direct all warranty and repair requests/inquiries to the OMEGA Customer Service Department. BEFORE RETURNING ANY PRODUCT(S) TO OMEGA, PURCHASER MUST OBTAIN AN AUTHORIZED RETURN (AR) NUMBER FROM OMEGA'S CUSTOMER SERVICE DEPARTMENT (IN ORDER TO AVOID PROCESSING DELAYS). The assigned AR number should then be marked on the outside of the return package and on any correspondence.

The purchaser is responsible for shipping charges, freight, insurance and proper packaging to prevent breakage in transit.

FOR **WARRANTY** RETURNS, please have the following information available BEFORE contacting OMEGA:

- Purchase Order number under which the product was PURCHASED,
- 2. Model and serial number of the product under warranty, and
- 3. Repair instructions and/or specific problems relative to the product.

FOR **NON-WARRANTY** REPAIRS, consult OMEGA for current repair charges. Have the following information available BEFORE contacting OMEGA:

- Purchase Order number to cover the COST of the repair,
- 2. Model and serial number of the product, and
- 3. Repair instructions and/or specific problems relative to the product.

OMEGA's policy is to make running changes, not model changes, whenever an improvement is possible. This affords our customers the latest in technology and engineering.

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